New Hole Gripper





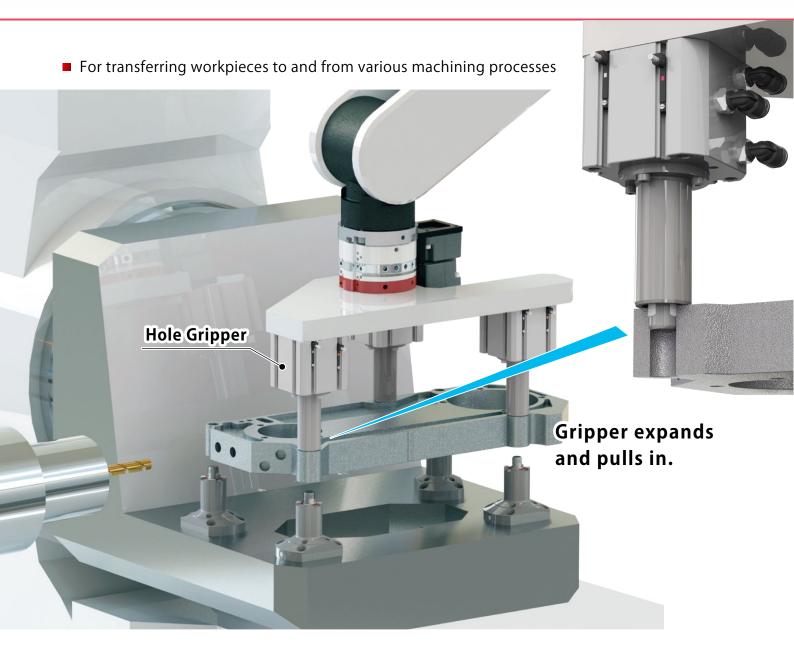
Hole Gripper

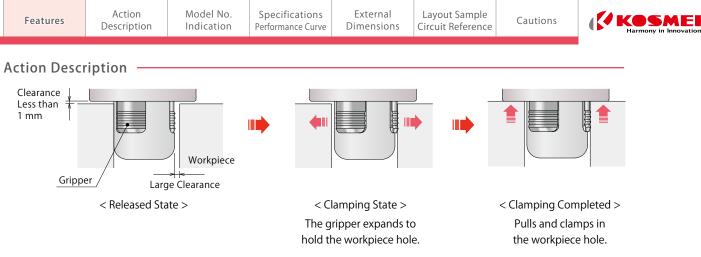
Model WKK



Transferring Workpieces with I.D. Gripping

Hole Gripper allows for 5 face accessibility. Light Weight, Compact and Mechanical Lock

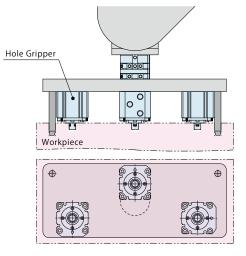




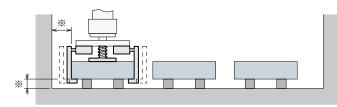
Advantages

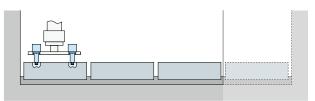
Space Saving for Transfer Hand Stocker

- Less interference compared to a hand that holds an outer surface of a workpiece:
 (1) Teaching will be easier.
 - (2) Transfer hands can be compact.
- Removing exterior tooling clearance enables space saving for workpiece stockers.



Workpiece holding stroke is short to allow for quicker gripping cycles.
 Eliminating interference enables robots to operate in a smaller footprint, leading to overall reduction in transfer time.



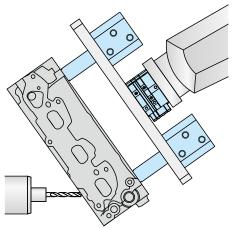


* Operating range of the transfer hand Traditional Exterior Transfer Stocking Method

Kosmek Hole Gripper Stocking Method

Using Transfer Hand as Fixture

 Hole gripper needs one face to hold the workpiece so 5 faces are accessible with no tooling interference. A robot can hold a workpiece and continue to the next processes by using a transfer hand as a fixture. Other processes can include deburring, washing and etc.

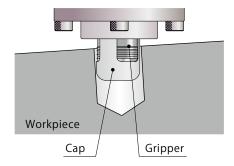


Features

Protective Cap for Stable Automation



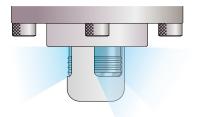
Minimal clearance between the cap and the gripper prevents cutting chips from entering inside the hole gripper.



