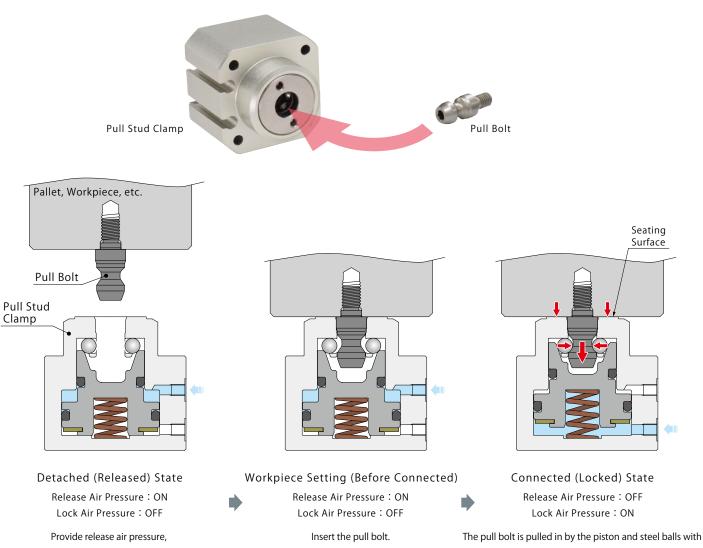


Clamps with the Pull Bolt. Compact Body with Powerful Holding Force For Various Applications: Pallet Transfer, Robotic Hand Gripper Change, etc.

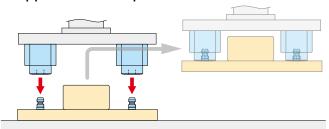
Connect the Pull Bolt with the Pull Stud Clamp



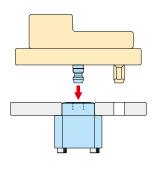
lock air + spring force to complete the locking operation.

allowing for pulling in and out the pull bolt.

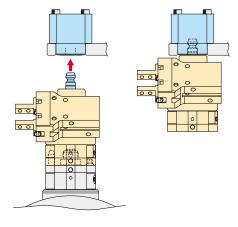
Application Examples



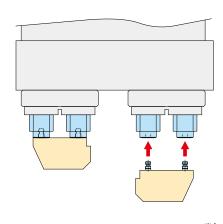
Pallet/Workpiece/Application Transfer. Allows for more compact hand.**1



Pallet Setup by Using with Locating Pin



Stocker for Robotic Hands

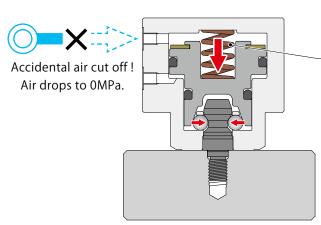


Gripper Change for Robotic Hands **1

Note:

※1. Use WPWZ□-P1S when clamping one workpiece with two or more High-Power Pull Stud Clamps. The accumulated mounting distance accuracy of pull bolts and clamps needs to be within ±0.1mm.

• Fall Prevention with Self-Locking Spring



Safe Self-Locking Spring

Self-locking spring enables to hold a workpiece even when air is accidentally cut off.

Make sure to supply lock air for normal use.

• Compact, Light, yet Powerful

Exerts Powerful Clamping Force and Holding Force with Mechanical Lock



WPT1000: 2436N

Action Detection with Sensor

Actions of the Pull Stud Clamp can be detected by using with the Sensor for Air Cylinder.

Refer to P.286 for further information.



Locating + Clamp

Locating

Hand • Clamp

Support

Valve • Coupler

Cautions • Others

Pallet Gripper

WVA

Locating Pin Clamp

SWP

igh-Power ull Stud Clamp WPT JES

FA Pneumatic Hole Clamp WKH

Lifting Hole Clamp SWJ

Ball Lock Cylinder

WKA

Pneumatic Robotic Hands

> WPS-C WPA WPH WPP

WPQ

Auto Switch Proximity Switch JEP

High-Power Pneumatio

Hole Clamp SWE

High-Power Pneumatic Swing Clamp WHE

High-Power Pneumatic Link Clamp WCE

Pneumatic

Hole Clamp

Pneumatic Swing Clamp

WHA
Double Piston

Pneumatic Swing Clamp WHD

Pneumatic

Link Clamp WCA

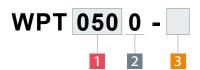
> Air Flow Control Valve BZW

Manifold Block

Block WHZ-MD

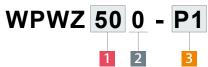
Model No. Indication (High-Power Pull Stud Clamp)







Model No. Indication



1 Size

050 : External Dimension □29mm
060 : External Dimension □35mm
080 : External Dimension 40×41mm
100 : External Dimension □45mm

1 Corresponding WPT High-Power Pull Stud Clamp Model No.

50 : For WPT050060 : For WPT060080 : For WPT0800100 : For WPT1000

2 Design No.

0 : Revision Number

2 Design No.

0 : Revision Number

3 Operating Temperature (Sealing Material)

Blank : Standard (Operating Temp. 0 ~ 70°C)

Sealing Material: Nitrile Rubber

V : High Temp. (Operating Temp. 0 ~ 120°C)

Sealing Material: Fluor Rubber

3 Function

P1 : Pull Bolt

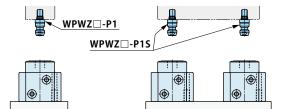
P15 : Pull Bolt (Slim Option)*1

Note:

1. WPT does not include Pull Bolt (WPWZ). Please order separately.

Note:

※1. Use WPWZ□-P1S when clamping one workpiece with two or more High-Power Pull Stud Clamps. The accumulated mounting distance accuracy of pull bolts and clamps needs to be within ±0.1mm.



Specifications

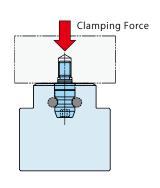
Model No.		WPT0500	WPT0600	WPT0800	WPT1000
Clamping Force (at 0.5MPa)	N	374	602	934	1187
Holding Force (at 0.5MPa)	N	768	1234	1918	2436
Residual Holding Force (at 0	MPa) ^{*2} N	(100)	(170)	(250)	(300)
Cylinder Capacity	Lock Side	0.77	1.45	2.62	3.81
cm ³	Release Side	0.41	0.80	1.45	1.75
Maximum Operating Pressur	re MPa	MPa 0.5			
Minimum Operating Pressur	e MPa		0	.3	
Withstanding Pressure	MPa		0.	75	
Operating	3 Blank		0 ~	70	
Temperature Range °C	3 V		0 ~ 1	20*3	
Usable Fluid		Dry Air			
Weight	g	55	95	155	215

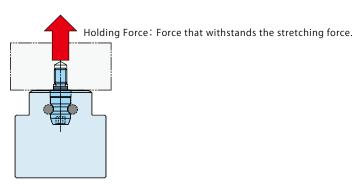
Notes: *2. Residual holding force means the holding force when air pressure drops to 0MPa after locking, and above number of residual holding force is just a reference value.

