High-Power Welding Swing Clamp

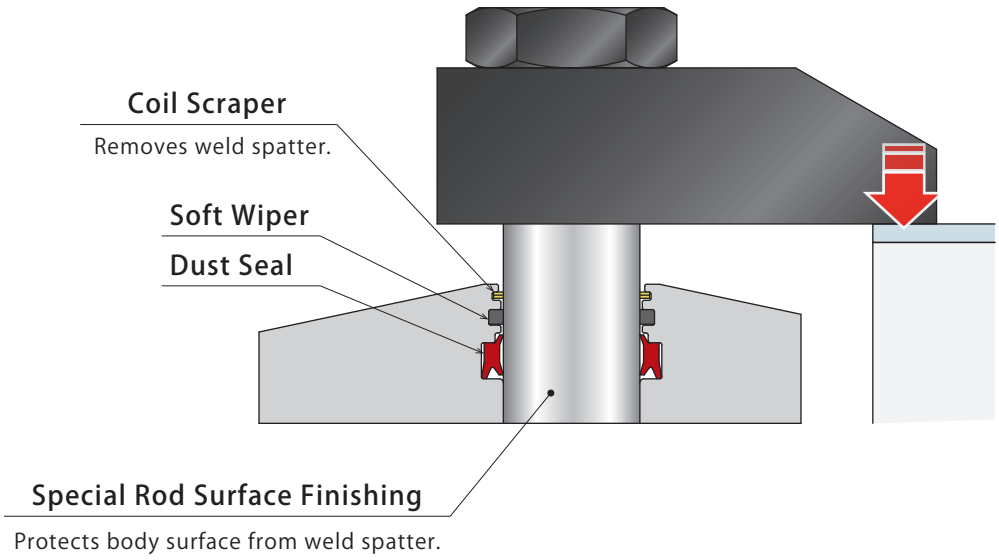
Model WHG

Spatter Resistant High-Power Welding Swing Clamp

PAT.

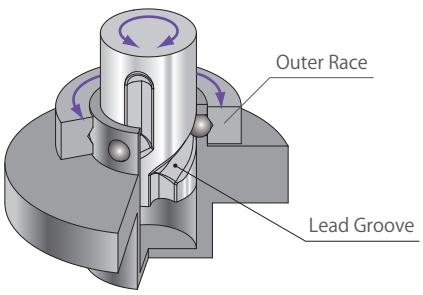
Features

High Durability Triple protective structure prevents contaminants from entering the cylinder.



- **Swing Mechanism with High Speed and High Durability**

  Our strong hydraulic clamp mechanism is used to pneumatic clamps.
  Makes it faster with 3 lines of lead groove + outer race.
  (High Rigidity makes it possible to use a long lever.)



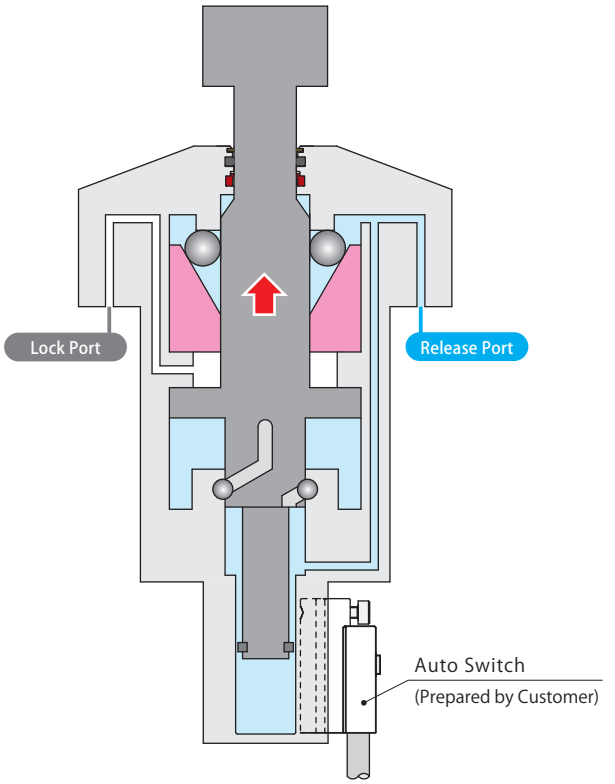
Ball Guide Part

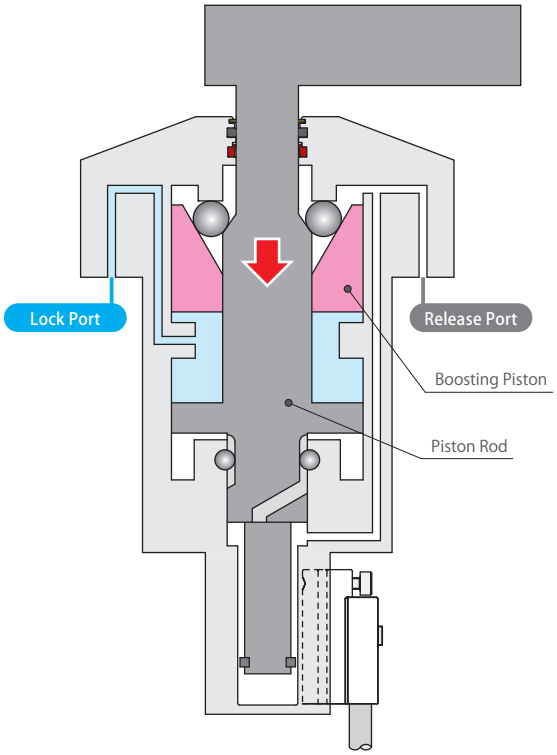
The High-Power Welding Swing Clamp is a hybrid system using air pressure and a mechanical lock.

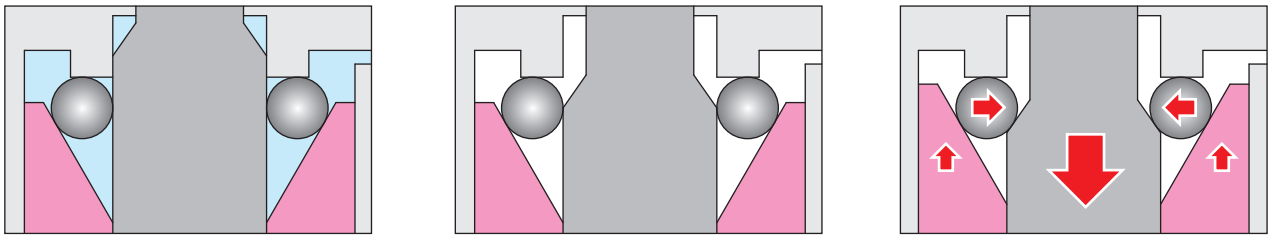
Action Description

Released State
Lock Air OFF
Release Air ON

Locked State
Lock Air ON
Release Air OFF







Released State

The piston rod ascends to release.

Locking Operation

(Swing Stroke+Vertical Stroke 2mm)

① The piston rod rotates while it descends along the cam.

② After swing completion, the piston descends vertically until the lever clamps the workpiece.

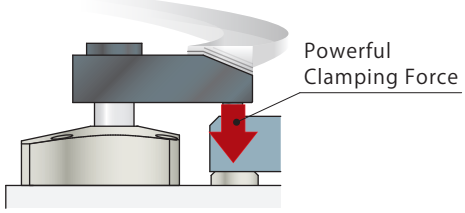
Locked State

(Boosting Stroke 4mm)

The piston rod descends and the boosting piston activates. Exerts strong clamping force and holding force with the wedge mechanism.

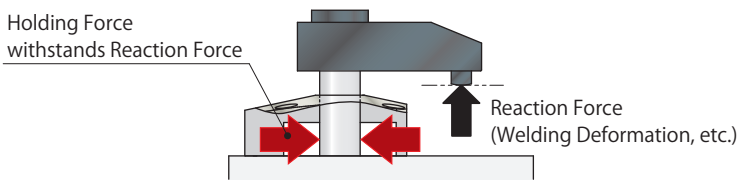
No Hydraulic Use

Welding fixture system with high-power welding clamps exerting equivalent force to hydraulic clamps needs no hydraulic pressure.



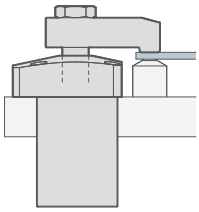
Holding Force

Minimal clamping force and powerful holding force minimize workpiece deformation. Mechanical locking allows holding force to exert 3 times the clamping force at most.

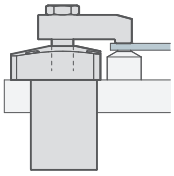


Smaller Footprint

Exerts three times clamping force compared to the same size general air cylinder. Smaller cylinder allows for more compact fixtures.

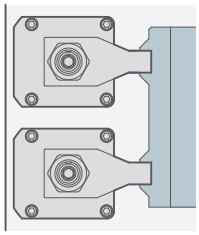


General Air Cylinder

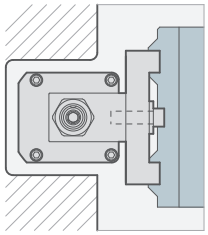


High-Power Welding Clamp

Downsized



General Air Cylinder

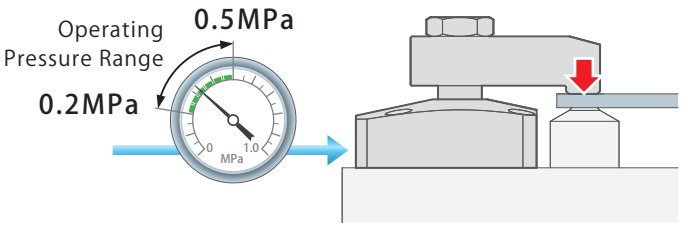


High-Power Welding Clamp

Reduced Number of Clamps

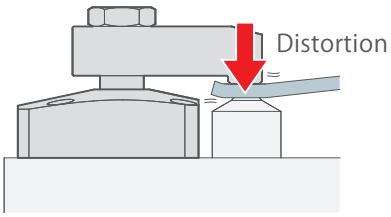
Energy Saving

Energy-saving clamp exerts high clamping force with low pressure.

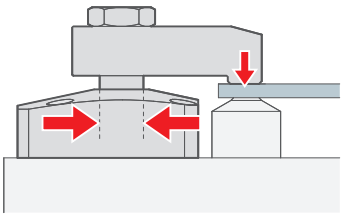


High Quality

Optimum clamping force does not distort workpiece and holding force is strong enough to withstand welding load.



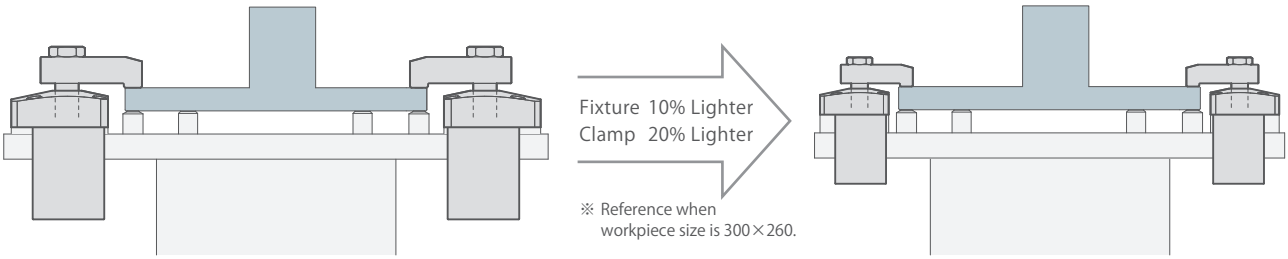
Strong clamping force distorts workpiece.