 The cap prevents the gripper from frictional wear when inserted to a workpiece hole.
 Loading and unloading becomes smoother with the cap preventing the

gripper from touching the workpiece.

• Air Blow Function Ensures Longevity Even in Machining Environments



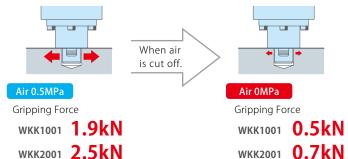
- Even with a little air flow, by air purging from the inside, it prevents coolant from entering inside the hole gripper.
- Action Confirmation Available



- Lock and release actions can be confirmed by an auto switch (sold separately).
 - % An auto switch is not included in WKK. Prepare it by referring to P.6.

Secured with Self-Locking Function

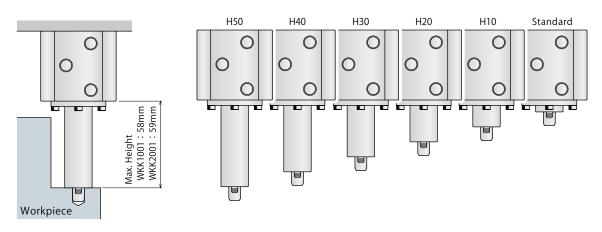
A built-in spring is provided in the lock side. This prevents a workpiece from falling even when air supply is lost due to blackout or cutoff of air hose.



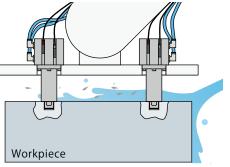
- Wide Range of Hole Diameters to Suit a Variety of Workpieces
- In order to suit different hole diameters and tolerances, hole diameters can be specified in 0.5mm increments.

| | Ma Jal Na | Workpiece Hole Diameter (mm) | | | | | | | | |
|----------------------------------|-------------|----------------------------------|------------------------------------|--|--|--|--|--|--|--|
| | Model No. | 6 6.5 7 7.5 8 8.5 9 | 9.5 10 10.5 11 11.5 12 12.5 13 | | | | | | | |
| | WKK1001 | Selectable Range | | | | | | | | |
| | WKK2001 | | Selectable Range | | | | | | | |
| Vorkpiece Hole Diameter ϕ d | Workpiece I | nole diameter ϕ 6 cannot be | selected for a tapered workpiece h | | | | | | | |

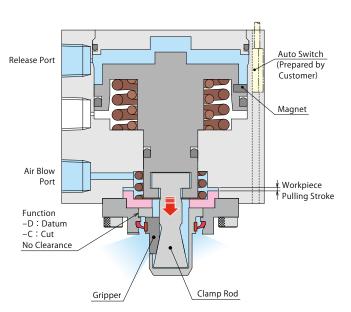
- Wide Range of Seating Surface Heights
- Level the height in 10mm increments according to the workpiece seating surface.
 This is effective to prevent interferences with workpieces.

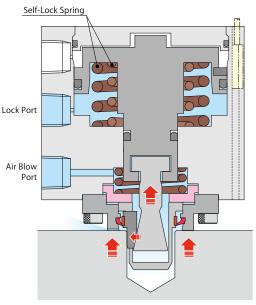


Machining process and washing process can be used with the Hole Gripper. The available seating height options allows auto switches and air piping to be protected from coolant and cutting fluid by installing the back plate and adjusting the seating height accordingly.



• Action Description * This is a simplified drawing. The actual part components may be different.



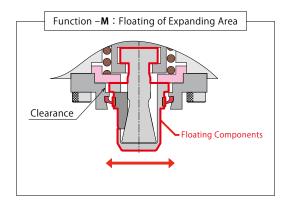


Release Action Description

- 1 Air is supplied to the release port.
- ② The clamp rod is moved forward by the air pressure, and the gripper will be retracted.

↓

※ Continuously supply air to the air blow port in order to prevent contamination.



Lock Action Description

① Release air to the release port and supply air to the lock port.

↓

 The self-locking spring force and air pressure powerfully pulls in the clamp rod. The gripper will be expanded.