*3. For action detection, be careful with the specification (temperature) of a switch or a sensor.

Model No.		WPWZ500-P1□	WPWZ600-P1□	WPWZ800-P1□	WPWZ1000-P1□
Weight	g	3	5	10	20

Clamping Force / Holding Force Curve



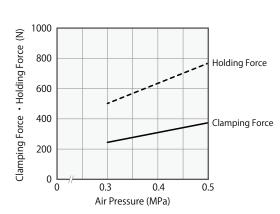


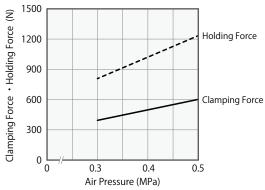
	WPT0500	
Air Pressure	Clamping Force (N)	Holding Force (N)
at 0.5MPa	374	768
at 0.4MPa	308	633
at 0.3MPa	243	499
at 0MPa	_	(100) ^{※4}

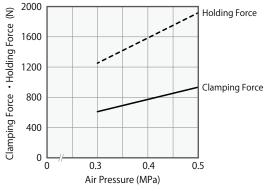
	WPT0600	
Air Pressure	Clamping Force (N)	Holding Force (N)
at 0.5MPa	602	1234
at 0.4MPa	497	1019
at 0.3MPa	393	806
at 0MPa	_	(170) ^{※4}

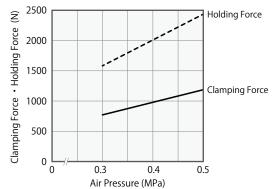
	WPT0800	
Air Pressure	Clamping Force (N)	Holding Force (N)
at 0.5MPa	934	1918
at 0.4MPa	772	1585
at 0.3MPa	610	1252
at 0MPa	-	(250)**4

	WPT1000	
Air Pressure	Clamping Force (N)	Holding Force (N)
at 0.5MPa	1187	2436
at 0.4MPa	979	2009
at 0.3MPa	771	1582
at 0MPa	_	(300)**4









Locating + Clamp

Locating

Hand • Clamp

Support

Valve • Coupler

Cautions • Others

Pallet Gripper WVA

Locating Pin Clamp

Pin Clamp SWP

High-Power Pull Stud Clamp WPT JES

Hole Clamp
WKH
Lifting

FA Pneumatic

Lifting Hole Clamp SWJ Ball Lock

Cylinder
WKA

Pneumatic
Robotic Hands

WPW-C
WPS-C
WPA
WPH
WPP

Auto Switch Proximity Switch JEP

High-Power Pneumatic Hole Clamp SWE

High-Power Pneumatic Swing Clamp WHE

High-Power Pneumation
Link Clamp
WCE

Pneumatic Hole Clamp

Pneumatic Swing Clamp WHA

Double Piston Pneumatic Swing Clamp WHD

Pneumatic Link Clamp WCA

Air Flow Control Valve

Manifold

Block WHZ-MD

External Dimensions: WPT0500, WPWZ500-P1

High-Power Pull Stud Clamp

WPT0500

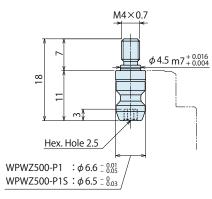
Seating Surface 2-\phi 2^{+0.03} Depth 3 from the back

12.5 ±0.03

 $4 - \phi 3.4$

M4×0.7 Thread

Pull Bolt **WPWZ500-P1**□

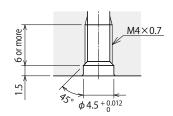


Seating Surface Outer Diam. ϕ 14.8 ϕ 6.6 $^{+0.05}_{+0.01}$ Release Air Port $M3 \times 0.5$

 $\phi 20_{-0.05}^{0}$

12.5 ^{±0.03}

Machining Dimensions of Pull Bolt (WPWZ500-P1□)



Tightening Torque when Mounting WPWZ500-P1 $\hfill \Box$ 2.3 N • m

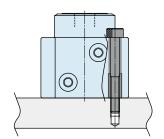
Note:

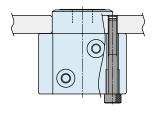
Lock Air Port M3×0.5

1. WPT does not include Pull Bolt (WPWZ). Please order separately.

WPT0500 Installation Method and Tightening Torque

5.5 4.5





[DWG 1: Bolt Down Mounting]

[DWG 2 : Bolt Up Mounting]

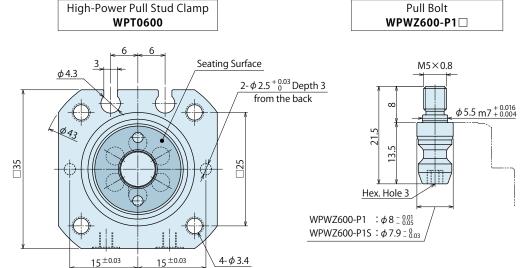
[DWG 3: Bolt Up Mounting]

Model No.	Mounting Direction	Mounting Bolt Nominal × Pitch	Number of Bolts	Tightening Torque (N • m)
	DWG 1: Bolt Down Mounting	M3×0.5	4	1
WPT0500	DWG 2: Bolt Up Mounting	M4×0.7	4	2.3
	DWG 3: Bolt Up Mounting	M3×0.5	4	1

Note:

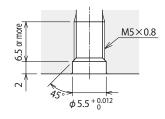
1. Mounting bolt and locating pin are not included. Please order separately.