Clamping force is lowered, yet workpiece can be supported with holding force.

Light Weight

High-Power Welding Clamp allows for lighter fixture, minimizing load to the positioner.

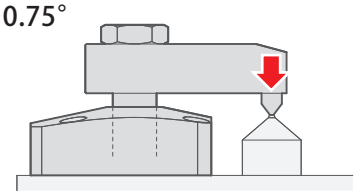


General Air Cylinder

High-Power Welding Clamp

High Accuracy

High locating accuracy at locked position allows for precise clamping.
Swing Complete Position Repeatability：±0.75°



Action Confirmation

Safely used in automation systems with action confirmation of Auto Switch.

Auto Switch (Prepared by Customer)

Ability to Confirm Lock/Release Actions

Recommended Auto Switch

Magnetic Field Resistant Model：D-P3DWA (made by SMC)
JEP/JES Series (made by KOSMEK) ※1 ※2

Notes :

※1. Please refer to FA・Industrial Robot Related Products Complete Catalog (CATALOG No.FA0020□□-□□-G1B) for the detailed specifications of JEP/JES series.

※2. Please use D-P3DWA (made by SMC) for an environment which generates a magnetic field disturbance. JEP/JES series cannot be used in such an environment.

1. When using an auto switch not made by Kosmek, check specifications of each manufacturer.
2. Auto Switch may be stuck out of the clamp depending on the installation position and direction.

Model No. Indication

WHG 160 0 – 2 A R T

1 2 3 4 5

1 Cylinder Force

100 : Cylinder Force 1.0 kN (Air Pressure 0.5MPa)
160 : Cylinder Force 1.6 kN (Air Pressure 0.5MPa)
250 : Cylinder Force 2.4 kN (Air Pressure 0.5MPa)
400 : Cylinder Force 3.9 kN (Air Pressure 0.5MPa)

※ Cylinder force differs from clamping force and holding force.

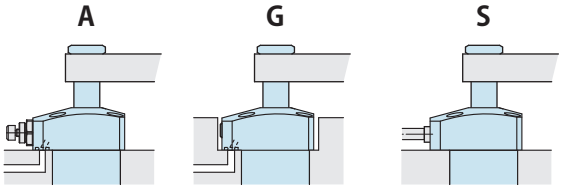
2 Design No.

0 : Revision Number

3 Piping Method

A : Gasket Option (with Ports for Speed Controller)
G : Gasket Option (with R Thread Plug)
S : Piping Option (Rc Thread)

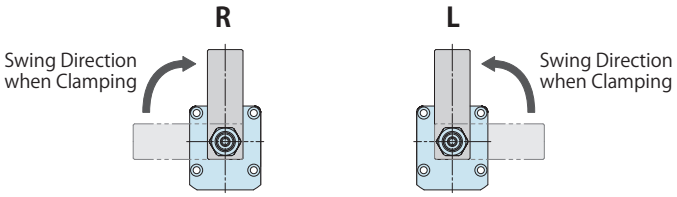
※ Speed control valve (BZW) is sold separately.
Please refer to P.79.



Gasket Option		Piping Option
With Ports for Speed Controller Includes R Thread Plug (order speed controller separately)	with R Thread Plug	Rc Thread No Gasket Port

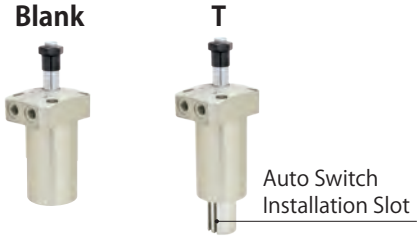
4 Swing Direction when Clamping

R : Clockwise
L : Counter-Clockwise



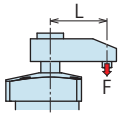
5 Action Confirmation Method

Blank : None (Standard)
T : With Auto Switch Installation Slot



Specifications

Model No.		WHG1000-2□□□	WHG1600-2□□□	WHG2500-2□□□	WHG4000-2□□□
Cylinder Force (at 0.5MPa)	kN	1.0	1.6	2.4	3.9
Clamping Force (Calculation Formula) ※1	kN	F=(1.8842-0.00346×L)×P	F=(3.0603-0.00505×L)×P	F=(4.7875-0.00654×L)×P	F=(7.6871-0.00947×L)×P
Holding Force (Calculation Formula) ※1	kN	$Fk=\frac{4.08\times P}{1-0.0021\times L}$	$Fk=\frac{6.628\times P}{1-0.0012\times L}$	$Fk=\frac{10.481\times P}{1-0.0008\times L}$	$Fk=\frac{16.806\times P}{1-0.0006\times L}$
Full Stroke	mm	14.5	15	17.5	19.5
Swing Stroke (90°)	mm	8.5	9	11.5	13.5
Vertical Stroke	mm	6			
(Break down) Idle Stroke	mm	2			
(Break down) Lock Stroke※2	mm	4			
Swing Angle Accuracy		90° ±3°			
Swing Completion Position Repeatability		±0.75°			
Max. Operating Pressure	MPa	0.5			
Min. Operating Pressure※3	MPa	0.2			
Withstanding Pressure	MPa	0.75			
Operating Temperature	℃	0 ~ 70			
Usable Fluid		Dry Air			



Notes：

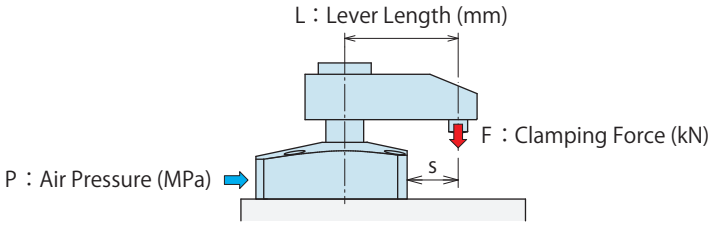
※1. F：Clamping Force (kN), Fk：Holding Force (kN), P：Supply Air Pressure (MPa),
L：Distance between the piston center and the clamping point (mm).

※2. The specification value of cylinder force, clamping force, holding force and swing completion position repeatability is fulfilled only when clamping within the lock stroke range.
(Please refer to "The specification value is not fulfilled when clamping out of the lock stroke range." on P.59.)

※3. Minimum pressure to operate the clamp without load.
The clamp may stop in the middle of swing action depending on the lever shape. (Refer to "Notes on Lever Design" on P.59.)

1. Please refer to External Dimensions for the cylinder capacity and the product weight.

Clamping Force Curve



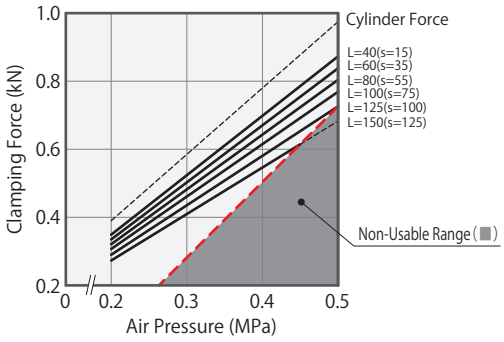
(How to read the Clamping Force Curve)
In case of WHG1600
Supply Air Pressure 0.4MPa
Lever Length L=60mm
Clamping force is about 1.1kN.

Notes：
※1. F : Clamping Force (kN), P : Supply Air Pressure (MPa), L : Lever Length (mm).
1. Tables and graphs show the relationship between the clamping force (kN) and supply air pressure (MPa).
2. Cylinder force (When L=0) cannot be calculated from the calculation formula of clamping force.
3. Clamping force shown in the below tables and graphs is the value when clamping within the lock stroke range. (Please refer to "The specification value is not fulfilled when clamping out of the lock stroke range." on P.59.)
4. The clamping force is shown with lever in the locked position.
5. The clamping force varies as per the lever length. Please use it with supply air pressure suitable for lever length.
6. Operation in the non-usable range can damage the clamp and lead to fluid leakage.

WHG1000

Clamping Force Calculation Formula※1(kN) $F = (1.8842 - 0.00346 \times L) \times P$

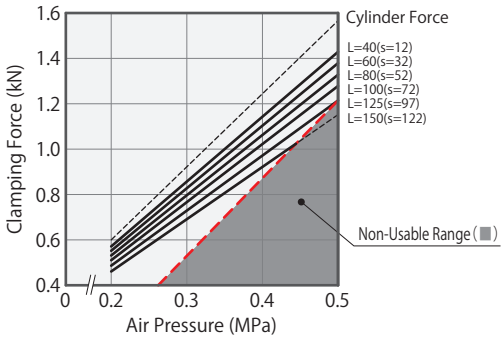
Air Pressure (MPa)	Cylinder Force (kN)	Clamping Force (kN) Non-Usable Range (■) Lever Length L (mm) 40	60	80	100	125	150	Max. Lever Length (mm)
0.5	0.98	0.87	0.84	0.80	0.77	0.73		125
0.4	0.78	0.70	0.67	0.64	0.62	0.58	0.55	180
0.3	0.59	0.52	0.50	0.48	0.46	0.44	0.41	190
0.2	0.39	0.35	0.34	0.32	0.31	0.29	0.27	190
Max. Operating Pressure (MPa)		0.5	0.5	0.5	0.5	0.5	0.44	



WHG1600

Clamping Force Calculation Formula※1(kN) $F = (3.0603 - 0.00505 \times L) \times P$

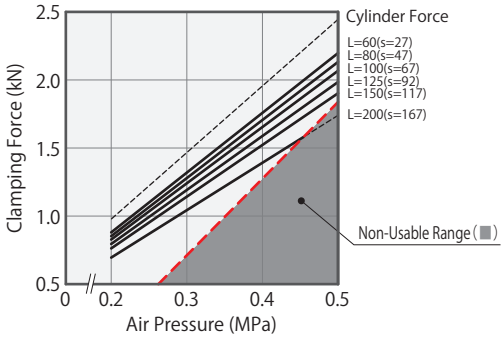
Air Pressure (MPa)	Cylinder Force (kN)	Clamping Force (kN) Non-Usable Range (■) Lever Length L (mm) 40	60	80	100	125	150	Max. Lever Length (mm)
0.5	1.57	1.43	1.38	1.33	1.28	1.22		125
0.4	1.25	1.14	1.10	1.06	1.02	0.97	0.92	174
0.3	0.94	0.86	0.83	0.80	0.77	0.73	0.69	200
0.2	0.63	0.57	0.55	0.53	0.51	0.49	0.46	200
Max. Operating Pressure (MPa)		0.5	0.5	0.5	0.5	0.5	0.44	



WHG2500

Clamping Force Calculation Formula※1(kN) $F = (4.7875 - 0.00654 \times L) \times P$

