**FA** • Robotic Automation Products

# **Application Examples**

Vol.3



# Find the Best Solutions based on Your Tasks

Kosmek Products for Automation and Setup Improvement in Every Process





Best Selling Product

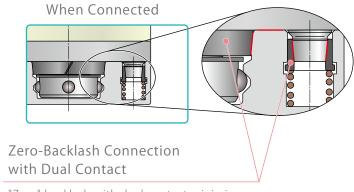
#### Robotic Hand Changer

model SWR

The World's Only Zero-Backlash Robotic Hand Changer

#### **KOSMEK Exclusive Non-Backlash Mechanism**





"Zero" backlash with dual contact minimizes the vibration of electrode and prevents noise and friction. Highly reliable electrode prevents moment stops caused by communication error.

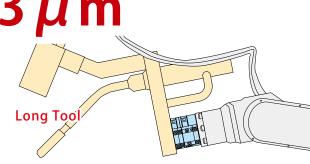


#### Secures the Aimed Position

When Connected, Repeatability is  $3 \mu m$ 

Even with long tools or hands, fluctuation of the edge is extremely small. It secures high accuracy processing even after tool change.

% Repeatability of SWR0010 (Payload : 0.5~1kg) is 5  $\mu$  m.

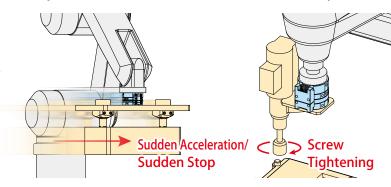


# 24-Hour Continuous Operation is Possible Uncomparably High Rigidity and Durability

Strong to "bending" and "torsion" with high rigidity obtained by non-backlash function.

Also, high strength material is used in all the contact part of the master and tool so that it ensures high durability and  $3 \mu \,\mathrm{m}^*$  locating repeatability even after 1 million cycles.

% Repeatability of SWR0010 (Payload : 0.5~1kg) is 5  $\mu$  m.



#### Compact Robotic Hand Changer

Extra-Small Robotic Hand Changer Compact and Light, yet Zero Backlash when Connected

#### Additional Option Line-up

Even More Flexibly Used with Additional Options for Robotic Hand Changer with 3kg ~ 120kg payload.



Air Port with Check Valve Easier to Choose Solenoid Valves



Payload:  $0.5 \sim 1 \text{kg}$ 

Model: SWR0010 Repeatability: 0.005mm



Resin Connector Electrode Easy to Connect • 16 signals



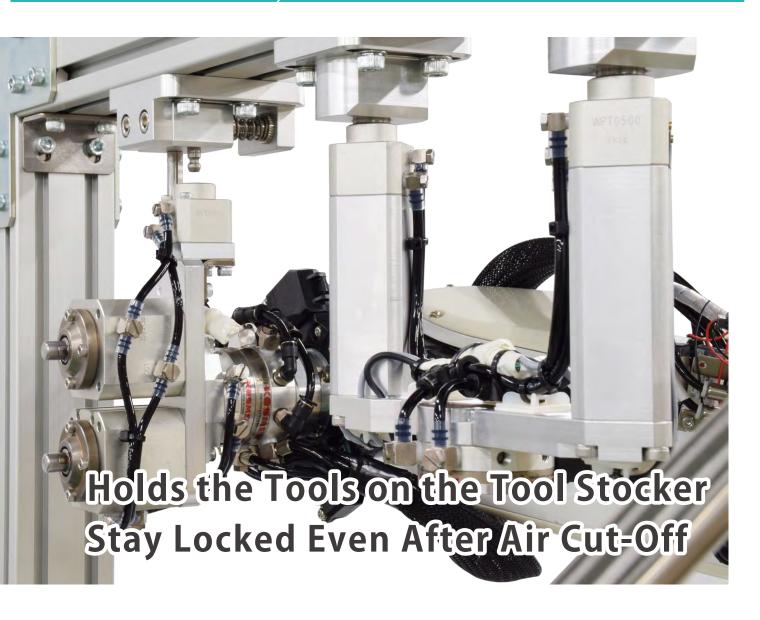
Compact Electric Power Transmission



Larger Port Air Joint Ability to Transmit AC/DC200V 5A Suitable for Negative Pressure