© External Dimensions: WPT0600, WPWZ600-P1□



$\phi 25_{-0.05}^{0}$ Seating Surface Outer Diam. ϕ 18.8 ϕ 8 + 0.05 Release Air Port 10 M3×0.5 35 ∞ M4×0.7 Thread Lock Air Port $M3 \times 0.5$

Machining Dimensions of Pull Bolt (WPWZ600-P1□)

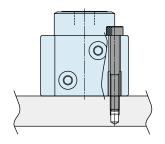


Tightening Torque when Mounting WPWZ600-P1□ 4.0 N • m

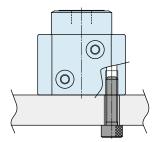
Note:

1. WPT does not include Pull Bolt (WPWZ). Please order separately.

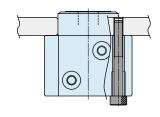
NPT0600 Installation Method and Tightening Torque



[DWG 1: Bolt Down Mounting]



[DWG 2: Bolt Up Mounting]



[DWG 3: Bolt Up Mounting]

Model No.	Mounting Direction	Mounting Bolt Nominal × Pitch	Number of Bolts	Tightening Torque (N • m)
	DWG 1: Bolt Down Mounting	M3×0.5	4	1
WPT0600	DWG 2: Bolt Up Mounting	M4×0.7	4	2.3
	DWG 3: Bolt Up Mounting	M3×0.5	4	1

1. Mounting bolt and locating pin are not included. Please order separately.

Locating Clamp

Locating

Hand • Clamp

Support

Valve • Coupler

Cautions · Others

Pallet Gripper

WVA

Locating Pin Clamp

SWP

WPT

JES FA Pneumatic

WKH Lifting Hole Clamp SWJ

Ball Lock Cylinder WKA

Pneumatic Robotic Hands

> WPS-C WPA WPH WPP

WPO Auto Switch Proximity Switch JEP

High-Power Pneumatic Hole Clamp SWE

High-Power Pneumatic

Swing Clamp WHE

High-Power Pneumatic Link Clamp

WCE

Pneumatic Hole Clamp

SWA

Pneumatic Swing Clamp

WHA Double Piston

Pneumatic Swing Clamp WHD

Pneumatic

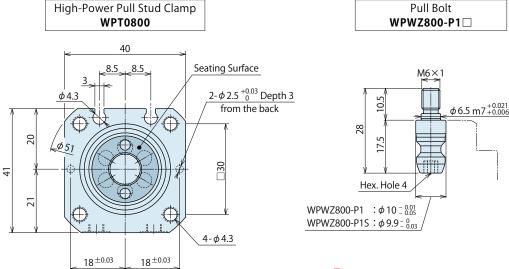
WCA

Air Flow Control Valve BZW

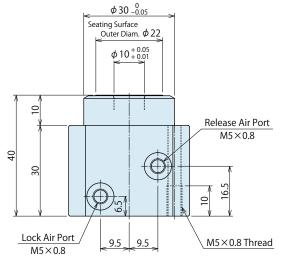
Manifold Block

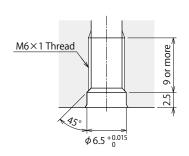
WHZ-MD

© External Dimensions: WPT0800, WPWZ800-P1



Machining Dimensions of Pull Bolt (WPWZ800-P1□)



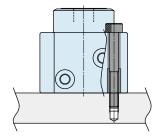


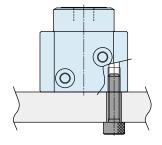
Tightening Torque when Mounting WPWZ800-P1 \square 9.0 N \cdot m

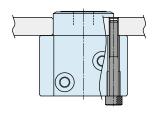
Note:

1. WPT does not include Pull Bolt (WPWZ). Please order separately.

NPT0800 Installation Method and Tightening Torque







[DWG 1: Bolt Down Mounting]

[DWG 2 : Bolt Up Mounting]

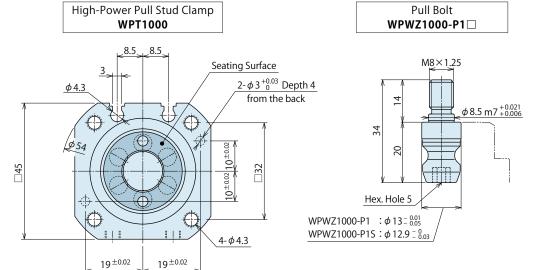
[DWG 3: Bolt Up Mounting]

Model No.	Mounting Direction	Mounting Bolt Nominal × Pitch	Number of Bolts	Tightening Torque (N • m)
	DWG 1: Bolt Down Mounting	M4×0.7	4	2.3
WPT0800	DWG 2: Bolt Up Mounting	M5×0.8	4	4.6
	DWG 3: Bolt Up Mounting	M4×0.7	4	2.3

lote :

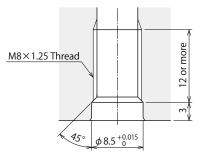
1. Mounting bolt and locating pin are not included. Please order separately.

©External Dimensions: WPT1000, WPWZ1000-P1



ϕ 35 $^{0}_{-0.05}$ Seating Surface Outer Diam. \$\phi\$ 26 ϕ 13 $^{+0.05}_{+0.01}$ Release Air Port M5×0.8 45 9 Lock Air Port $M5 \times 0.8$ Thread 10 10 $M5 \times 0.8$

Machining Dimensions of Pull Bolt (WPWZ1000-P1□)

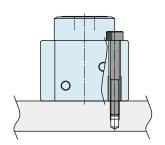


Tightening Torque when Mounting WPWZ1000-P1□ 18 N • m

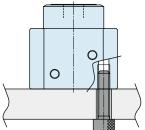
Note:

1. WPT does not include Pull Bolt (WPWZ). Please order separately.

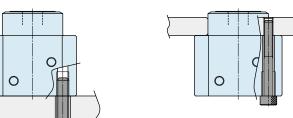
NPT1000 Installation Method and Tightening Torque



[DWG 1: Bolt Down Mounting]



[DWG 2: Bolt Up Mounting]



[DWG 3: Bolt Up Mounting]

	Model No.	Mounting Direction	Mounting Bolt Nominal × Pitch	Number of Bolts	Tightening Torque (N • m)
		DWG 1: Bolt Down Mounting	M4×0.7	4	2.3
WPT1000		DWG 2: Bolt Up Mounting	M5×0.8	4	4.6
		DWG 3: Bolt Up Mounting	M4×0.7	4	2.3