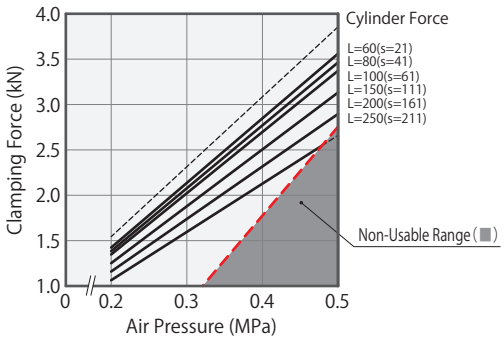
Air Pressure (MPa)	Cylinder Force (kN)	Clamping Force (kN) Non-Usable Range (■) Lever Length L (mm) 60	80	100	125	150	200	Max. Lever Length (mm)
0.5	2.44	2.20	2.13	2.07	1.99	1.90		170
0.4	1.96	1.76	1.71	1.65	1.59	1.52	1.39	245
0.3	1.47	1.32	1.28	1.24	1.19	1.14	1.04	270
0.2	0.98	0.88	0.85	0.83	0.79	0.76	0.70	270
Max. Operating Pressure (MPa)		0.5	0.5	0.5	0.5	0.5	0.45	



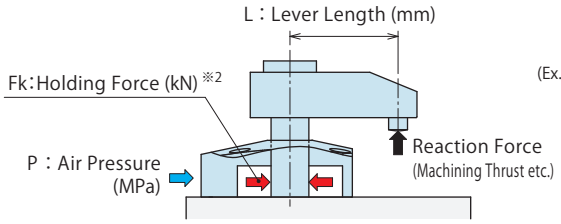
WHG4000

Clamping Force Calculation Formula※1(kN) $F = (7.6871 - 0.00947 \times L) \times P$

Air Pressure (MPa)	Cylinder Force (kN)	Clamping Force (kN) Non-Usable Range (■) Lever Length L (mm) 60	80	100	150	200	250	Max. Lever Length (mm)
0.5	3.86	3.56	3.46	3.37	3.13	2.90		230
0.4	3.09	2.85	2.77	2.70	2.51	2.32	2.13	330
0.3	2.32	2.14	2.08	2.02	1.88	1.74	1.60	330
0.2	1.54	1.42	1.39	1.35	1.25	1.16	1.06	330
Max. Operating Pressure (MPa)		0.5	0.5	0.5	0.5	0.5	0.48	

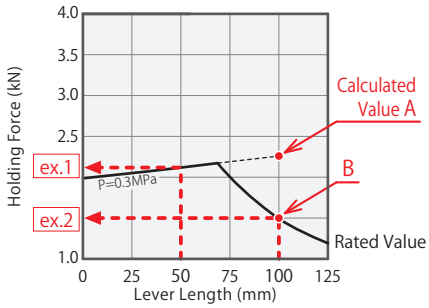


Holding Force Curve



(Ex.1) In case of WHG1600 :
When supply air pressure P is 0.3MPa and lever length L is 50mm, holding force becomes about 2.1kN.

(Ex.2) In case of WHG1600 : When supply air pressure P is 0.3MPa and lever length L is 100mm, the calculated value is at the point A but it is above the rated value. In this case, the value of intersection B on the rated value becomes the holding force that counters the reaction force, and it becomes about 1.5kN.



Notes:

※2. Holding force is the force that counters the reaction force in the clamping state, and differs from clamping force.
Please keep in mind that it can produce displacement depending on lever rigidity even if the reaction force is lower than holding force.
(If slight displacement is also not allowed, please keep the reaction force beyond clamping force from being applied.)

※3. Fk : Holding Force (kN) , P : Supply Air Pressure (MPa) , L : Lever Length (mm).
When the calculated holding force exceeds the rated value in the graph, the holding force becomes the rated value.

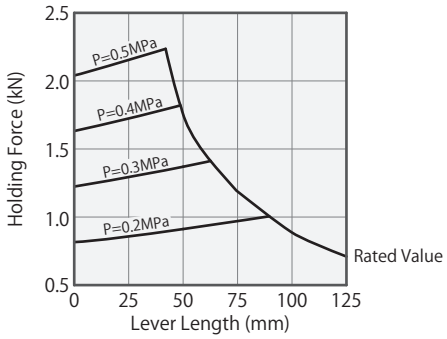
1. Tables and graphs show the relationship between the holding force (kN) and lever length (mm).
2. Values in below charts indicate holding force when clamping within the lock stroke range.
(Please refer to "The specification value is not fulfilled when clamping out of the lock stroke range." on P.59.)
3. Values in below charts indicate holding force when the lever locks a workpiece in horizontal position.
4. The holding force varies depending on the lever length. Set the suitable supply air pressure based on the lever length.
5. The reaction force exceeding the holding force shown in the table and the graph may cause damage and fluid leakage.

WHG1000

Holding Force Formula ※3 (Fk ≦ Rated Value) (kN)

$$Fk = \frac{4.08 \times P}{1 - 0.0021 \times L}$$

Air Pressure (MPa)	Holding Force (kN) Non-Usable Range( ) Lever Length L (mm)					
	40	60	80	100	125	150
0.5	2.23	1.51	1.13	0.91	0.73	
0.4	1.78	1.51	1.13	0.91	0.73	0.61
0.3	1.34	1.40	1.13	0.91	0.73	0.61
0.2	0.89	0.93	0.98	0.91	0.73	0.61

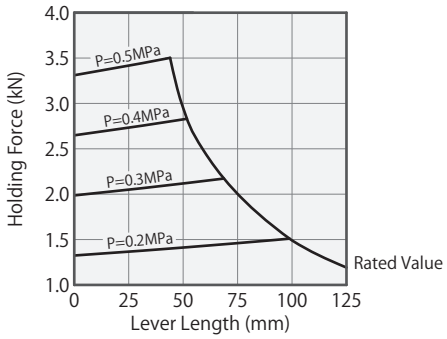


WHG1600

Holding Force Formula ※3 (Fk ≦ Rated Value) (kN)

$$Fk = \frac{6.628 \times P}{1 - 0.0012 \times L}$$

Air Pressure (MPa)	Holding Force (kN) Non-Usable Range( ) Lever Length L (mm)					
	40	60	80	100	125	150
0.5	3.48	2.53	1.90	1.52	1.22	
0.4	2.79	2.53	1.90	1.52	1.22	1.01
0.3	2.09	2.14	1.90	1.52	1.22	1.01
0.2	1.39	1.43	1.47	1.51	1.22	1.01

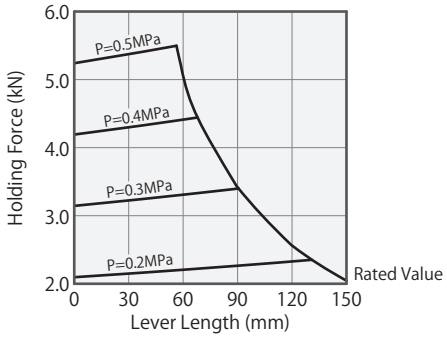


WHG2500

Holding Force Formula ※3 (Fk ≦ Rated Value) (kN)

$$Fk = \frac{10.481 \times P}{1 - 0.0008 \times L}$$

Air Pressure (MPa)	Holding Force (kN) Non-Usable Range( ) Lever Length L (mm)					
	60	80	100	125	150	200
0.5	5.21	3.91	3.12	2.50	2.08	
0.4	4.40	3.91	3.12	2.50	2.08	1.56
0.3	3.30	3.36	3.12	2.50	2.08	1.56
0.2	2.20	2.24	2.28	2.33	2.08	1.56

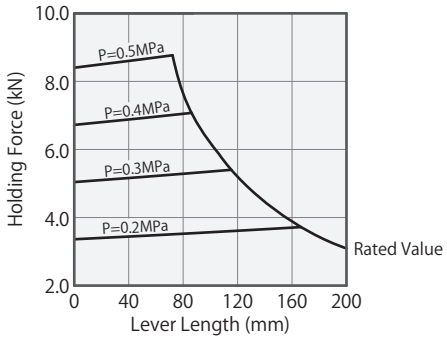


WHG4000

Holding Force Formula ※3 (Fk ≦ Rated Value) (kN)

$$Fk = \frac{16.806 \times P}{1 - 0.0006 \times L}$$

Air Pressure (MPa)	Holding Force (kN) Non-Usable Range( ) Lever Length L (mm)					
	60	80	100	150	200	250
0.5	8.72	7.92	6.34	4.22	3.17	
0.4	6.97	7.06	6.34	4.22	3.17	2.53
0.3	5.23	5.30	5.36	4.22	3.17	2.53
0.2	3.49	3.53	3.58	3.69	3.17	2.53

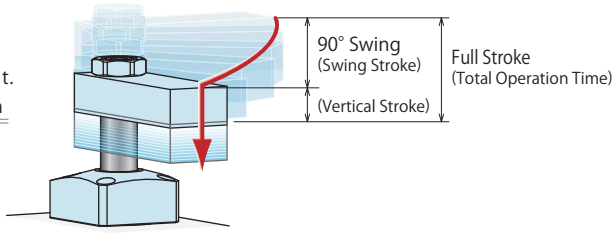


Allowable Swing Time Graph

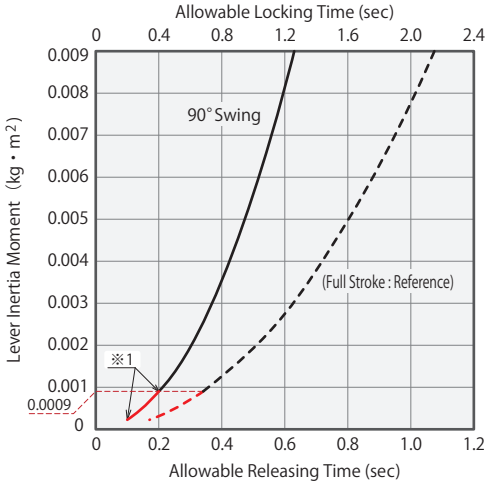
Adjustment of Swing Time

The graph shows allowable swing time against lever inertia moment. Please make sure that an operation time is more than the operation time shown in the graph.

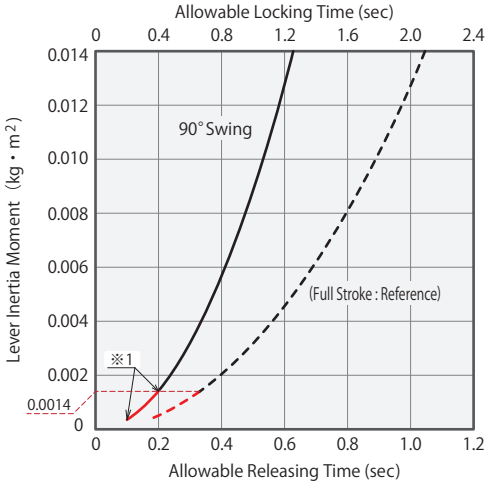
Excessive action speed can reduce stopping accuracy and damage internal parts.