#### A Variety of Electrode/Air Joint Options



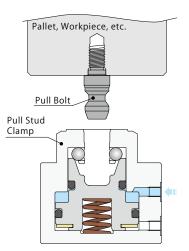


The Latest Product

#### High-Power Pull Stud Clamp

model WPT

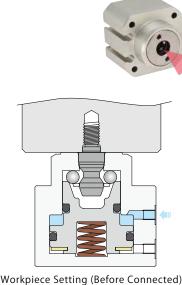
Clamps by pulling the Pull Bolt. Compact, Light and Easy to Install. For Various FA Applications: Pallet Transfer, Stocker for Hands/Tools, etc.



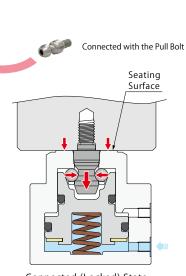
Detached (Released) State

Release Air Pressure: ON Lock Air Pressure: OFF

Provide release air pressure, allowing for pulling in and out the pull bolt.



Release Air Pressure: ON Lock Air Pressure: OFF Insert the pull bolt.



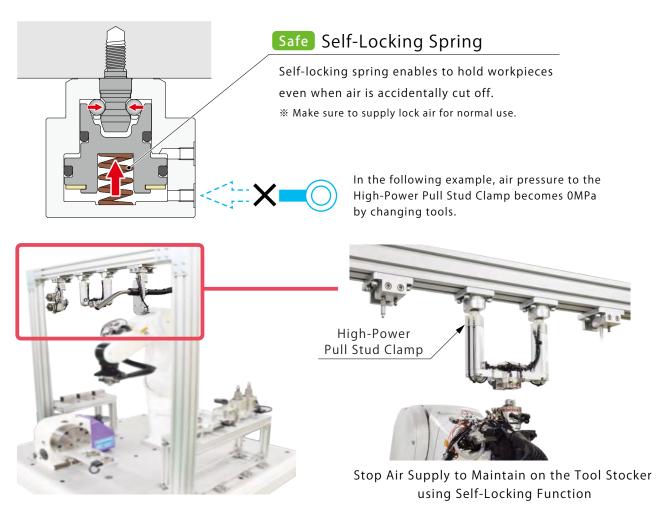
Connected (Locked) State

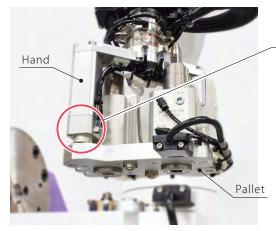
Release Air Pressure: OFF Lock Air Pressure: ON

The pull bolt is pulled in by the piston and steel balls with lock air + spring force to complete the locking operation.



# Self-Locking Function Holds the Tools with Residual Holding Pressure even when Robotic Hand Tool is detached.





#### Pallet Transfer with High-Power Pull Stud Clamp

High-Power Pull Stud Clamp is light so it has minimal effect on robot's payload. Yet holding force is very powerful and this enables to transfer a heavy pallet, etc.





Model: WPT0500

Max. Holding Force: 768 N
Residual Holding Force (at 0MPa): 100 N
Body Weight: 55g Pull Bolt Weight: 3 g

\* Refer to the WPT catalog for further information.