1. Mounting bolt and locating pin are not included. Please order separately.

Locating

Clamp Locating

Hand • Clamp

Support

Valve • Coupler

Cautions · Others

Pallet Gripper WVA

Locating Pin Clamp SWP

WPT

JES FA Pneumatic

WKH

Lifting Hole Clamp SWJ

Ball Lock Cylinder WKA

Pneumatic Robotic Hands

WPS-C WPA WPH WPP WPO

Auto Switch Proximity Switch JEP

High-Power Pneumatic Hole Clamp SWE

High-Power Pneumatic

Swing Clamp WHE

High-Power Pneumatic Link Clamp

WCE

Pneumatic Hole Clamp

SWA

Pneumatic Swing Clamp WHA

Double Piston Pneumatic

Swing Clamp WHD

Pneumatic WCA

Air Flow Control Valve

BZW Manifold

Block WHZ-MD

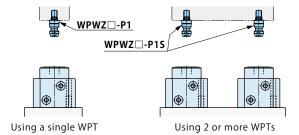
282

Notes for Design

- 1) Check Specifications
- Model WPT: Maximum operating air pressure is 0.5 MPa.
 Minimum operating air pressure is 0.3 MPa.
 Applying excessive load on the Pull Stud Clamp leads to deformation, galling and air leakage.
- 2) Do not apply impact on a workpiece, etc. connected to Pull Bolt.
- Otherwise, it may result in breakage of the product.
- 3) Notes for Circuit Design
- Please design the air circuit properly and review the circuit design in advance in order to avoid malfunction or breakage of the device.
- 4) Please supply filtered clean dry air.
- Oil supply with a lubricator etc. is unnecessary.
- 5) Operating Environment
- WPT has no function that prevents contaminants.
 Do not use under environment with coolant and cutting chips.
- 6) Insertion of Pull Bolt
- Please insert the Pull Bolt to the end before providing lock air pressure. (Prevention of clamping failure and damage of Pull Bolt.)

- 7) Protective Cover Installation
- If the moving parts of the robot or robotic hand may endanger operator, please install the protection cover.
- 8) Fall Prevention Measures
- In case of accident such as detachment of a workpiece, please prepare fall prevention measures for safety.
- 9) For Use of Auto Switch
- In order to ensure stable detections, please use the 3-wire sensor of the high accuracy sensor for air cylinder "model JES0000-02□□".
- 10) When using more than two High-Power Pull Stud Clamps
- Use WPWZ□-P1S when clamping one workpiece with two or more High-Power Pull Stud Clamps.

The accumulated mounting distance accuracy of pull bolts and clamps needs to be within $\pm 0.1 \text{mm}$.



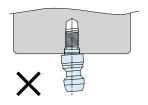


Installation Notes

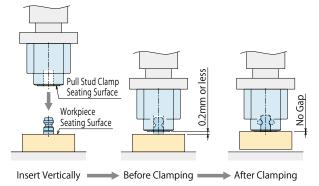
- 1) Usable Fluid
- Please supply filtered clean dry air. (Install a drain removing device.)
- Oil supply with a lubricator etc. is unnecessary. Oil supply with a lubricator may cause loss of the initial lubricant. The operation under low pressure and low speed may be unstable. (When using lubricant, please supply lubricant oil continuously. Otherwise, the initial grease applied by KOSMEK will be removed.)
- 2) Preparation for Piping
- The pipeline, piping connector and fixture circuits should be cleaned and flushed thoroughly.
 - The dust and cutting chips in the circuit may lead to air leakage and malfunction.
- There is no filter provided with this product for prevention of contaminants in the air circuit.
- 3) Applying Sealing Tape
- When using sealing tape, wrap with it 1 to 2 times following the screwing direction. When piping, be careful that contaminant such as sealing tape does not enter in products. Pieces of the sealing tape can cause air leakage and malfunction.
- 4) Installation of the Main Body and the Pull Bolt
- Please use hexagonal socket bolts (with tensile strength of A2-70 or greater), and tighten the product with the tightening torque listed on P.279 ~ P.282.
- The tightening torque for pull bolt is shown below.

Model No.	Bolt Size	Tightening Torque (N • m)
WPWZ500-P1□	M4×0.7	2.3
WPWZ600-P1□	M5×0.8	4.0
WPWZ800-P1□	M6×1	9.0
WPWZ1000-P1□	M8×1.25	18

- Installation failure causes air leakage, deformation and damage of the Pull Stud Clamp and the Pull Bolt.
- 5) Do Not Use Deformed Pull Bolts
- If a Pull Bolt is deformed as shown below, Pull Stud Clamp and Pull Bolt will be broken, and/or will not be able to release properly.

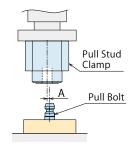


- 6) Allowable Offset while Clamping
- While clamping, the gap between the seating surfaces of the Pull Stud Clamp and a workpiece, etc. should be 0.2mm or less. At this time, insert the Pull Stud Clamp vertical to the Pull Bolt. After clamping, the Pull Bolt is pulled in and the seating surfaces and workpiece come in contact.



• Allowable position offset of Pull Stud Clamp and Pull Bolt while teaching must be within the allowable position offset range. At this time, the changing workpiece shouldn't be completely fixed and should have space within the range of allowable offset.

Allowable Position Offset in Horizontal Direction



Model No.	Allowable Offset Amm
WPT0500	$A = \pm 0.5 \text{mm}$
WPT0600	$A = \pm 0.7 \text{mm}$
WPT0800	$A = \pm 0.8 \text{mm}$
WPT1000	$A = \pm 0.9 \text{mm}$

Locating Clamp

Locating

Hand • Clamp

Support

Valve • Coupler

Cautions • Others

Pallet Gripper WVA

Locating Pin Clamp SWF

> WPT JES

FA Pneumatic WKH

Lifting Hole Clamp SWJ

Ball Lock Cylinder WKA

Pneumatic Robotic Hands

> WPS-C WPA WPH WPP

WPO Auto Switch Proximity Switch JEP

High-Power Pneumatio Hole Clamp SWE

High-Power Pneumatio Swing Clamp

WHE High-Power Pneumatio

Link Clamp WCE

Pneumatic Hole Clamp

SWA Pneumatic

Swing Clamp WHA

Double Piston Pneumatic

Swing Clamp WHD

Pneumatic Link Clamp WCA

> Air Flow Control Valve BZW

Manifold Block

WHZ-MD

Notes on Handling

- 1) It should be handled by qualified personnel.
- The hydraulic and pneumatic equipment should be operated and maintained by qualified personnel.
- Do not operate or remove the product unless the safety protocols are ensured.
- ① The machine and equipment can only be inspected or prepared when it is confirmed that the preventive devices are in place.
- ② Before removing the product, make sure that the above-mentioned safety devices are in place. Shut off the pressure and power source, and make sure no pressure exists in the air and hydraulic circuits.
- ③ After stopping the product, do not remove until the temperature drops.
- Make sure there is no trouble/issue in the bolts and respective
 parts before restarting the machine or equipment.
- In order to avoid injury, please do not touch the clamp while it is operating.