 \downarrow

 ③ After the gripper holds a workpiece, the pulling force pulls in the workpiece onto the seating surface. (Clamping Force = Pulling Force toward Seating Surface)

| Features | Action Description | Model No. Indication | Specifications Performance Curve | External Dimensions | Layout Sample Circuit Reference | Cautions | |
|-------------|-----------------------|-------------------------|-------------------------------------|------------------------|------------------------------------|----------|--|
| C Auto Swit | | g position can b | e detected by ar | auto switch (pr | epared by custor | ner). | |



Note :

1. Depending on difference of workpiece hole diameter, the detection range of an auto switch can be insufficient. If using an auto switch (JEP), workpiece hole diameter difference should be within ± 0.3 mm.

| [Applicable Auto Switch / High-Accuracy Sensor for Air Cylinder] |
|--|
|--|

| Switch Type | Model No. | Output Method | Wiring Method | Cable Length | Shape | Protection Grade |
|---|----------------|--|------------------|-----------------|----------------|---------------------|
| | JEP0000-B2 | | | 1m | Straight | |
| | JEP0000-B2L | | 2.14/ | 3m | A ROULE = 2018 | |
| Auto Curitali | JEP0000-B3C | Non-Contact : NPN Output | 3-Wire | 1m | L Shaped | |
| Auto Switch | JEP0000-B3CL | | | 3m | A Starting | IP67 |
| | JEP0000-B3B | Non Contact | 2-Wire | 1m | L Shaped | |
| | JEP0000-B3BL | Non-Contact | 2-wire | 3m | attended a | |
| | JES0000-02GN | Non-Contact : NPN Output N-Pole Sensor ^{**} 2 | | | Straight | |
| | JES0000-02GS | Non-Contact : NPN Output S-Pole Sensor ^{**} 2 | | | | |
| | JES0000-02GPN | Non-Contact : PNP Output N-Pole Sensor ^{**} 2 | | | at the second | |
| High-Accuracy | JES0000-02GPS | Non-Contact : PNP Output S-Pole Sensor ^{*2} | 2 \\//inc | 1 | | 1067 |
| Sensor for Air Cylinder ^{**1} | JES0000-02LGN | Non-Contact : NPN Output N-Pole Sensor ^{**} 2 | 3-Wire | 1m | L Shaped | IP67 |
| Air Cylinder | JES0000-02LGS | Non-Contact : NPN Output S-Pole Sensor ^{**} 2 | | | | |
| | JES0000-02LGPN | Non-Contact : PNP Output N-Pole Sensor ^{**} 2 | | | | |
| | JES0000-02LGPS | Non-Contact : PNP Output S-Pole Sensor ^{**} 2 | | | | |

Notes :

- 2. Auto Switch / High-Accuracy Sensor for Air Cylinder may be stuck out of the hole gripper depending on the installation position and direction.
- %1. The detection range of High-Accuracy Sensor for Air Cylinder (JES) is different from Auto Switch (JEP), and even small stroke can be securely detected by JES. Refer to "Performance Curve" on the JES catalog for further information.
- *2. When detecting both lock and release actions with High-Accuracy Sensor for Air Cylinder (JES), both N-pole sensor and S-pole sensor are required.

^{1.} For further information, refer to the product catalogs of Auto Switch (JEP) and High-Accuracy Sensor for Air Cylinder (JES) on our website. When using an auto switch not made by Kosmek, check specifications of each manufacturer.

Model No. Indication (Workpiece Hole Shape : Straight)



1 Body Size

- **1** : Select from workpiece hole diameters between $\phi 6$ and $\phi 9$
- **2** : Select from workpiece hole diameters between ϕ 9 and ϕ 13

2 Design No.

0 : Revision Number

3 Workpiece Hole Diameter (Workpiece Hole Code)

| Workpiece Hole Code : Workpiece Hole Diameter $\phi d^{+0.7}_{-0.3}$ | | | | | | | | | | | | | | | | |
|--|--------|-------|------|-------|--------|-------|-------|-------|--------|-------|--------|-------|-----|------|-----|-----------|
| Workpiece Hole Code | 060 | 065 | 070 | 075 | 080 | 085 | 090 | 095 | 100 | 105 | 110 | 115 | 120 | 125 | 130 | |
| Hole Diameter $\phi d_{-0.3}^{+0.7}$ (mm) | 6 | 6.5 | 7 | 7.5 | 8 | 8.5 | 9 | 9.5 | 10 | 10.5 | 11 | 11.5 | 12 | 12.5 | 13 | \square |
| WKK1001 | | | Al | lowab | le Ran | ige | | | | | | | | | | |
| WKK2001 | | | | | | | | | | Allov | vable | Range | | | | 6 |
| $\%$ Indicate the workpiece hole diameter ϕ d within the allowable range in 0.5mm increments. | | | | | | | | | | | | | | | | |
| ※ For the hole diameter | ers ma | arked | with | ▲, th | e max | kimur | n ope | ratin | g pres | ssure | is 0.5 | MPa. | | | | < |

% When using with Auto Switch (JEP), workpiece hole diameter variance should be within \pm 0.3mm.