Model: WPT0600

Max. Holding Force: 1234 N

Residual Holding Force (at 0MPa): 170 N

Body Weight: 95g Pull Bolt Weight: 5 g





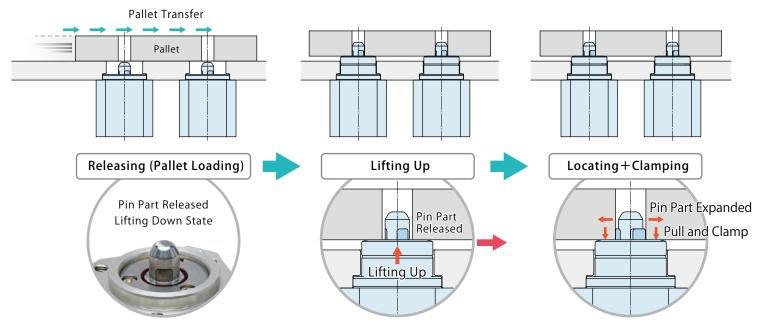


The Latest Product

Lifting Hole Clamp

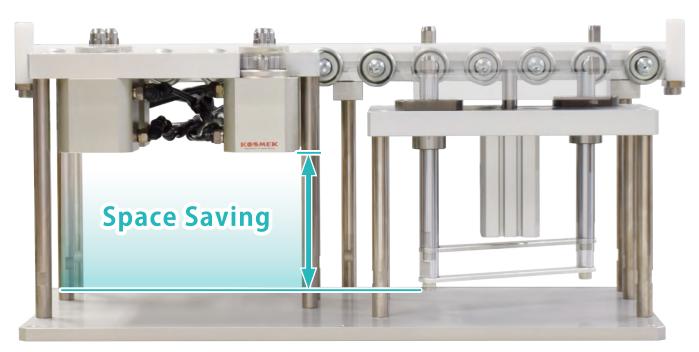
model SWJ

Lifting type hole clamp with functions of lift cylinder, linear guide, locating and clamping. Locating part expands to eliminate the gap between the pin and workpiece hole. Zero gap makes no backlash.









#### **After**

#### **Lifting Hole Clamp**

Integrated Lift Cylinder, Linear Guide and Locating Pin with Clamping Function.

- Simple Number of Parts : Few
- Space Saving
- With Clamping Function
- No Backlash due to no gap between the pin and pallet hole.

#### Before

#### **General Cylinder + Fixture**

Needs to place lift cylinders, linear guides and locating pins separately.

- Complicated Number of Parts : Many
- Requires Space
- Requires Additional Clamps
- Backlash due to gap between the pin and pallet hole.

Lifting Hole Clamp

Specifications



Model: SWJ2000-S10

Workpiece Hole Diam. :  $\phi$  10 $\pm$ 0.2 mm

Repeatability: 0.1 mm Lifting Stroke: 16 mm

Lifting Force (at Extend) : 30 N  $\,$ 

Lifting Force (at 0.5MPa after operation): 400 N

Gripping Force (at 0.5MPa): 500 N Clamping Force (at 0.5MPa): 50 N

\* Refer to the SWJ catalog for further information.







Compact Pneumatic Location Clamp

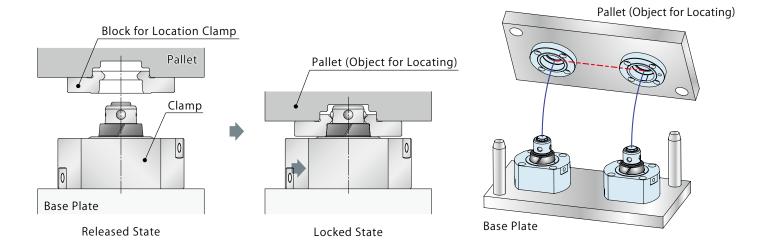
model SWQ

Drastically minimizes pallet setup time improves productivity.

Locating Repeatability :  $3 \mu m$ 

Suitable for automatic setup with robot.

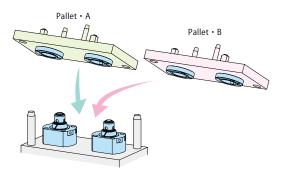
Action Description



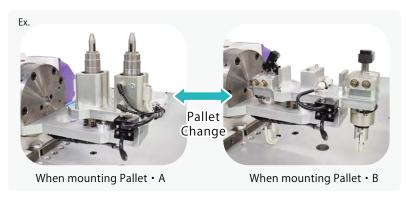


#### Setup Improvement Enhances Productivity

Pneumatic locating clamp locates with high accuracy and clamps at once. (Fixture alignment and inspection are eliminated.) Fixture change over is faster and easier, thus by eliminating alignment inspection for accuracy which is done in many different ways. Suitable for automatic pallet setup.

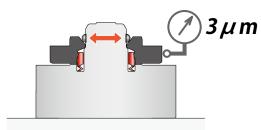


< Setup Change for Assembly Device • Inspection Device • Welding Fixture >



#### Repetitive Locating with High Accuracy

Locating Repeatability : 3  $\mu$  m Used with a combination of the clamp and block. Mount the block on the object for locating.