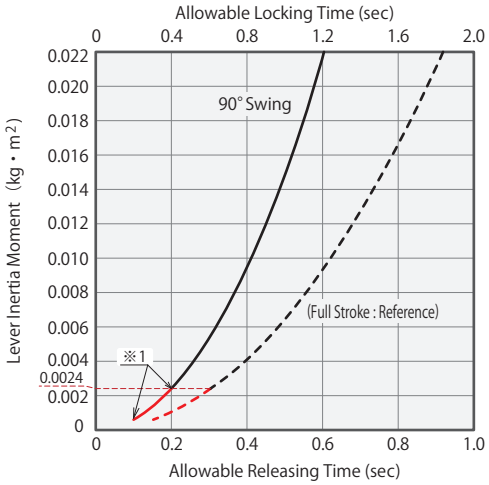
WHG1000



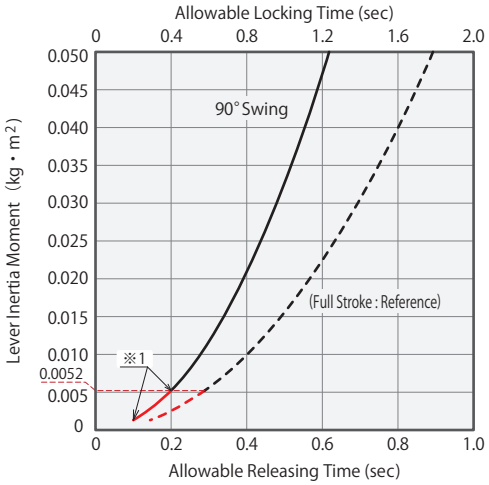
WHG1600



WHG2500



WHG4000



Notes:

※1. For any lever inertia moment, minimum 90° swing time should be 0.2 sec.

1. There may be no lever swing action with large inertia depending on supply air pressure, flow and lever mounting position.
2. For speed adjustment of clamp lever, please use meter-out flow control valve.
   In case of meter-in control, the clamp lever may be accelerated by its own weight during swinging motion (clamp mounted horizontally) or the piston rod may be moving too fast.
   (Please refer to P.59 for speed adjustment.)
3. Please contact us if operational conditions differ from those shown on the graphs.

(How to read the Allowable Swing Time Graph)

In case of WHG1600

Lever Inertia Moment : 0.005 kg·m²

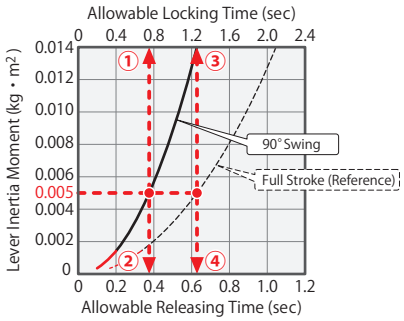
① 90° Swing Time when Locking : About 0.76 sec or more

② 90° Swing Time when Releasing : About 0.38 sec or more

③ Total Lock Operation Time : About 1.27 sec or more

④ Total Release Operation Time : About 0.63 sec or more

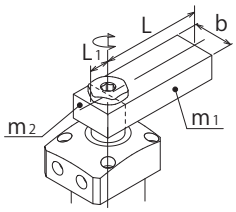
1. The total operation time on the graph represents the allowable operation time when fully stroked.



How to calculate inertia moment (Estimated)

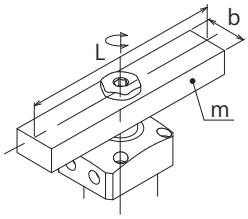
I : Inertia Moment (kg・m²) L,L₁,L₂,K,b : Length (m) m,m₁,m₂,m₃ : Weight (kg)

① For a rectangular plate (cuboid), the rotating shaft is vertically on one side of the plate.



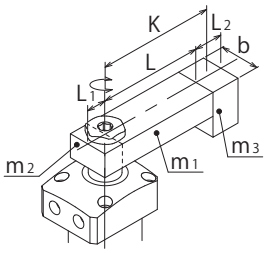
$$I = m_1 \frac{4L^2+b^2}{12} + m_2 \frac{4L_1^2+b^2}{12}$$

② For a rectangular plate (cuboid), the rotating shaft is vertically on the gravity center of the plate.



$$I = m \frac{L^2+b^2}{12}$$

③ The load is applied on the lever front end.

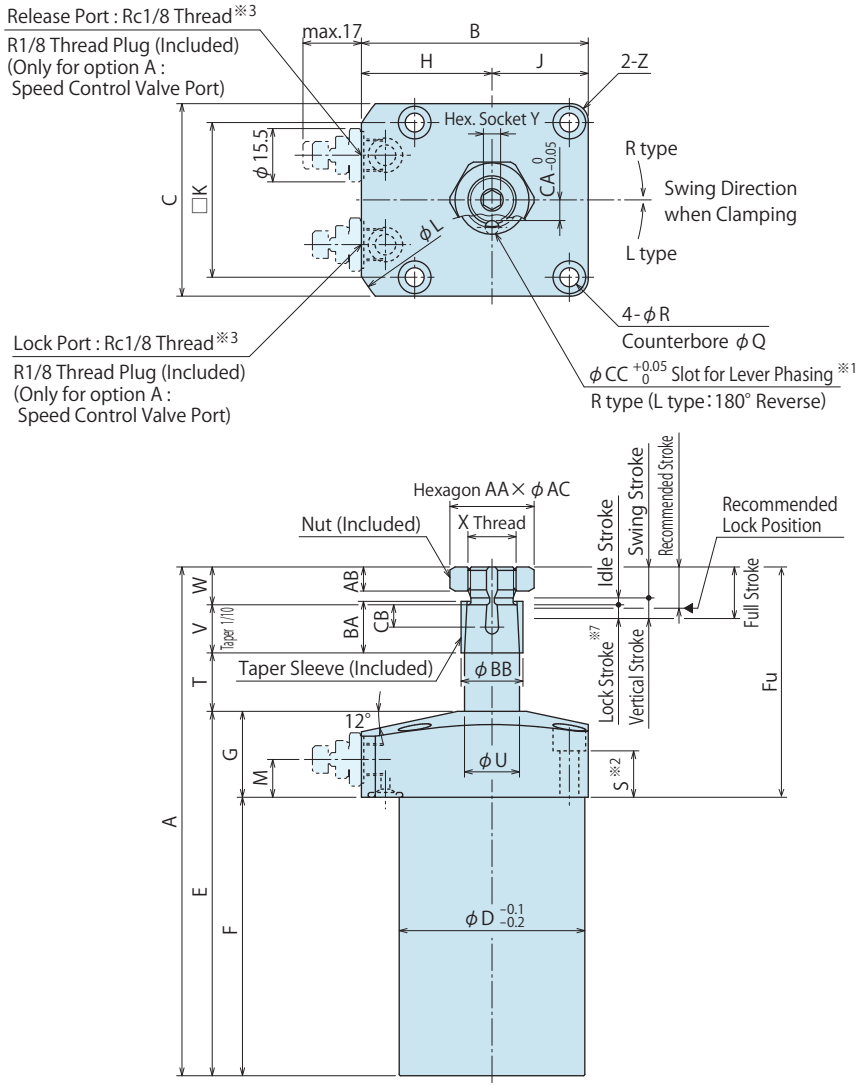


$$I = m_1 \frac{4L^2+b^2}{12} + m_2 \frac{4L_1^2+b^2}{12} + m_3K^2 + m_3 \frac{L_2^2+b^2}{12}$$

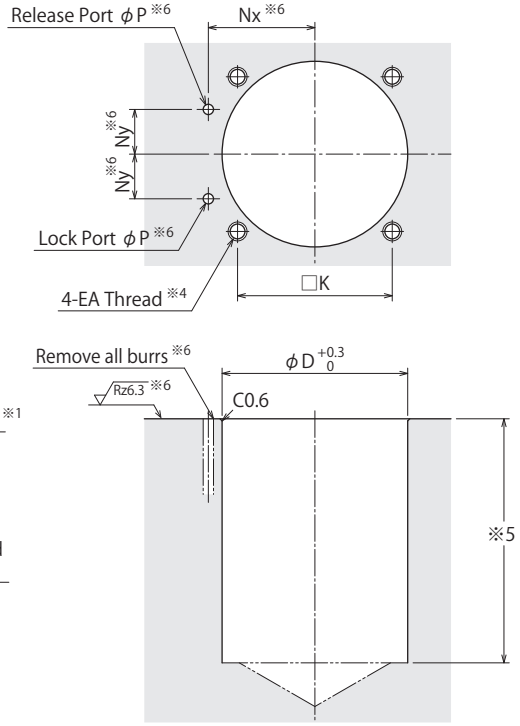
External Dimensions

A：Gasket Option (With Ports for Speed Controller：R-Thread Plug Included)

※ The drawing shows the released state of WHG-2AR.



Machining Dimensions of Mounting Area

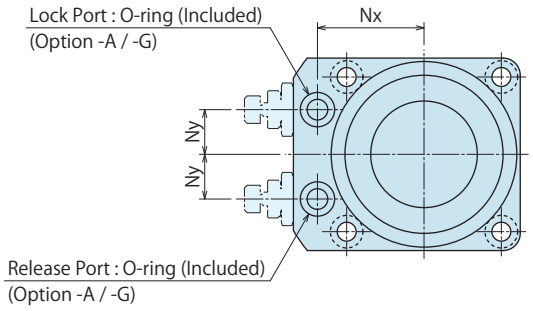


Notes：

※4. EA tapping depth of the mounting bolt should be decided according to the mounting height referring to dimension 'S'.

※5. The depth of the body mounting hole ϕD should be decided according to the mounting height referring to dimension 'F'.

※6. The machining dimension is for -A/-G：Gasket Option.



Notes：

※1. The slot for lever phasing faces the port side when locked.

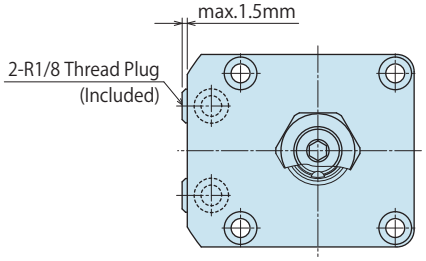
※2. Mounting bolts are not provided. Please prepare them according to the mounting height referring to dimension 'S'.

※3. Speed control valve is sold separately. Please refer to P.79.

Piping Method

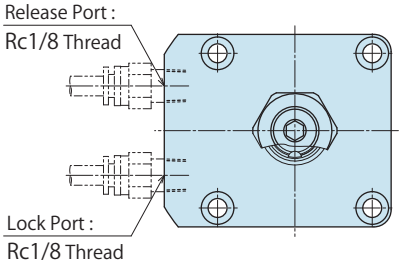
G : Gasket Option (With R Thread Plug)

※The drawing shows the released state of WHG-2GR.



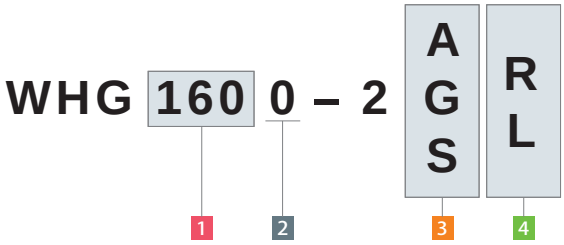
S : Piping Option (Rc Thread)

※The drawing shows the released state of WHG-2SR.