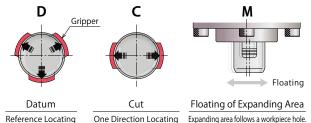


4 Functions

- D : Datum (For Reference Locating)
- С : Cut (For One Direction Locating)
- : Floating of Expanding Area (No Locating Function) Μ

% When using it with expansion locating pin (model VWH, VWM, VWK, VRA, VRC, VX, etc.) please select Function M.

| Workpiece Hole Code | 060 ~ 085 | 090 ~ 130 | | | | |
|---------------------|-------------------------------|-------------------------------|--|--|--|--|
| Function D | Not Available | Available Gripper Qty. : 3 | | | | |
| Function C | Available Gripper Qty. : 2 | Available Gripper Qty.: 2 | | | | |
| Function M | Available Gripper Qty.: 2 | Available Gripper Qty.: 3 | | | | |



One Direction Locating Expanding area follows a workpiece hole.

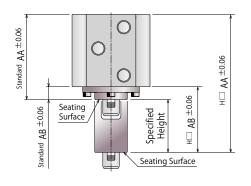
% When roughly locating a workpiece with workpiece hole code 060 ~ 085, refer to "Hole Gripper Installation" on P.25.

| Features | Action Description | Model No. Indication | Specifications Performance Curve | External Dimensions | Layout Sample Circuit Reference | Cautions | |
|----------|-----------------------|-------------------------|-------------------------------------|------------------------|------------------------------------|----------|--|
| | | | | | | | |

5 Seating Height Dimension

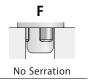
| Blank | :Standard Height |
|------------------|---|
| H Seating Height | : Specified Seating Height (In 10mm increments) |
| | (mm) |

| MadalNia | Cumber | Standard | | Specified | | | | | | | | | |
|-----------|--------|----------|-----|-----------|-----|-----|-----|--|--|--|--|--|--|
| Model No. | Symbol | Blank | H10 | H20 | H30 | H40 | H50 | | | | | | |
| WKK1001 | AA | 55 | 65 | 75 | 85 | 95 | 105 | | | | | | |
| WKKIUUI | AB | 8 | 18 | 28 | 38 | 48 | 58 | | | | | | |
| WKK2001 | AA | 60 | 70 | 80 | 90 | 100 | 110 | | | | | | |
| WKK2001 | AB | 9 | 19 | 29 | 39 | 49 | 59 | | | | | | |



6 Shape of Gripper (Workpiece Hole)

- **F** : No Serration (Workpiece Hole Shape : Straight)
- **S** : With Serration (Workpiece Hole Shape : Straight)





With Serration Digs into and powerfully clamps a workpiece.



Refer to P.9 ~ P.10 for the taper workpiece hole.

% Contact us when ordering the taper hole model.

7 Shape of Cap End



Κ

Model No. Indication (Workpiece Hole Shape : Tapered)



1 Body Size

- **1** : Select from workpiece hole diameters between ϕ 6.5 and ϕ 9
- 2 : Select from workpiece hole diameters between ϕ 9 and ϕ 13

2 Design No.

0 : Revision Number

3 Workpiece Hole Diameter (Workpiece Hole Code)

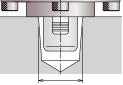
Workpiece Hole Code : Workpiece Hole Mouth Diameter ϕ d

- % Workpiece hole mouth diameter ϕ d should be specified in 0.5mm increments from the allowable range in the following table.
- % The allowable tolerance of the hole mouth diameter ϕ d differs

| | de | epend | ling o | n the | slop | e ang | ile. Re | efer to | o the | table | belov | Ν. | | | | |
|--|-----|-------|--------|-------|-------|-------|---------|---------|-------|-------|--------|-------|-----|------|-----|----------------------|
| Workpiece Hole Code | 060 | 065 | 070 | 075 | 080 | 085 | 090 | 095 | 100 | 105 | 110 | 115 | 120 | 125 | 130 | |
| Hole Mouth Diam. ϕd (mm) | - | 6.5 | 7 | 7.5 | 8 | 8.5 | 9 | 9.5 | 10 | 10.5 | 11 | 11.5 | 12 | 12.5 | 13 | ⊢ Hole Mouth Diar |
| WKK1001 | | | | Allo | wable | Rang | e | | | | | | | | | |
| WKK2001 | | | | | | | | | | Allow | able f | Range | - | | | |
| $\%$ For the hole diameters marked with \blacktriangle , the maximum operating pressure is 0.5MPa. | | | | | | | | | | | | | | | | |

※ For the hole di * The workpiece hole diameter : **060** cannot be selected for the taper workpiece hole model.