#### Self-Locking (Safety) Function (Maintains Clamping at Zero Air Pressure)

Even if air pressure is at zero, it will stay locked with self-locking spring.

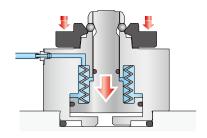
(Refer to Holding Force at OMPa for detail.)

\* More than the minimum operating air pressure is required for locating.



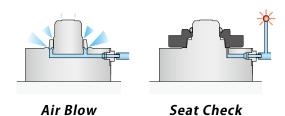
#### Clamping Function

Clamping force is ranged from 0.25kN~1.1kN. Clamps with air pressure and spring for self locking. Clamping force is selectable for your needs.



#### Air Blow and Seat Check

Contaminants are removed by air blow. Seating surface is provided with the air hole, and seating confirmation is available with a gap sensor.





Model: SWQ0030-S□ Clamping Force (at 0.5MPa): 310 N

Lift-up Force (at 0.5MPa): 80N

Max. Loading Weight: 50kg regardless of no. of clamps. Consideration should be given to lift-up force.

Model: SWQ0070-S□

Clamping Force (at 0.5MPa): 600 N Lift-up Force (at 0.5MPa): 200N

Max. Loading Weight: 100kg regardless of no. of clamps. Consideration should be given to lift-up force.

\* Refer to the SWQ catalog for further information.



For more powerful force: model SWT / model WVS. For manual operation: model VXE / model VXF. Refer to our website for further information.



High-Power Pneumatic Swing / Link Clamp  $\mathbf{WH} \square / \mathbf{WC} \square$ 

With built-in mechanical lock, it exerts powerful clamping and holding force, allowing for more compact application.

# Action Description Link Clamp Swing Clamp Released State Locked State Locked State Locked State Locked State Clamping



#### Best Selling Product

#### High-Power Pneumatic Swing / Link Clamp

#### model WHE/ WCE

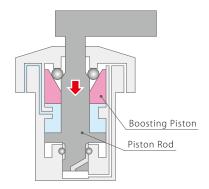
Standard High-Power Pneumatic Clamp with Built-in Mechanical Lock for general use and cutting oil of machine tools.



Mechanism of the High Power

\* Simplified drawing

Boosting piston generates powerful clamping force and holding force with wedge mechanism.



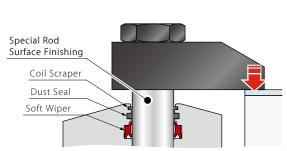
#### The Latest Product

### High-Power Welding Swing / Link Clamp

model WHG/ WCG

High-Power Pneumatic Clamp with Built-in Mechanical Lock and Spatter Resistant Body for Welding Applications





Triple Protective Structure



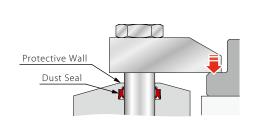
The rod operates without failure even after exposed to spatter for a long time.

#### The Latest Product

## High-Power Swing / Link Clamp for Washing Application

High-Power Pneumatic Clamp with Built-in Mechanical Lock and Corrosion-Resistant Body for High Pressure Washing





Prevent Washing Liquid from Entering a Cylinder



Highly Durable Parts Designed for Washing Applications



The Latest Product

Locating Pin Clamp

model SWP

Expansion Locating Pin Clamp allows for
High Accuracy Locating and Clamping of Thin Workpieces

Action Description



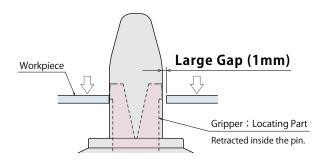
#### No Gap. Spatter Entering Protection

The pin itself goes down along with the gripper when locking, so there is hardly any gap at locked state, preventing contaminants.



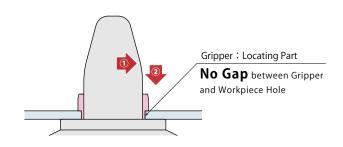
#### **High Accuracy**

Expansion of locating part allows for higher accuracy than general locating pin. Smooth loading/unloading due to large gap at released state.



#### **Released State**

Gripper is retracted at released state. Workpiece can be smoothly installed due to an adequate space between the workpiece hole and pin. Also, the locating part does not touch a workpiece since it is retracted inside the pin.