Model No. Indication

(Format Example：WHG1000-2AR, WHG2500-2SL)



1 Cylinder Force
2 Design No.
3 Piping Method
4 Swing Direction when Clamping
5 Action Confirmation (When Blank is chosen)

External Dimensions and Machining Dimensions for Mounting

(mm)

Model No.	WHG1000-2□□	WHG1600-2□□	WHG2500-2□□	WHG4000-2□□
Full Stroke	14.5	15	17.5	19.5
Swing Stroke (90°)	8.5	9	11.5	13.5
Vertical Stroke	6			
(Breakdown) Idle Stroke	2			
(Breakdown) Lock Stroke ※7	4			
Recommended Stroke	11.5	12	14.5	16.5
A	138.5	148	174	192.5
B	60	66	76	87
C	50	56	66	78
D	46	54	64	77
E	99.5	106	124.5	135
F	74.5	81	94.5	105
Fu	64	67	79.5	87.5
G	25	25	30	30
H	35	38	43	48
J	25	28	33	39
K	39	45	53	65
L	79	88	98	113
M	11	11	13	13
Nx	28	31	36	41
Ny	10	13	15	20
P	max. ϕ5	max. ϕ5	max. ϕ5	max. ϕ5
Q	9.5	9.5	11	11
R	5.5	5.5	6.8	6.8
S	14	13.5	16	15
T	16.5	17	19.5	21.5
U	14	16	20	25
V	12	14	17	21
W	10.5	11	13	15
X (Nominal × Pitch)	M12×1.5	M14×1.5	M16×1.5	M22×1.5
Y	5	5	6	8
Z (Chamfer)	R5	R5	R6	R6
AA	19	22	24	32
AB	6.5	7	8	10
AC	21.2	24.5	26.5	35.5
BA	13	15	18	22
BB	16	18	22	28
CA	5	6	8	10
CB	4.5	6.5	5.5	9.5
CC	4	4	4	6
EA (Nominal×Pitch)	M5×0.8	M5×0.8	M6×1	M6×1
O-ring (Option A/G)	1BP7	1BP7	1BP7	1BP7
Cylinder Capacity cm³ Lock	21.8	35.5	61.3	103.8
Cylinder Capacity cm³ Release	25.5	40.3	69.2	117.6
Weight ※8 kg	0.8	1.0	1.8	2.9

Notes：

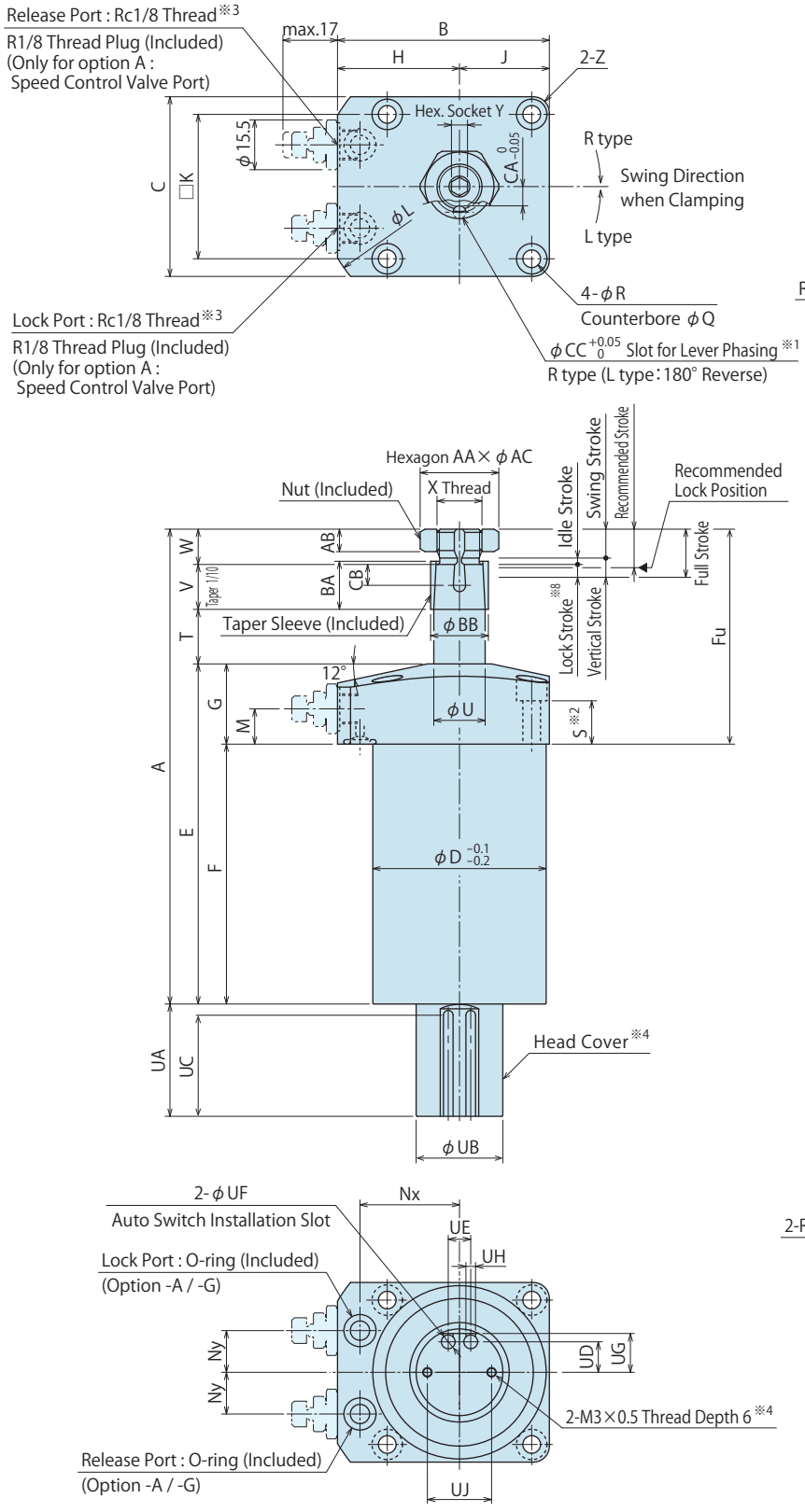
※7. The specification value of cylinder force, clamping force, holding force and swing completion position repeatability is fulfilled only when clamping within the lock stroke range.
(The specification value is not fulfilled when clamping within the range of swing stroke and idle stroke.)

※8. It shows the weight of single swing clamp including taper sleeve and nut.

External Dimensions

A：Gasket Option (With Ports for Speed Controller：R-Thread Plug Included)

※ The drawing shows the released state of WHG-2ART.



Notes：

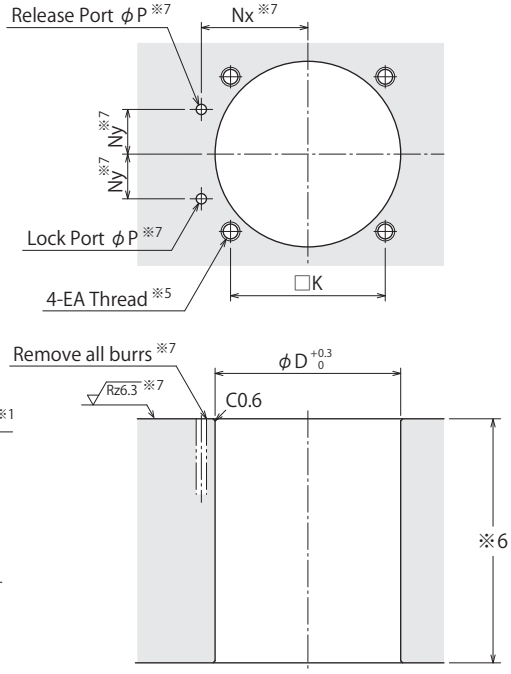
※1. The slot for lever phasing faces the port side when locked.

※2. Mounting bolts are not provided. Please prepare them according to the mounting height referring to dimension 'S'.

※3. Speed control valve is sold separately. Please refer to P.79.

※4. The direction of the Head Cover is not as indicated in the drawing. Adjust the direction as you need. Use M3 tapped holes on the bottom to fix the head cover with bracket.

Machining Dimensions of Mounting Area



Notes：

※5. EA tapping depth of the mounting bolt should be decided according to the mounting height referring to dimension 'S'.

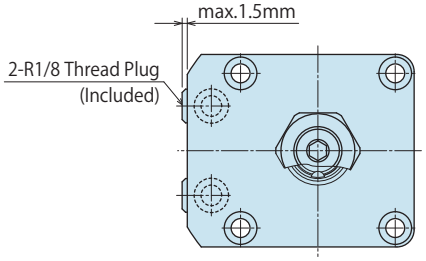
※6. The depth of the body mounting hole ϕD should be decided according to the mounting height referring to dimension 'F'.

※7. The machining dimension is for -A/-G：Gasket Option.

Piping Method

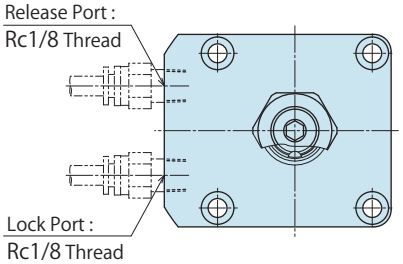
G : Gasket Option (With R Thread Plug)

※The drawing shows the released state of WHG-2GRT.



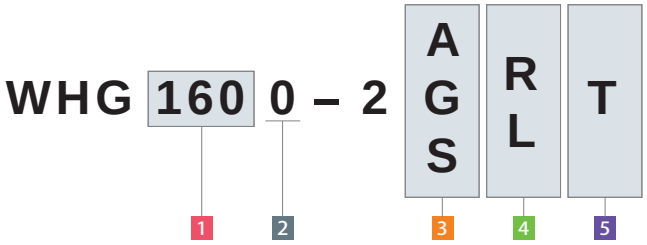
S : Piping Option (Rc Thread)

※The drawing shows the released state of WHG-2SRT.