- 4) When a robot is in operation, make sure the safety of environment in case of a workpiece detachment.
- 5) Do not disassemble or modify.
- If the equipment is taken apart or modified, the warranty will be voided even within the warranty period.
- Built-in spring is very strong and can be dangerous.

Maintenance and Inspection

- 1) Removal of the Product and Shut-off of Pressure Source
- Before the product is removed, make sure that safety measures and preventive devices are in place. Shut off the pressure and power source, and make sure no pressure exists in the air and hydraulic circuits.
- Make sure there is no trouble/issue in the bolts and respective parts before restarting.
- 2) Clean the product regularly.
- Using the product contaminated with dirt may lead to damage of the product or detachment of a workpiece due to lack of gripping force and malfunctioning, etc.
- Regularly tighten pipings, mounting bolts, etc. to ensure proper use.
- 4) Make sure there is smooth action and no abnormal noise.
- Especially when it is restarted after left unused for a long period, make sure it can be operated correctly.
- 5) The products should be stored in the cool and dark place without direct sunshine or moisture.
- 6) Please contact us for overhaul and repair.Built-in spring is very strong and can be dangerous.



Action Confirmation Method: Sensor for Air Cylinder

This product (model WPT) is able to detect the locking action and releasing action of Sensor for Air Cylinder (sold separately).



Sensor for Air Cylinder model **JES**

In order to ensure stable detections, please use the 3-wire sensor of the high accuracy sensor for air cylinder "model JES0000-02 \square " .

JES is extremely compact.

Refer to P.287 for detailed specifications of JES.

[The Usage Example of Sensor for Air Cylinder]

State	Released State	Locked State
Mounting Ex. for WPT0500	Sensor 1 Sensor 2	
Mounting Ex. for WPT0600	Sensor 1 Sensor 2	
Cylinder Sensor State	Sensor 1 O N Sensor 2 O F F	Sensor 1 OFF Sensor 2 ON

The mounting position and direction of the sensor for air cylinder vary depending on the individual product differences and the magnetic flux change due to the surrounding environment. Please adjust the position of the actual product before use. The sensor for air cylinder may stick out from the installation slot of WPT.

Locating Clamp

Locating

Hand • Clamp

Support

Valve • Coupler

Cautions · Others

Pallet Gripper WVA

Locating

Pin Clamp SWP

WPT

FA Pneumatic

WKH

Lifting Hole Clamp SWJ

Ball Lock Cylinder WKA

Pneumatic

Robotic Hands WPS-C

WPA WPH WPP

WPO Auto Switch Proximity Switch

JEP

High-Power Pneumatio Hole Clamp

SWE

High-Power Pneumatio Swing Clamp

WHE

High-Power Pneumatic Link Clamp WCE

Pneumatic

Hole Clamp SWA

Pneumatic

Swing Clamp WHA

Double Piston Pneumatic

Swing Clamp WHD

Pneumatic Link Clamp

WCA

Air Flow Control Valve BZW

Manifold Block

WHZ-MD

Model No. Indication



1 Design No.

0 : Revision Number

2 Shape

02: Straight (Round Body) **02L**: L Shaped (Round Body) **01**: Straight (Rectangular Body) **01L**: L Shaped (Rectangular Body)









Straight (Round Body)

L Shaped (Round Body) (Rectangular Body) (Rectangular Body)

3 Output Format • Detection Polarity

GN: NPN Output N-Pole Sensor (Cable Color:Black) *1 : NPN Output S-Pole Sensor (Cable Color: Gray) GPN: PNP Output N-Pole Sensor (Cable Color: Black) *1 **GPS**: PNP Output S-Pole Sensor (Cable Color: Gray)

※1. The N-pole sensor cannot be used for the models WCC, WFC and WHC (marked with ※2 in the application table).

For detecting both lock and release actions, both the N-pole sensor and the S-pole sensor are required. However, for the models WCC, WFC and WHC (marked with 32 in the application table), use two S-pole sensors.

Output Application Table $\bullet = canbe installed.$

Shape	Round Body	Rectangular Body
Model No.	JES0000-02G□ JES0000-02GP□ JES0000-02LG□ JES0000-02LGP□	JES0000-01G JES0000-01GP JES0000-01LG JES0000-01LGP
SWJ2000	•	Not Applicable
SWP050□	•	Not Applicable
SWP100□	•	Not Applicable
wcc 🖂	● ※2 (S-pole sensor only)	Not Applicable
WCG <u></u> -T	•	Not Applicable
WFC 🖂	● ※2 (S-pole sensor only)	Not Applicable
WHC 🗀	● ※2 (S-pole sensor only)	Not Applicable
WHGT	•	Not Applicable
WKH200□	•	Not Applicable
WKK100□	•	Not Applicable
WKK200□	•	Not Applicable
WPA0120	•	Not Applicable
WPA0160	•	Not Applicable
WPA0200	•	Not Applicable
WPA0250	•	Not Applicable
WPB0160	•	Not Applicable
WPB0200	•	Not Applicable
WPB0250	•	Not Applicable
WPE0160	•	Not Applicable
WPE0200	Not Applicable	•
WPE0300	Not Applicable	•
WPE0400	Not Applicable	•
WPE0500	Not Applicable	•
WPE0800	Not Applicable	•

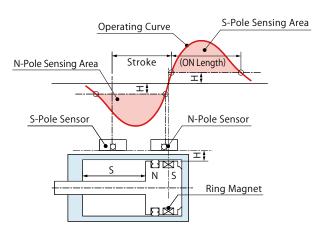
Shape	Round Body	Rectangular Body	
Model No.	JES0000-02G□ JES0000-02GP□ JES0000-02LG□ JES0000-02LGP□	JES0000-01G JES0000-01GP JES0000-01LG JES0000-01LGP	
WPF0100	Not Applicable		
WPF0120	Not Applicable		
WPF0160	•	Not Applicable	
WPF0200	Not Applicable		
WPF0300	Not Applicable	•	
WPH0100	•	Not Applicable	
WPH0160	•	Not Applicable	
WPH0200	Not Applicable	•	
WPJ0120	Not Applicable		
WPJ0160	•	Not Applicable	
WPJ0200	Not Applicable	•	
WPJ0250	Not Applicable	•	
WPJ0300	Not Applicable	•	
WPJ0400	Not Applicable	•	
WPS0160-C	•	Not Applicable	
WPS0200-C	•	Not Applicable	
WPT	•	Not Applicable	
WPW 🗀 -C	•	Not Applicable	
WVAM	•	Not Applicable	
WVBM	•	Not Applicable	
WVGTT	•	Not Applicable	