% When using with Auto Switch (JEP), workpiece hole diameter variance should be within \pm 0.3mm.



meter ød

Workpiece Hole Slope Angle and Allowable Tolerance of Hole Mouth Diameter

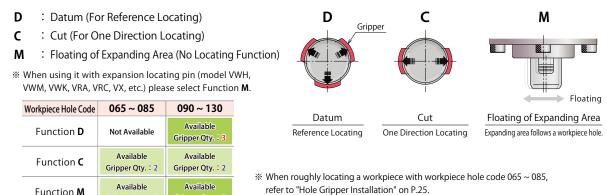
| Slope Angle θ | C0.5 or less |
|----------------------|--------------|
| | |
| Hole Mouth Diamet | er ød |

| Model No. | Workpiece Hole Code | Slope Angle θ | Allowable Tolerance of Hole Mouth Diam. |
|-----------|---------------------|----------------------------------|---|
| Model No. | workpiece Hole Code | 1 5 | |
| WKK1001 | 065 ~ 085 | $1 \leq \theta^{\circ} \leq 2.5$ | ϕ d \pm 0.3 |
| | 005 ~ 005 | $2.5 < \theta ^{\circ} \leq 3$ | ϕ d $^{+0.3}_{-0.15}$ |
| | | $1 \leq \theta^{\circ} \leq 2$ | ϕ d $^{\pm 0.3}$ |
| | 090 | $2 < \theta \circ \leq 2.5$ | $\phi d^{+0.3}_{-0.15}$ |
| | | $2.5 < \theta \circ \leq 3$ | $\phi d {}^{+0.3}_{0}$ |
| | | $1 \leq \theta^{\circ} \leq 2$ | ϕ d $^{\pm 0.3}$ |
| | 090 | $2 < \theta \circ \leq 2.5$ | $\phi d^{+0.3}_{-0.15}$ |
| WKK2001 | | $2.5 < \theta \circ \leq 3$ | $\phi d {}^{+0.3}_{0}$ |
| | 005 120 | $1 \leq \theta^{\circ} \leq 2.5$ | ϕ d \pm 0.3 |
| | 095 ~ 130 | $2.5 < \theta \circ \leq 3$ | φd ^{+0.3} _{-0.15} |

% Please contact us when the slope angle is less than 1°.

| Features | Action Description | Model No. Indication | Specifications Performance Curve | External Dimensions | Layout Sample Circuit Reference | Cautions | |
|----------|-----------------------|-------------------------|-------------------------------------|------------------------|------------------------------------|----------|---|
| | | | | | | | 1 |

4 Functions



5 Seating Height Dimension

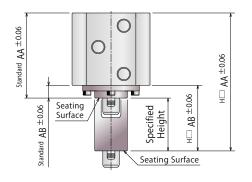
Function **M**

| Model No. Symbol Standard Specified Specified Blank H10 H20 H30 H40 H50 | | | | | | | |
|---|--|--|--|--|--|--|--|

Gripper Qty. 3

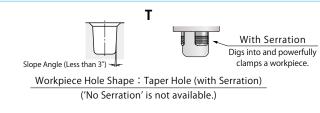
| | | Blank | HIO | H20 | H30 | H40 | H50 |
|---------|----|-------|-----|-----|-----|-----|-----|
| WKK1001 | AA | 55 | 65 | 75 | 85 | 95 | 105 |
| WKKTUUT | AB | 8 | 18 | 28 | 38 | 48 | 58 |
| WKK2001 | AA | 60 | 70 | 80 | 90 | 100 | 110 |
| WKKZUUT | AB | 9 | 19 | 29 | 39 | 49 | 59 |