#### **Locked State**

Gripper expansion enables zero gap and high accuracy locating. Repeatability: 0.05mm

Unlike general locating pin, the Locating Pin Clamp remains high accuracy regardless of variation in tolerance of workpiece hole diameter.

#### Compact • Light

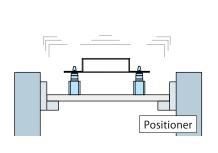
Short body allows for more compact and lighter applications.



Ex. 1 SWP0501-D/C-100- $\square$  (Workpiece Hole Diam.  $\phi$  10)

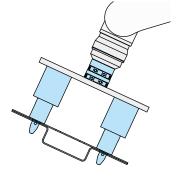


Ex. 2 SWP1001-D/C-200-(Workpiece Hole Diam. \$\phi\$ 20)



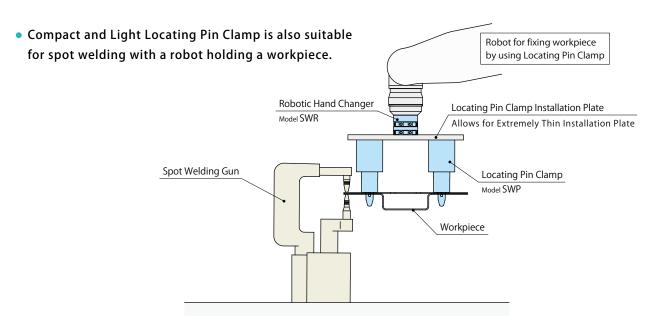
Light fixture with light Pin Clamp decreases load to the positioner.

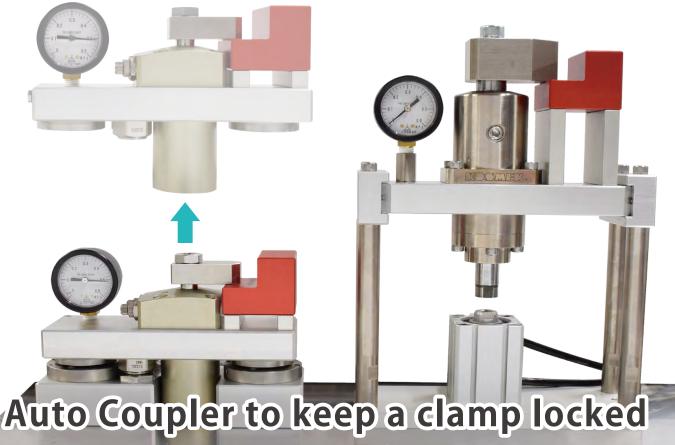
Less Load to the Positioner



#### **Compact and Light Transfer Hand**

Compact and Light Locating Pin Clamp is also suitable for transferring thin plates.





even when detached from air source. For transfer / washing application, etc.

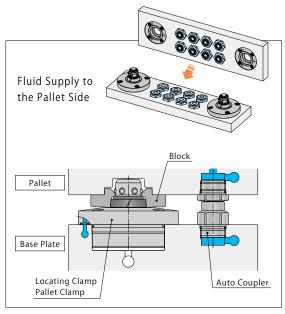
Auto Coupler

Suitable for detaching coupler to exchange pallets.

model JV

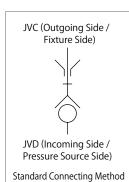
Easy to be used with Location Clamp / Pallet Clamp (model SWT / WVS).

No reaction force generated during pallet setting when using with SWT/WVS/VS.



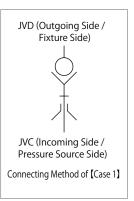
Application Example when using with Pallet Clamp







model JVC



Circuit Diagram





to the clamp via Auto Coupler

#### [Case 1] Transfer with Pressure Maintained

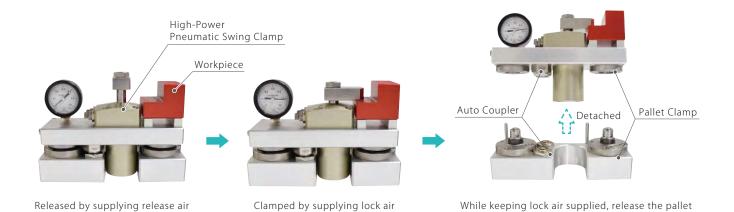
Detaching Method using Auto Coupler and High-Power Pneumatic Swing Clamp Maintains air pressure with check valve of Auto Coupler JVD.