Specifications

Model No.	JES0000-02G S S JES0000-02LG S S	JES0000-01G N S	JES0000-02GP S JES0000-02LGP S	JES0000-01GP S JES0000-01LGP S
Body Shape	Round	Rectangular	Round	Rectangular
Output Specification	NPN (ON when in proximity)		PNP (ON when in proximity)	
Output Current	20mA Max.		80mA Max.	
Current Consumption	8mA Max.		8mA Max.	
Wiring Method	3-Wire			
Applicable Load	Relay, Programmable Logic Controller (PLC)			
Voltage	DC 5 ~ 24V			
Response Speed	16 μ sec or less			
Material	Case: GF Reinforced PBT Black Set Screw: Brass			iss
Indicator Light	Red			
Withstand Voltage	AC1000V (1 minute / Packaged Charging Part / between the Case)			
Insulation Resistance	DC250V (20M Ω or more in Megohms, between the Case)			
Operating Temperature	−20°C ~ +85°C (Make sure no condensation)			
Operating Humidity	20 ~ 95%RH			
Protection Grade	IP67			
Cable Length	1m			

Performance Curve

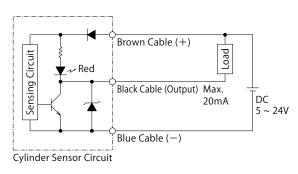
JES detects only the magnetic force that is vertical to the detection surface. The operating curve is shown below. Operating point is on the steep part of the operating curve, so even small stroke can be surely detected.



Electric Circuit Diagram

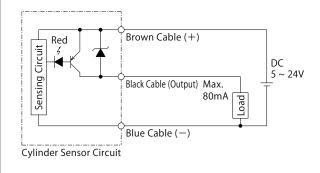
NPN Output

JES0000-02G□、JES0000-02LG□ JES0000-01G□、JES0000-01LG□



PNP Output

JES0000-02GP□、JES0000-02LGP□ JES0000-01GP□、JES0000-01LGP□



Locating + Clamp

Locating

Hand • Clamp

Support

Valve • Coupler

Cautions • Others

Pallet Gripper WVA

Locating

Pin Clamp SWP

High-Power
Pull Stud Clamp
WPT
JES

FA Pneumatic Hole Clamp WKH

Lifting Hole Clamp

SWJ Ball Lock

Cylinder WKA

Pneumatic Robotic Hands

> WPS-C WPA WPH WPP

WPQ
Auto Switch
Proximity Switch

JEP
High-Power Pneumatic
Hole Clamp

SWE

High-Power Pneumatic Swing Clamp WHE

High-Power Pneumatic Link Clamp

WCE

Pneumatic Hole Clamp

SWA Pneumatic

Swing Clamp WHA

Double Piston

Pneumatic Swing Clamp WHD

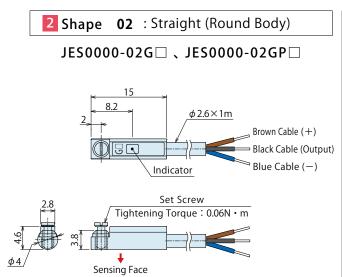
Pneumatic Link Clamp WCA

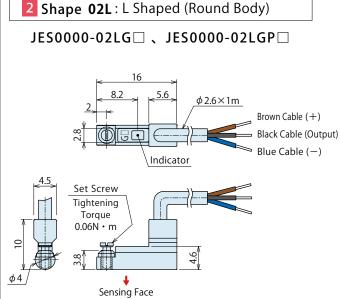
> Air Flow Control Valve BZW

Manifold

Block WHZ-MD

External Dimensions





Shape 01 : Straight (Rectangular Body)

JES0000-01G□ 、JES0000-01GP□

15

02.8×1m

Brown Cable (+)

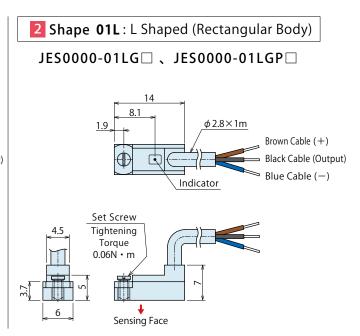
Black Cable (Output)

Blue Cable (−)

Set Screw

Tightening Torque : 0.06N · m

Sensing Face



Notes for Design

- 1) Check the Specifications
- Please use each product according to the specifications.
 The product may be damaged or malfunction if used outside the range of load or specifications.
- 2) Notes on Use in the Interlock Circuit
- When the sensor is used for an interlock signal that requires high reliability, please use a double interlock system by providing a mechanical protection function. Or by using another sensor together with the product. Also, please perform periodic maintenance and confirm proper operation.
- 3) Please avoid using loads that generate surge voltage.
- If driving a relay, put a Zener diode in parallel for surge protection.

Notes on Operating Environment

- 1) Never use the product in an atmosphere with explosive gases.
- Sensor for Air Cylinder is not designed to prevent explosion.
 Do not use the product in an atmosphere with explosive gases since it may cause serious explosions.
- The product may malfunction if an intense magnetic field is applied to a pole body.
- Make sure to prepare shield measures when using in the following environments.
- Where large current and/or strong magnetic field are generated.
- Where noise occurs due to static electricity, etc.
- Where magnetic powder or dust such as iron powder occurs or scatters.
- Do not use the product in an environment where it is continuously exposed to coolant or chemical liquid.
- Although IEC standard IP67 structure is satisfied, please avoid using sensors in an environment where continuously exposed to coolant or chemical liquid. This may cause insulation failure or malfunction.
- 5) Do not use the product in an environment with oil or chemicals.
- If sensors are used in an environment with coolant or cleaning solvent, even in a short time, they may be adversely affected by improper insulation, malfunction due to swelling of potting resin and or hardening of electric cable.
- Do not use the product in an environment with excessive vibrations or impacts.