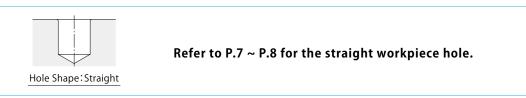
Gripper Qty.: 2



6 Shape of Workpiece Hole (Gripper)

Т : Taper Hole (with Serration)





7 Shape of Cap End

Blank : Standard (Low Head Model)

(**B** : Cone Point Model)



:K

Specifications (Workpiece Hole Shape : Straight)

Applicable Model No.

| WKK1001F | | | | | | | | | | | | | | | |
|----------------------------|-----------------------------------|----------------------|---------|---------|------|--------|-------|-------|---------|--------------|------------------------|------------|-------|--------|----|
| Model No. | | | - | | | _ | | | | | WKK2001- WKK2001- | | | _ | |
| Model No. | ole Code | | | | | | | 090 | | 100 105 1 | | - <u>T</u> | | 130 | |
|) (/ | Hole Diam. ϕ d $\frac{1}{2}$ | | | 6.5 | 7 | 7.5 | 8 | 8.5 | 9 | 9.5 | 10 10.5 | 11 11 | .5 12 | 2 12.5 | 13 |
| Workpiece | Hardness | | | | | | HB | 250 | or les | s (In ca | se of <mark>6</mark> S | 5) | | | |
| Locating Repe | mm | | | | C |).03 (| Whe | n con | nbinin | g 🛿 🗛 and | d C) | | | | |
| Allowable Offset (Floating | g Clearance of Expanding Are | a) ^{**2} mm | = | ±0.3 | (In | case | of | 1 M) | | | ±0.5 (In ca | ase of | f 4 | N) | |
| Workpiece Pu | lling Stroke | mm | 1.0 | | | | | | | | | | | | |
| Cylinder Capacity | Release | cm ³ | 5.3 6.7 | | | | | | | | | | | | |
| (Empty Action) | Lock | cm ³ | | 4.6 5.8 | | | | | | | | | | | |
| Max. Operatin | ig Pressure | MPa | 0. | 0.5 0.7 | | | | | | | | | | | |
| Min. Releasing | g Pressure | MPa | | | | | | | | 0.25 | | | | | |
| Withstanding | Pressure | MPa | 0.7 | 75 | | | | | | 1 | .0 | | | | |
| Recommended | e MPa | | | | | | | 0. | 2 ~ 0.3 | 6 | | | | | |
| Air Blow Flow R | L/min | | | | | | | 15 | or moi | re | | | | | |
| Operating Ter | °C | | 0~70 | | | | | | | | | | | | |
| Usable Fluid | | Dry Air | | | | | | | | | | | | | |
| Weight | | | Re | efer t | o th | e ext | ernal | dime | ensions | s for the pr | oduct | weig | ght. | | |

Notes :

1. Locating repeatability under the same condition (no load).

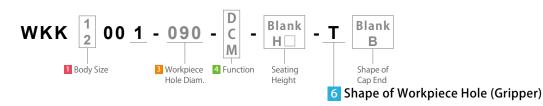
%2. The expanding part of option M is an adjusting structure and the clamping operation is done by locating a workpiece hole. The value in the table shows the amount of tolerance value of single hole gripper. Please consider the distance accuracy of each cylinder mounting hole and each workpiece machining hole when using with another location clamp / location cylinder, or when using more than two of these products.

| | Features | Action Description | Model No. Indication | Specifications Performance Curve | External Dimensions | Layout Sample Circuit Reference | Cautions | |
|--|----------|-----------------------|-------------------------|-------------------------------------|------------------------|------------------------------------|----------|--|
|--|----------|-----------------------|-------------------------|-------------------------------------|------------------------|------------------------------------|----------|--|



• Specifications (Workpiece Hole Shape : Tapered)

Applicable Model No.