Able to transfer a workpiece even when detached from air source. High-power pneumatic clamp withstands reaction force with holding force generated by mechanical locking. Piston rod will not be pressed back by reaction force so that air pressure in the circuit will not be compressed.

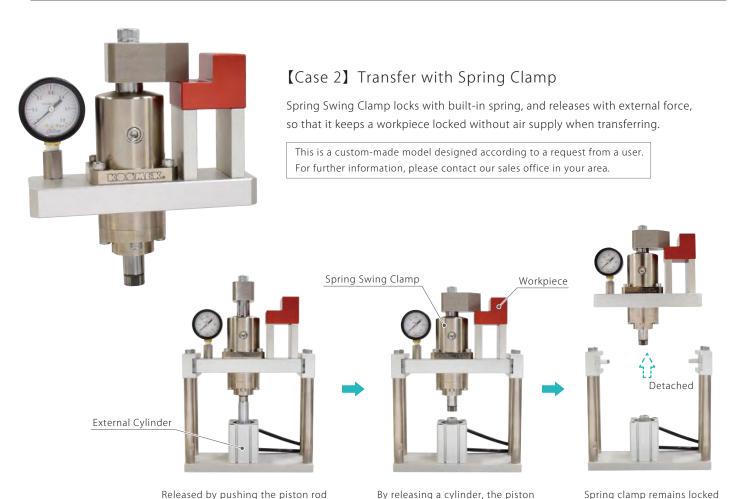
[Important] Maintaining air pressure is not a function that Auto Coupler guarantees.

Please verify before use. If you are considering using this method,
contact our sales office in your area.

clamp to detach the pallet. Air pressure is maintained and the Swing Clamp remains locked.



to the clamp via Auto Coupler

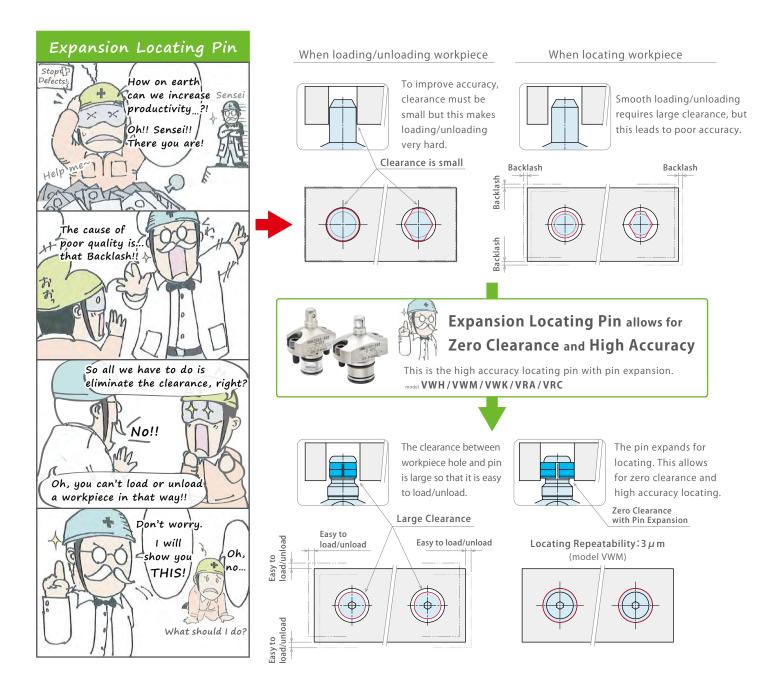


of the spring clamp with external

force of a cylinder, etc.

By releasing a cylinder, the piston rod of the clamp is descended, and it clamps the workpiece.

Spring clamp remains locked even after detaching.





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■ For Further Information on Unlisted Specifications and Sizes, Please call us.

■ Specifications in this Leaflet are Subject to Change without Notice.



2018/07 First 2Ry 2020/08 2nd 0Ry