Installation Notes

- 1) Electric Wiring Reverse Connection Protection
- Follow the electric circuit diagram on P.287 and make sure to connect properly. Never connect the power reversely.
- 2) Tighten sensors with appropriate tightening torque.
- Use the set screw mounted on the sensor body and tighten it with the following torque.

JES0000: 0.06N · m

- 3) Wiring
- Do not damage the cables. Damaged, forcibly bended, stretched, winded, load applied or pinched cables will cause fire, electric shock, and/or malfunction due to electric leakage and/or continuity failure.
- Do not apply excessive stress on the cable port of the sensor.
- Minimum bending radius of the cable port is R7.
- If cables are to move, fix the middle of the cables so that no stress is applied to the cable port.
- 4) Mounting position of the sensor should be adjusted by checking actual operating state.

Locating + Clamp

Locating

Hand • Clamp

Support

Valve • Coupler

Cautions • Others

Pallet Gripper

WVA

Locating Pin Clamp SWP

Stud Clamp

FA Pneumatic Hole Clamp WKH

Lifting Hole Clamp

SWJ Ball Lock

Cylinder

Pneumatic Robotic Hands

> WPS-C WPA WPH WPP

WPQ
Auto Switch
Proximity Switch

JEP

High-Power Pneumatic Hole Clamp SWE

High-Power Pneumation

Swing Clamp WHE

High-Power Pneumation
Link Clamp
WCE

Pneumatic

Hole Clamp

Pneumatic

Swing Clamp WHA

Double Piston Pneumatic

Pneumatic Swing Clamp WHD

Pneumatic

Link Clamp WCA

> Air Flow Control Valve

Manifold Block

WHZ-MD

Notes on Handling

- 1) It should be operated by qualified personnel.
- The hydraulic and pneumatic equipment should be operated and maintained by qualified personnel.
- Do not operate or remove the product unless the safety protocols are ensured.
- ① The machine and equipment can only be inspected or prepared when it is confirmed that the safety devices are in place.
- ② Before the product is removed, make sure that the above-mentioned safety devices are in place. Shut off the pressure and power source, and make sure no pressure exists in the air and hydraulic circuits.
- ③ After stopping the product, do not remove until the temperature drops.
- Make sure there is no trouble/issue in the bolts and respective
 parts before restarting the machine or equipment.
- 3) Do not disassemble or modify.
- If the equipment is taken apart or modified, the warranty will be voided even within the warranty period.
 Never modify the product as it contains a powerful magnet.
- 4) Keep more than one meter away from this product if you have a heart pacemaker, etc. It may be malfunctioned by strong magnetism.
- This sensor is made by ASA Electronics Industry Co. Ltd.
 Please contact us or ASA Electronics Industry for further inquiries.

Maintenance and Inspection

- 1) Removal of the Product and Shut-off of Pressure Source
- Before removing the product, make sure that safety devices and preventive devices are in place. Shut off the pressure and power source, and make sure no pressure exists in the air and hydraulic circuits.
- Make sure there is no trouble/issue in the bolts and respective parts before restarting.
- 2) Never touch terminals while the power is on.
- Otherwise it will cause electric shock, malfunction and damage to the sensor for air cylinder.
- 3) Retightening of Set Screw
- When mounting position of the sensor for air cylinder is shifted due to looseness of set screw, retighten it after adjusting the mounting position.
- 4) Check if the electric cable is damaged or not.
- Damaged cables may cause insulation failure.
 Replace a sensor for air cylinder or repair the reed if the electric cable is damaged.
- 5) Product Storage
- The products should be stored in the cool and dark place without direct sunshine or moisture.

Electric Circuit Model No. Indication Application Table Specifications External Dimensions Cautions Diagram



MEMO

Locating Pin Clamp Ball Lock Pneumatic Double Piston

Locating Clamp Locating

Support

Valve • Coupler

Cautions • Others

Pallet Gripper

WVA

SWP

High-Power Pull Stud Clamp WPT JES

FA Pneumatic Hole Clamp WKH

Lifting Hole Clamp

SWJ

Cylinder WKA

Pneumatic Robotic Hands

WPS-C WPA WPH

WPP WPQ

Auto Switch Proximity Switch JEP

High-Power Pneumatic Hole Clamp

SWE

High-Power Pneumatic Swing Clamp

WHE

High-Power Pneumatic Link Clamp WCE

Pneumatic Hole Clamp

SWA

Swing Clamp WHA

Pneumatic Swing Clamp WHD

Pneumatic

Link Clamp

WCA

Air Flow Control Valve BZW

Manifold

Block WHZ-MD

Notes on Handling

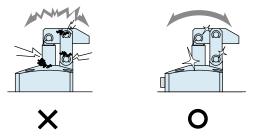
- 1) It should be operated by qualified personnel.
- The hydraulic machine and air compressor should be operated and maintained by qualified personnel.
- 2) Do not operate or remove the product unless the safety protocols are ensured.
- ① The machine and equipment can only be inspected or prepared when it is confirmed that the safety devices are in place.
- ② Before the product is removed, make sure that the above-mentioned safety devices are in place. Shut off the pressure and power source, and make sure no pressure exists in the air and hydraulic circuits.
- ③ After stopping the product, do not remove until the temperature drops.
- 4 Make sure there is no trouble/issue in the bolts and respective parts before restarting the machine or equipment.
- Do not touch a clamp (cylinder) while it is working.
 Otherwise, your hands may be injured.



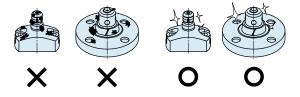
- 4) Do not disassemble or modify.
- If the equipment is taken apart or modified, the warranty will be voided even within the warranty period.

Maintenance and Inspection

- 1) Removal of the Machine and Shut-off of Pressure Source
- Before removing the product, make sure that the safety devices are in place. Shut off the pressure and power source and make sure no pressure exists in the air and hydraulic circuits.
- Make sure there is no trouble/issue in the bolts and respective parts before restarting.
- 2) Regularly clean the area around the piston rod and plunger.
- If it is used when the surface is contaminated with dirt, it may lead to packing seal damage, malfunctioning, fluid leakage.