Model No. Indication

(Format Example：WHG1000-2ART, WHG2500-2SLT)



1 Cylinder Force
2 Design No.
3 Piping Method
4 Swing Direction when Clamping
5 Action Confirmation (When T is chosen)

External Dimensions and Machining Dimensions for Mounting

(mm)

Model No.	WHG1000-2□□T	WHG1600-2□□T	WHG2500-2□□T	WHG4000-2□□T
Full Stroke	14.5	15	17.5	19.5
Swing Stroke (90°)	8.5	9	11.5	13.5
Vertical Stroke	6			
(Break down) Idle Stroke	2			
(Break down) Lock Stroke ※8	4			
Recommended Stroke	11.5	12	14.5	16.5
A	138.5	148	174	192.5
B	60	66	76	87
C	50	56	66	78
D	46	54	64	77
E	99.5	106	124.5	135
F	74.5	81	94.5	105
Fu	64	67	79.5	87.5
G	25	25	30	30
H	35	38	43	48
J	25	28	33	39
K	39	45	53	65
L	79	88	98	113
M	11	11	13	13
Nx	28	31	36	41
Ny	10	13	15	20
P	max. ϕ5	max. ϕ5	max. ϕ5	max. ϕ5
Q	9.5	9.5	11	11
R	5.5	5.5	6.8	6.8
S	14	13.5	16	15
T	16.5	17	19.5	21.5
U	14	16	20	25
V	12	14	17	21
W	10.5	11	13	15
X (Nominal × Pitch)	M12×1.5	M14×1.5	M16×1.5	M22×1.5
Y	5	5	6	8
Z (Chamfer)	R5	R5	R6	R6
AA	19	22	24	32
AB	6.5	7	8	10
AC	21.2	24.5	26.5	35.5
BA	13	15	18	22
BB	16	18	22	28
CA	5	6	8	10
CB	4.5	6.5	5.5	9.5
CC	4	4	4	6
EA (Nominal×Pitch)	M5×0.8	M5×0.8	M6×1	M6×1
UA	35	35	38	40
UB	27	27	30	30
UC	31	31.5	34	36
UD	9.5	9.5	11	11
UE	7	7	7	7
UF	4.3	4.3	4.3	4.3
UG	12.1	12.1	13.6	13.6
UH	3	3	3	3
UJ	20	20	22	22
O-ring (Option A/G)	1BP7	1BP7	1BP7	1BP7
Cylinder Capacity cm³ Lock	21.8	35.5	61.3	103.8
Cylinder Capacity cm³ Release	25.5	40.3	69.2	117.6
Weight ※9 kg	0.9	1.1	1.9	3.0

Notes:

※8. The specification value of cylinder force, clamping force, holding force and swing completion position repeatability is fulfilled only when clamping within the lock stroke range.
(The specification value is not fulfilled when clamping within the range of swing stroke and idle stroke.)

※9. It shows the weight of single swing clamp including taper sleeve and nut.

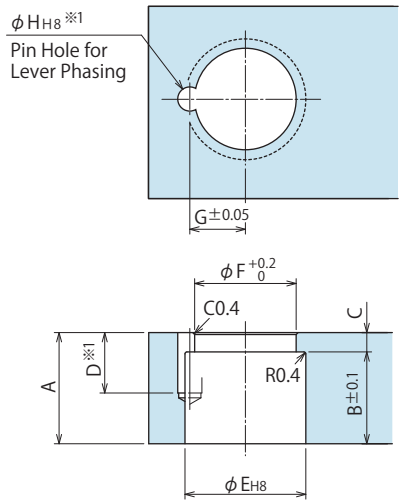
Taper Lock Lever Design Dimensions

※ Reference for designing taper lock swing lever.

Corresponding Model No.

WHG □ 0 - 2 [A / G / S] [L / R] [Blank / T]

1 Cylinder Force



(mm)

Corresponding Model No.	WHG1000-2□□□	WHG1600-2□□□	WHG2500-2□□□	WHG4000-2□□□
A	16	18	22	26
B	13	15	18	22
C	3	3	4	4
D	8.5	10.5	10.5	14.5
E	16 +0.027 0	18 +0.027 0	22 +0.033 0	28 +0.033 0
F	13	15	17	23.5
G	7.1	8.1	10.1	13.1
H	4 +0.018 0	4 +0.018 0	4 +0.018 0	6 +0.018 0
Phasing Pin (Reference)※2	ϕ4(h8)×8	ϕ4(h8)×10	ϕ4(h8)×10	ϕ6(h8)×14

Notes：

1. Swing lever should be designed with its length according to performance curve.
2. If the swing lever is not in accordance with the dimensions shown above, performance may be degraded and damage can occur.

※1. The pin hole (ϕH) for determining the lever phase should be added, if necessary.

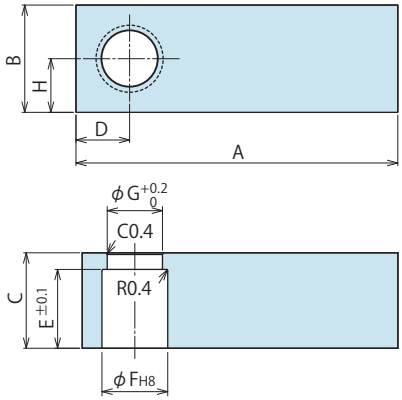
※2. Phasing pin is not included. Prepare it separately.

Accessories：Material Swing Lever for Taper Lock Option

Model No. Indication

WHZ 160 0 – T

- 160: Size (Refer to the table.)
- 0: Design No. (Revision Number)



(mm)

Model No.	WHZ1000-T	WHZ1600-T	WHZ2500-T	WHZ4000-T
Corresponding Model No.	WHG1000-2□□□	WHG1600-2□□□	WHG2500-2□□□	WHG4000-2□□□
A	90	125	150	170
B	25	28	34	45
C	16	18	22	26
D	12.5	14	17	23
E	13	15	18	22
F	$16^{+0.027}_{0}$	$18^{+0.027}_{0}$	$22^{+0.033}_{0}$	$28^{+0.033}_{0}$
G	13	15	17	23.5
H	12.5	14	17	22.5

Notes：

1. Material : S50C
2. If necessary, the front end should be additionally machined.
3. When determining the phase, refer to taper lock lever design dimensions for each model for the additional machining.

Cautions

Notes for Design

1) Check Specifications

- Please use each product according to the specifications.

2) Notes for Circuit Design

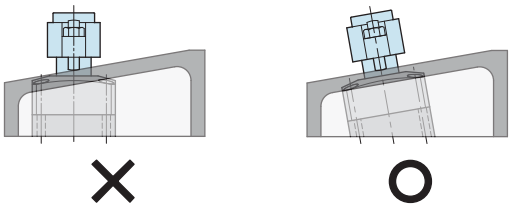
- Ensure there is no possibility of supplying air pressure to the lock port and the release port simultaneously. Improper circuit design may lead to malfunctions and damages.

3) Swing lever should be designed so that the inertia moment is small.

- Large inertia moment will degrade the lever's stopping accuracy and cause undue wear to the clamp.
  Additionally, the clamp may not function, depending on supplied air pressure and lever mounting position.
- Please set the operating time after the inertia moment is calculated. Please make sure that the clamps work within allowable operating time referring to the allowable operating time graph.
- If supplying a large amount of air right after installation, action time will be extremely fast leading to severe damage on a clamp. Install the speed controller (meter-in) near the air source and gradually supply air pressure.

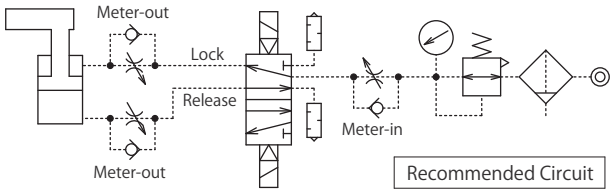
4) When clamping on a sloped surface of the workpiece

- Make sure the clamping surface and the mounting surface of the clamp are parallel.



5) Swing Speed Adjustment

- If the clamp operates too fast the parts will wear out leading to premature damage and ultimately complete equipment failure. Adjust the speed following "Allowable Swing Time Graph".
- Install a speed control valve (meter-out) and gradually control the flow rate from the low-speed side (small flow) to the designated speed. Controlling from the high-speed side (large flow) causes excessive surge pressure or overload to the clamp leading to damage of a machine or device.



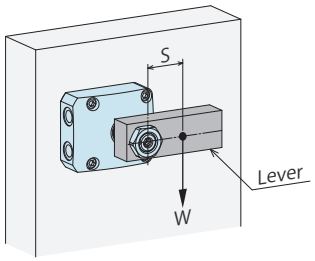
- When operating multiple clamps simultaneously, please install the speed controller (meter-out) to each clamp.

6) For Use of Auto Switch

- Select an auto switch depending on the environment.
- Please use a magnetic field resistant auto switch for an environment which generates a magnetic field disturbance.
  Recommended Auto Switch：D-P3DWA (made by SMC)
- An auto switch may be stuck out of the clamp depending on the installation position and direction.

7) Notes for Lever Design

- Please design the lever as light as possible, and it should be no larger than necessary.
  The clamp may not function depending on supplying air pressure, mounting position and shape of the lever. If using a large lever with the mounting position shown below, it may stop in the middle of swing action. Please use a lever with (Lever Weight W) × (Gravity Center S) lighter than shown in the following table.

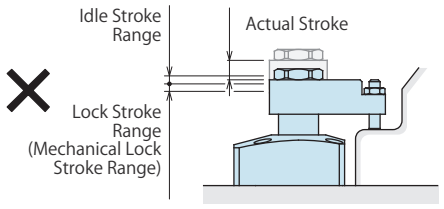


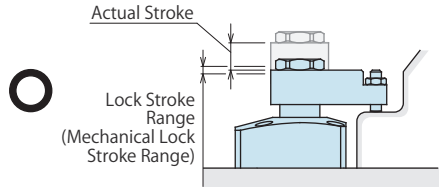
Model No.	(Lever Length W) × (Center of Gravity S) (N·m)
WHG1000	0.10
WHG1600	0.20
WHG2500	0.45
WHG4000	0.90

8) The specification value is not fulfilled when clamping out of the lock stroke range.

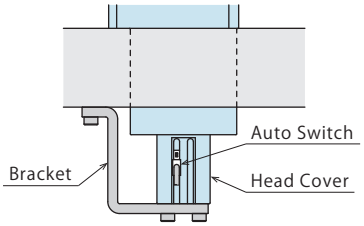
- The mechanical lock function will not work when clamping within the range of swing stroke and idle stroke, and the specification value of cylinder force, clamping force, holding force and swing completion position repeatability will not be fulfilled.

The actual stroke of the piston that descends from the release-end to lock-end should be designed to have the same value as the recommended stroke listed in the external dimensions.





9) Adjust the direction of the head cover as you need.
Use M3 tapped holes on the bottom to fix the head cover with bracket.



Installation Notes

1) Check the fluid to use.

- Please supply filtered clean dry air. (Install a drain removing device.)
- Oil supply with a lubricator etc. is unnecessary. Oil supply with a lubricator may cause loss of the initial lubricant. The operation under low pressure and low speed may be unstable. (When using secondary lubricant, please supply lubricant continuously. Otherwise, the initial grease applied from KOSMEK will be removed from the secondary lubricant.)

2) Preparation for Piping

- The pipeline, piping connector and fixture circuits should be cleaned and flushed thoroughly.
  The dust and cutting chips in the circuit may lead to fluid leakage and malfunction.
- There is no filter provided with this product for prevention of contaminants in the air circuit.

3) Applying Sealing Tape

- Wrap with tape 1 to 2 times following the screw direction.
  Wrapping in the wrong direction will cause leakage and malfunction.
- Pieces of the sealing tape can lead to air leakage and malfunction.
- When piping, be careful that contaminant such as sealing tape does not enter in products.

4) Installation of the Product

- When mounting the product use four hexagonal socket bolts (with tensile strength of 12.9) and tighten them with the torque shown in the table below. Tightening with greater torque than recommended can depress the seating surface or break the bolt.