| Model No. | | | WKK | 100 | I-□- | - |] -T | | ,_ | the Hole Diameter on P.9. 0 or less bining $\begin{array}{c} 4 \\ \end{array}$ D and C) ± 0.5 (In case of $\begin{array}{c} 4 \\ \end{array}$ M) 1.0 6.7 5.8 0.7 0.25 1.0 ~ 0.3 or more ~ 70 | | | | | | | |
|------------------------|---|-----|---------|------------|-------|----------|-------------|------------|-------|---|-------|--------|-------|------------|-----|------|-----|
| | 3 Workpiece Hole Code | 060 | 065 | 070 | 075 | 080 | 085 | 09 | 0 | 095 | 100 | 105 | 110 | 115 | 120 | 125 | 130 |
| | Hole Mouth Diam. ϕd m | n - | 6.5 | 7 | 7.5 | 8 | 8.5 | 9 |) | 9.5 | 10 | 10.5 | 11 | 11.5 | 12 | 12.5 | 13 |
| Workpiece | Allowable Tolerance of Hole Mouth Diam | - | 1 | | Pot | fer to | 3 | Wor | knia | - 0 LI | | Jiam | otor | | 20 | | |
| Workpiece | Hole Slope Angle | - | | | nei | | | WUI | kpied | еп | olei | Jian | ietei | OIT | .9. | | |
| | Hardness | - | 1 | | | | | ŀ | HB25 | 0 or | less | i | | | | | |
| Locating Re | peatability ^{% 1} mr | า - | 1 | | | 0.0 | 3 (W | hen | coml | bini | ng | 4 D | and | C) | | | |
| Allowable Offset (Flo | ating Clearance of Expanding Area) $^{st 2}$ mr | n - | ±(|).3 (I | n ca | se o | f 4 | M) | | = | ±0.5 | (In | case | of | 4 M |) | |
| Workpiece | Pulling Stroke mr | n - | | | | | | | | 1.0 | | | | | | | |
| Cylinder Capac | ity Release cm | 3 _ | | | 5 | .3 | | | | | | | 6.7 | | | | |
| (Empty Actio | n) Lock cm | 3_ | | | 4 | .6 | | | | | | | 5.8 | | | | |
| Max. Opera | ting Pressure MP | a - | 0 | .5 | | | | | | 0. | 7 | | | | | | |
| Min. Releas | ing Pressure MP | a - | 1 | | | | | | C |).25 | | | | | | | |
| Withstandi | ng Pressure MP | a - | 0. | 75 | | | | | | 1. | 0 | | | | | | |
| Recommend | ed Air Blow Pressure MP | a - | | | | | | | 0.2 | ~ 0 | .3 | | | | | | |
| Air Blow Flow | v Rate (per cylinder) L / mi | n - | 1 | 15 or more | | | | | | | | | | | | | |
| Operating ⁻ | ° ۲emperature | - 1 | | 0~70 | | | | | | | | | | | | | |
| Usable Flui | d | - | Dry Air | | | | | | | | | | | | | | |
| Weight | | - | | Refe | er to | the e | exter | nal d | limer | nsioi | ns fo | or the | e pro | duct | wei | ght. | |

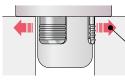
** The workpiece hole diameter : **060** cannot be selected when selecting **6 T** : Taper Hole model.

Notes :

1. Locating repeatability under the same condition (no load).

*2. The expanding part of option M is an adjusting structure and the clamping operation is done by locating a workpiece hole. The value in the table shows the amount of tolerance value of single hole gripper. Please consider the distance accuracy of each cylinder mounting hole and each workpiece machining hole when using with another location clamp / location cylinder, or when using more than two of these products.

€ Gripping Force • Clamping Force Curve



FH: Gripping Force^{*1} It shows the expanding force generated inside a workpiece hole.

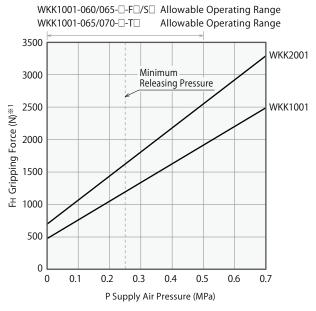


Fc: Clamping Force It shows the force that pulls a workpiece

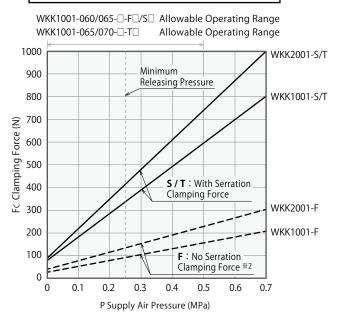
to the seating surface.