- Regularly clean the reference surfaces (taper reference surface and seating surface) of locating products (SWT/SWQ/SWP/VRA/ VRC/VX/VXE/VXF/WVS/VWH/VWM/VWK).
- Locating products (except VRA/VRC/VX/VXE/VXF and SWR without air blow port) can remove contaminants with the cleaning function. When installing a workpiece or a pallet, make sure there are no contaminants such as thick sludge.
- Continuous use with dirt on components will lead to locating failure, fluid leakage and malfunction.



- 4) Regularly tighten pipe, mounting bolt, nut, snap ring, cylinder and others to ensure proper use.
- 5) Make sure the hydraulic fluid has not deteriorated.
- 6) Make sure there is a smooth action without an irregular noise.
- Especially when it is restarted after left unused for a long period, make sure it can be operated correctly.
- 7) The products should be stored in the cool and dark place without direct sunshine or moisture.
- 8) Please contact us for overhaul and repair.



Warranty

- 1) Warranty Period
- The product warranty period is 18 months from shipment from our factory or 12 months from initial use, whichever is earlier.
- 2) Warranty Scope
- If the product is damaged or malfunctions during the warranty period due to faulty design, materials or workmanship, we will replace or repair the defective part at our expense. Defects or failures caused by the following are not covered.
- ① If the stipulated maintenance and inspection are not carried out.
- ② Failure caused by the use of the non-confirming state at the user's discretion.
- ③ If it is used or operated in an inappropriate way by the operator. (Including damage caused by the misconduct of the third party.)
- ④ If the defect is caused by reasons other than our responsibility.
- ⑤ If repair or modifications are carried out by anyone other than Kosmek, or without our approval and confirmation, it will void warranty.
- ⑥ Other caused by natural disasters or calamities not attributable to our company.
- $\ensuremath{{\ensuremath{\bigcirc}}}$ Parts or replacement expenses due to parts consumption and deterioration.

(Such as rubber, plastic, seal material and some electric components.)

Damages excluding from direct result of a product defect shall be excluded from the warranty.

Clamp Locating

Locating

Hand • Clamp

Support

Valve • Coupler

Cautions • Others

Cautions

Installation Notes

Company Profile

Company Profile Our Products

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Alphabetical Order

Sales Offices



Sales Offices

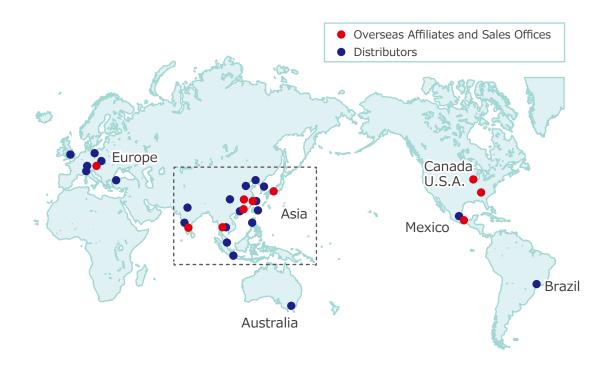
Sales Offices across the World

Japan	KOSMEK LTD. HEAD OFFICE	TEL. +81-78-991-5162 FAX. +81-78-991-8787 1-5, 2-chome, Murotani, Nishi-ku, Kobe-city, Hyogo, Japan 651-2241
USA	KOSMEK (USA) LTD. Overseas Affiliate	TEL. +1-630-620-7650 FAX. +1-630-620-9015 650 Springer Drive, Lombard, IL 60148 USA
	KOSMEK (USA) LTD. Atlanta Branch Office	TEL. +1-630-620-7650 303 Perimeter Center North, Suite 300, Atlanta, GA 30346 USA
Mexico	KOSMEK (USA) LTD. Mexico Branch Office	TEL. +52-442-851-1377 Av. Santa Fe 103, Int. 59, col. Santa Fe Juriquilla, Queretaro, QRO, 76230, Mexico
Europe	KOSMEK EUROPE GmbH Overseas Affiliate	TEL. +43-463-287587 FAX. +43-463-287587-20 Schleppeplatz 2 9020 Klagenfurt am Wörthersee Austria
	KOSMEK (CHINA) LTD. Overseas Affiliate	TEL.+86-21-54253000 FAX. +86-21-54253709 Room601, RIVERSIDE PYRAMID No.55, Lane21, Pusan Rd, Pudong Shanghai China
China	KOSMEK (CHINA) LTD. Dongguan Office Overseas Affiliate (Sales Office)	TEL.+86-769-85300880 Room301,AcerBuilding No.15,Dezheng(W)Road,Changan Town Dongguan Guangdong 523843,,P.R.China
	KOSMEK (CHINA) LTD. Wuhan Office Overseas Affiliate (Sales Office)	TEL.+86-27-59822303 A-502 Jingkai Future City,Zhuankou Economic Development Zone Wuhan Huibei
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Taiwan	FULL LIFE TRADING CO., LTD. Taiwan Exclusive Distributor	TEL. +886-2-82261860 FAX. +886-2-82261890 16F-4, No.2, Jian Ba Rd., Zhonghe District, New Taipei City Taiwan 23511
Philippines	G.E.T. Inc, Phil. Philippines Exclusive Distributor	TEL.+63-2-310-7286 FAX. +63-2-310-7286 Victoria Wave Special Economic Zone Mt. Apo Building, Brgy. 186, North Caloocan City, Metro Manila, Philippines 1427
Indonesia	PT. Yamata Machinery Indonesia Exclusive Distributor	TEL. +62-21-29628607 FAX. +62-21-29628608 Delta Commercial Park I, Jl. Kenari Raya B-08, Desa Jayamukti Kec. Cikarang Pusat Kab. Bekasi 17530 Indonesia

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Head Office Osaka Sales Office Overseas Sales	TEL. 078-991-5162 1-5, 2-chome, Murotani, Nish	FAX. 078-991-8787 i-ku, Kobe-city, Hyogo, 651-2241, Japan
Tokyo Sales Office	TEL. 048-652-8839 81, 4-chome, Onari-cho, Kita-	FAX. 048-652-8828 -ku, Saitama City, Saitama, 331-0815, Japan
Nagoya Sales Office	TEL. 0566-74-8778 10-1, 2-chome, Misono-cho,	FAX. 0566-74-8808 Anjo City, Aichi, 446-0076, Japan
Fukuoka Sales Office	TEL. 092-433-0424 8-10-101, 1-chome, Kamimut	FAX. 092-433-0426 ta, Hakata-ku, Fukuoka City, Fukuoka, 812-0006, Japan

Global Network



Asia Detailed Map