Model	Thread Size	Tightening Torque (N·m)
WHG1000	M5×0.8	6.3
WHG1600	M5×0.8	6.3
WHG2500	M6×1	10
WHG4000	M6×1	10

5) Installation of the Flow Control Valve

- Tightening torque for installing flow control valve is 5 to 7 N・m.

6) Installation / Removal of the Swing Lever

- Oil or debris on the mating surfaces of the lever, taper sleeve or piston rod can cause the lever to loosen.
  Please clean them thoroughly before installation.
- Tightening torque for the swing lever is shown below.

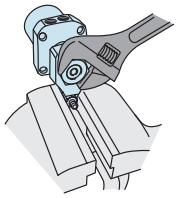
Standard：Taper Lock Lever Option

Model	Thread Size	Tightening Torque (N·m)
WHG1000	M12×1.5	17 ~ 20
WHG1600	M14×1.5	21 ~ 25
WHG2500	M16×1.5	33 ~ 40
WHG4000	M22×1.5	84 ~ 100

- If the piston rod is subjected to excessive torque or shock, the rod or the internal mechanism may be damaged.
  Observe the following points to prevent such shock.

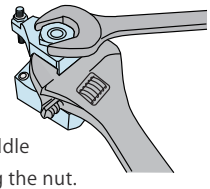
Installation Procedure

① With a clamp positioned to a jig, determine the lever position, and tighten the nut for fixing the lever (temporal tightening).



② Remove the clamp from the jig, fix the lever with a machine vise etc., and tighten the nut.

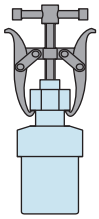
③ If tightening the nut with the clamp positioned to the jig, use a wrench to the hexagon part of piston rod, or fix the lever with a spanner.
It is best to bring the lever to the middle of the swing stroke before tightening the nut.



Removal Procedure

① While the clamp is on the jig or vise, use a hex wrench to bring the lever to the middle of the swing stroke and then loosen the nut.

② Loosen the nut after securing the lever two or three turns then remove the lever with a puller without any rotational torque applied on the piston rod.



7) Swing Speed Adjustment

- Adjust the speed following "Allowable Swing Time Graph".
  If the clamp operates too fast the parts will wear out leading to premature damage and ultimately complete equipment failure.
- Turn the speed control valve gradually from the low-speed side (small flow) to the high-speed side (large flow) to adjust the speed.

8) Checking Looseness and Retightening

- At the beginning of the machine installation, the bolt and nut may be tightened lightly. Check the looseness and re-tighten as required.

※ Please refer to P.83 for general cautions. ・Notes on Handling ・Maintenance/Inspection ・Warranty

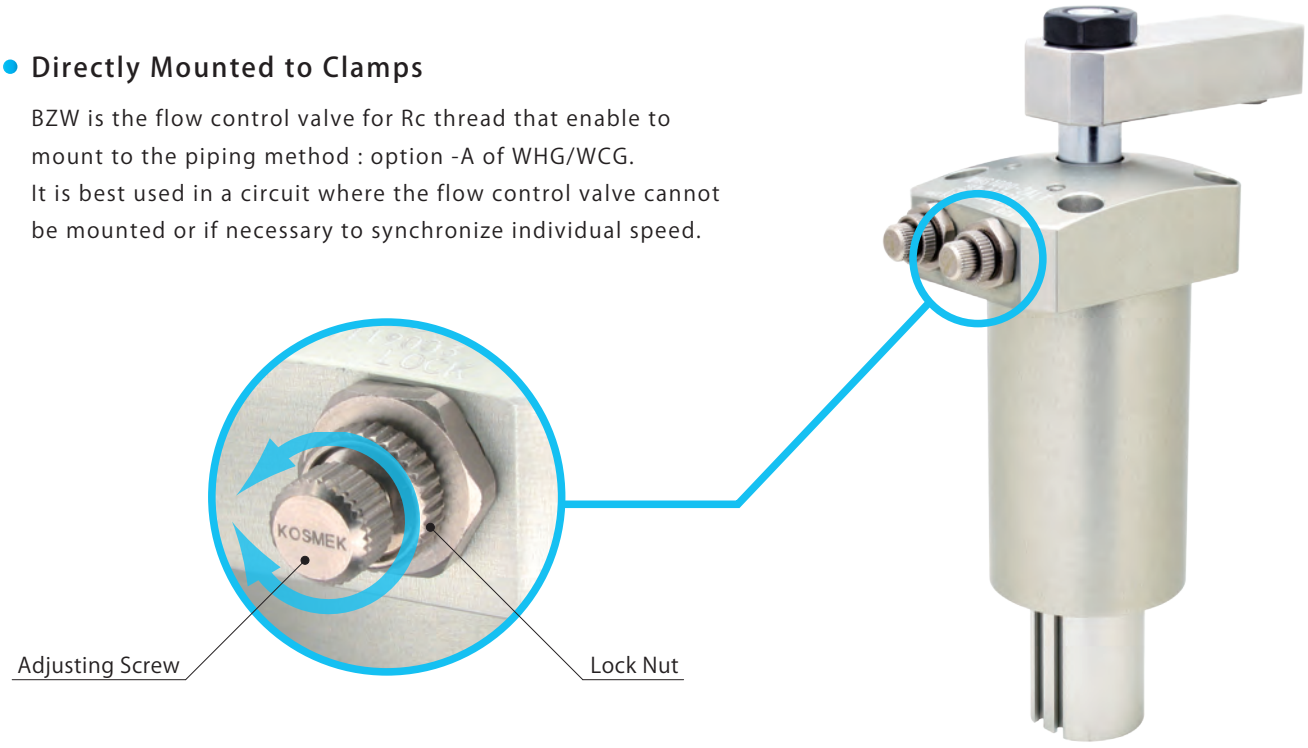
Air Flow Control Valve

Model **BZW**

Directly mounted to clamps, easy adjusting

● Directly Mounted to Clamps

BZW is the flow control valve for Rc thread that enable to mount to the piping method : option -A of WHG/WCG.
It is best used in a circuit where the flow control valve cannot be mounted or if necessary to synchronize individual speed.



Corresponding Product Model

Clamp	BZW Model No.	Clamp Model No.
High-Power Welding Link Clamp	BZW0100-**A**	WCG□0-2**A**□
High-Power Welding Swing Clamp	BZW0100-**B**	WHG□0-2**A**□

Corresponding to piping method -A option.

※ When mounting BZW to piping method G, take off R thread plug and remove the seal tape not to get inside cylinder.

Model No. Indication

BZW 010 0 – B

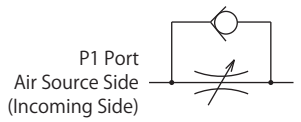
- **B**: Control Method — **B** : Meter-out, **A** : Meter-in
- **0**: Design No. — **0** : Revision Number
- **010**: R Thread Size — **010** : Rc1/8

Specifications

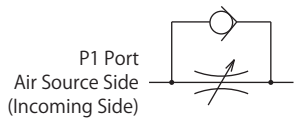
Model No.	BZW0100-B	BZW0100-A
Control Method	Meter-out	Meter-in
Operating Pressure MPa	0.1 ~ 1.0	
Withstanding Pressure MPa	1.5	
Adjust Screw Number of Rotations	10 Rotations	
Tightening Torque N•m	5 ~ 7	
Weight g	13	
Corresponding Model No.	WHG□-2A□	WCG□-2A□

Circuit Symbol

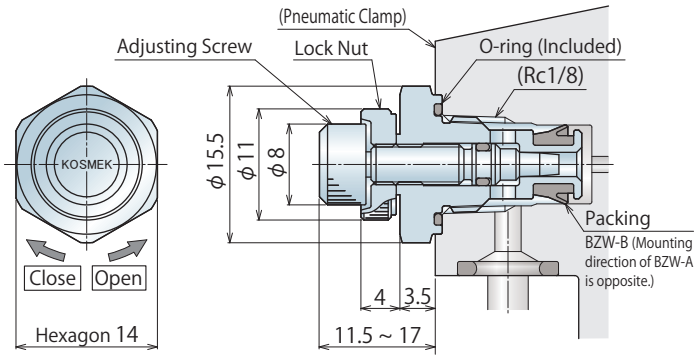
BZW0100-B : Meter-out



BZW0100-A : Meter-in

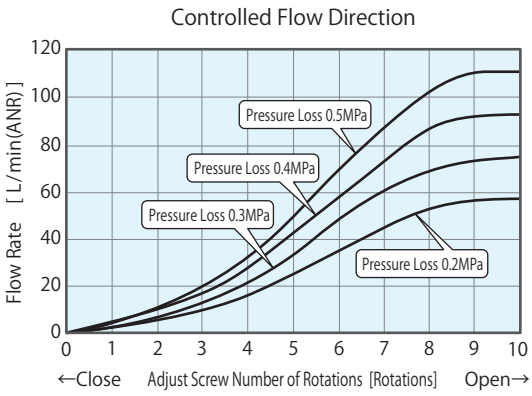


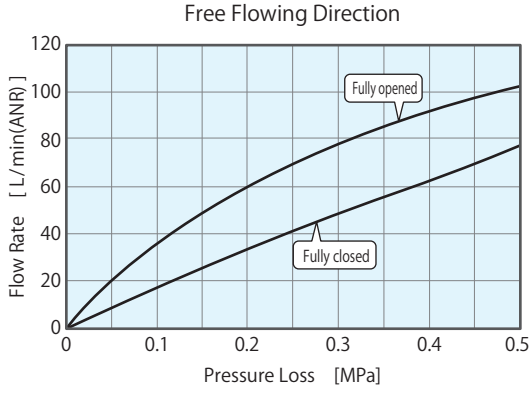
External Dimensions



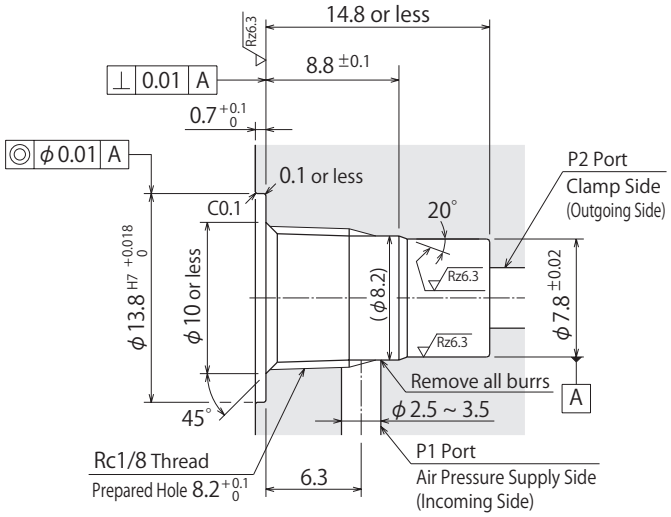
Flow Rate Graph

BZW0100-B/BZW0100-A common





Machining Dimensions of Mounting Area



Notes :

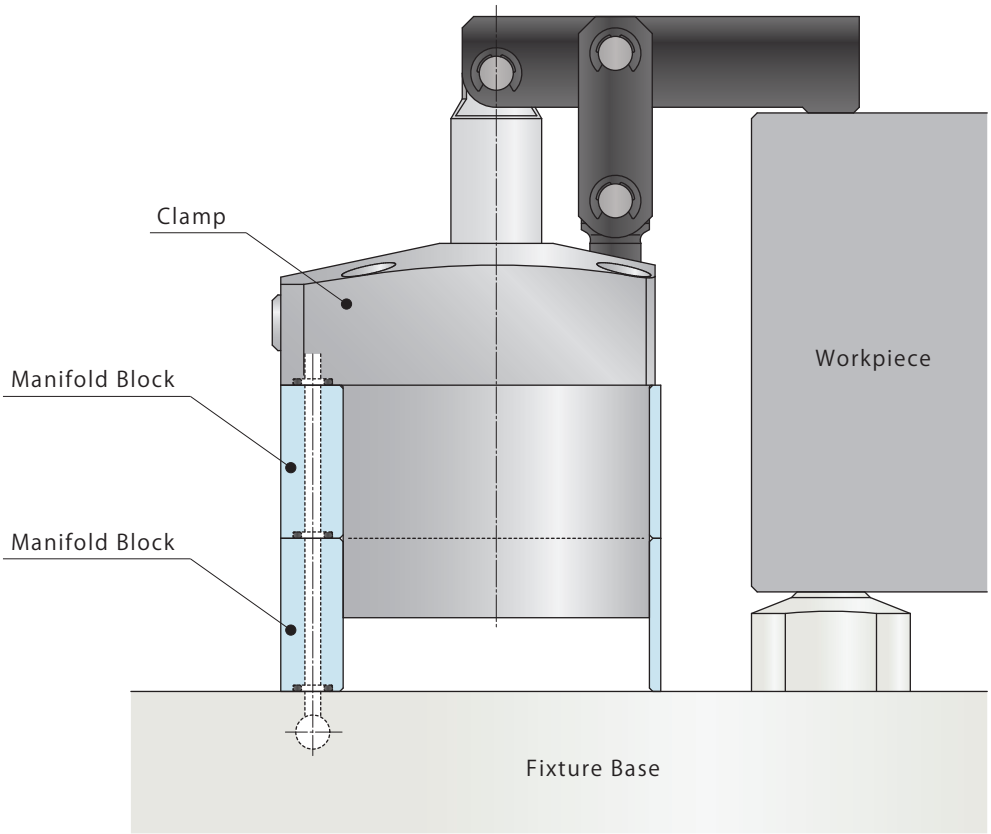
1. Since the $\sqrt{Rz6.3}$ area is sealing part, be careful not to damage it.
2. No cutting chips or burr should be at the tolerance part of machining hole.
3. As shown in the drawing, P1 port is used as the air supply side and P2 port as the clamp side.

Manifold Block

Model **WHZ-MD**

Manifold Block

The mounting height of clamp is adjustable with the manifold block.



Applicable Model

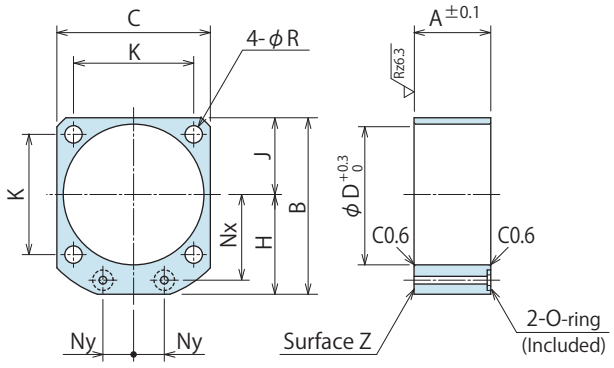
Manifold Block Model No.	Corresponding Item Model No.
Model WHZ-MD	Model WCG Model WHG

Manifold Block for WCG/WHG

Model No. Indication

WHZ 048 0 – MD

- 048: Size (Refer to following table)
- 0: Design No. (Revision Number)



(mm)

Model No.	WHZ0320-MD	WHZ0400-MD	WHZ0500-MD	WHZ0630-MD
Corresponding Item Model Number	WCG1000 WHG1000	WCG1600 WHG1600	WCG2500 WHG2500	WCG4000 WHG4000
A	25	27	31	35
B	60	67	77	88.5
C	50	58	68	81
D	46	54	64	77
H	35	38	43	48
J	25	29	34	40.5
K	39	45	53	65
Nx	28	31	36	41
Ny	10	13	15	20
R	5.5	5.5	6.5	6.5
O-ring	1BP7	1BP7	1BP7	1BP7
Weight kg	0.1	0.1	0.2	0.2

Notes : 1. Material : A2017BE-T4
2. Mounting bolts are not provided. Prepare mounting bolts according to the mounting height using the dimension A as a reference.
3. If thickness other than A is required, perform additional machining on surface Z. Please refer to the drawing.

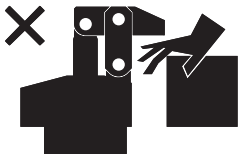
Cautions

Notes on Handling

1) It should be operated by qualified personnel.
- Hydraulic and/or pneumatic machines and devices should be operated and maintained by qualified personnel.

2) Do not operate or remove the product unless the safety protocols are ensured.
① The machine and equipment can only be inspected or prepared when it is confirmed that the safety devices are in place.
② Before removing the product, make sure that the above-mentioned safety devices are in place. Shut off the pressure and power source, and make sure no pressure exists in the air circuits.
③ After stopping the product, do not remove until the temperature drops.
④ Make sure there is no trouble/issue in the bolts and respective parts before restarting the machine or equipment.

3) Do not touch the clamp (cylinder) while it is working.
Otherwise, your hands may be injured.

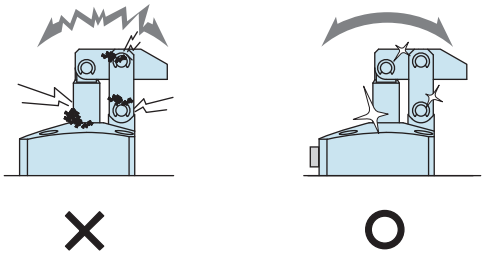


4) Do not disassemble or modify.
- If the product is taken apart or modified, the warranty will be voided even within the warranty period.

Maintenance and Inspection

1) Removal of the Product and Shut-off of Pressure Source
- Before removing the product, make sure that safety devices and preventive devices are in place. Shut off the pressure and power source, and make sure no pressure exists in the air and hydraulic circuits.
- Make sure there is no abnormality in the bolts and respective parts before restarting.

2) Regularly clean the area around the piston rod.
- If it is used when the surface is contaminated with dirt, it may lead to packing seal damage, malfunctioning and fluid leakage.



3) Regularly tighten pipes, mounting bolts, nuts, snap rings, cylinders and others to ensure proper use.

4) Make sure there is a smooth action without an irregular noise.
- Especially when it is restarted after left unused for a long period, make sure it can be operated correctly.

5) The products should be stored in the cool and dark place without direct sunshine or moisture.

6) Please contact us for overhaul and repair.

Warranty

1) Warranty Period

- The product warranty period is 18 months from shipment from our factory or 12 months from initial use, whichever is earlier.

2) Warranty Scope

- If the product is damaged or malfunctions during the warranty period due to faulty design, materials or workmanship, we will replace or repair the defective part at our expense.
  Defects or failures caused by the following are not covered.

① If the stipulated maintenance and inspection are not carried out.
② Failure caused by the use of the non-confirming state at the user's discretion.
③ If it is used or handled in inappropriate way by the operator.
(Including damage caused by the misconduct of the third party.)
④ If the defect is caused by reasons other than our responsibility.
⑤ If repair or modifications are carried out by anyone other than Kosmek, or without our approval and confirmation, it will void warranty.
⑥ Other caused by natural disasters or calamities not attributable to our company.
⑦ Parts or replacement expenses due to parts consumption and deterioration.
(Such as rubber, plastic, seal material and some electric components.)

Damages excluding from direct result of a product defect shall be excluded from the warranty.

Company Profile

KOSMEK LTD. Head Office

Company Name	KOSMEK LTD.
Established	May 1986
Capital	¥99,000,000
President & CEO	Koji Kimura
Employee Count	270
Group Company	KOSMEK LTD.　KOSMEK ENGINEERING LTD. KOSMEK (USA) LTD.　KOSMEK EUROPE GmbH KOSMEK (CHINA) LTD.　KOSMEK LTD. - INDIA
Business Fields	Design, production and sales of precision products, and hydraulic and pneumatic equipment
Customers	Manufacturers of automobiles, industrial machinery, semiconductors and electric appliances
Banks	Resona bank, Tokyo-Mitsubishi bank

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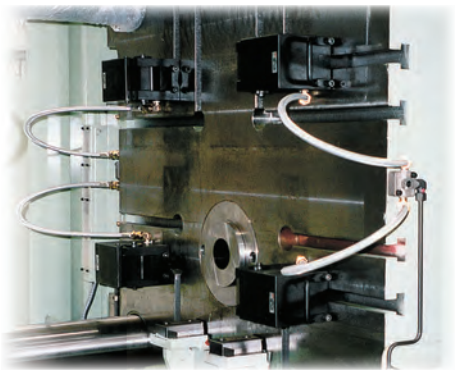
■ Quick Die Change Systems

FOR PRESS MACHINES

■ Kosmek Factory Automation Systems

FACTORY AUTOMATION INDUSTRIAL ROBOT RELATED PRODUCTS

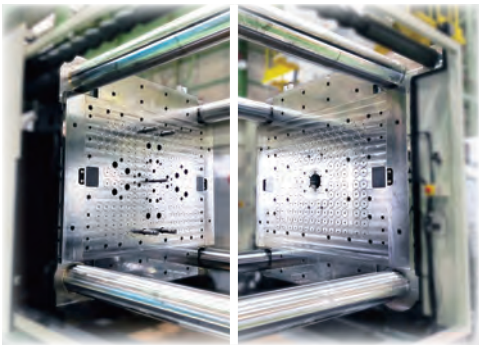


■ Diecast Clamping Systems

FOR DIECAST MACHINES

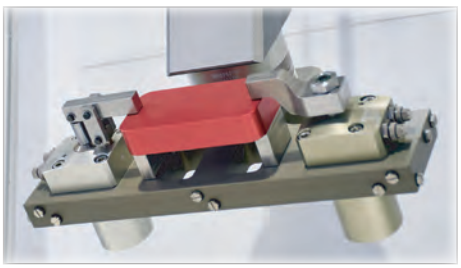
■ Kosmek Work Clamping Systems

MACHINE TOOL RELATED PRODUCTS



■ Quick Mold Change Systems

FOR INJECTION MOLDING MACHINES



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■ For Further Information on Unlisted Specifications and Sizes, Please call us.
■ Specifications in this Leaflet are Subject to Change without Notice.

ISO 9001
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CM009

CAT.NO. SWP001-06-G1B
Printed in Japan

2017/12 First 1Ry
2024/09 6th 0Ry