| | | | 6 S / T : with Serration | | | | | | | | 6 F : No Serration | | | |
|---------------------|----|---|---------------------------------|-----------|-----|--------------------------|-----------------|------------------|----------------------|--------------------|---------------------------|----------------|---------------------|--|
| Model No. | | | WKK100 | WKK1001S- | | (K10 |)01- □ · | ·D-D- T D | WKK2001S WKK2001T | wк | WKK1001-□-□-□-F□ | | WKK2001F | |
| | | 3 Workpiece Hole Code | 060 065 | 070~090 | 060 | 065 | 070 | 075~090 | 090 ~ 130 | 060 | 065 | $070 \sim 090$ | 090 ~ 130 | |
| | | Air Pressure 0.7 MPa | | 2500 | - | - | - | 2500 | 3300 | - | - | 2500 | 3300 | |
| | | Air Pressure 0.6 MPa | | 2200 | - | - | - | 2200 | 2900 | - | - | 2200 | 2900 | |
| | | Air Pressure 0.5 MPa | 1 | 900 | - | - | 19 | 00 | 2500 | | 1900 | | 2500 | |
| Gripping | N | Air Pressure 0.4 MPa | 1 | 600 | - | | 16 | 00 | 2200 | 1600 | | 1600 | 2200 | |
| Force ^{%1} | IN | Air Pressure 0.3 MPa | 1 | 1300 | - | - | 13 | 00 | 1800 | | | 1300 | 1800 | |
| | | Air Pressure 0.25 MPa | 1 | 200 | - | | 12 | 00 | 1600 | | | 1200 | 1600 | |
| | | Air Pressure $0_{MPa} \begin{pmatrix} Zero Air \\ Pressure \end{pmatrix}$ | | 480 | - | | 48 | 80 | 700 | | | 480 | 700 | |
| | | Calculation Formula ^{%3} | $F_H = 2870P + 480$ | | - | $-F_{\rm H} = 2870P + 4$ | | 0P + 480 | $F_H = 3700P + 700$ | F _H = 2 | | 870P + 480 | $F_H = 3700P + 700$ | |
| | | Air Pressure 0.7 MPa | | 800 | - | - | 800 | | 1000 | 210 | | 210 | 300 | |
| | | Air Pressure 0.6 MPa | | 700 | - | 700 | | 700 | 870 | 180 | | 180 | 260 | |
| | | Air Pressure 0.5 MPa | | 600 | - | 600 | | 00 | 740 | | 160 | | 220 | |
| Clamping | N | Air Pressure 0.4 MPa | | 490 | - | | 490 | | 610 | | | 130 | 190 | |
| Force | IN | Air Pressure 0.3 MPa | | 390 | - | | 39 | 90 | 480 | | | 100 | 150 | |
| | | Air Pressure 0.25 MPa | 340 | | _ | | 340 | | 420 | | | 88 | 130 | |
| | | Air Pressure $0_{MPa} \begin{pmatrix} Zero Air \\ Pressure \end{pmatrix}$ | | 80 | - | 80 | | 0 | 90 | 20 | | 20 | 30 | |
| | | Calculation Formula ^{*3} | Fc= 10 | 030P + 80 | _ | Fc= | = 103 | 0P + 80 | Fc= 1300P + 90 | Fc= 270P + 20 | | 270P + 20 | Fc= 390P + 30 | |

Gripping Force Curve



Clamping Force Curve



Notes :

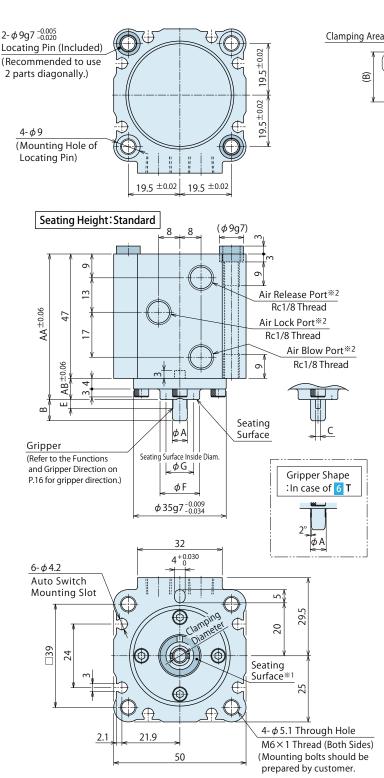
- 1. The table and graph show the relationship among supply air pressure, gripping force and clamping force.
- 2. Gripping force shows the expanding force acting perpendicular to the hole gripper's center axis.
 - Clamping force shows the force that pulls a workpiece to the seating surface.
- 3. Thin wall around the workpiece hole can be deformed by clamping action and the specifications may not be filled.
- *1. Gripping force shows the calculated value when the friction coefficient of expanding area is μ 0.15.
- 2. Clamping force of F:No Serration shows the calculated value when the friction coefficient of workpiece and gripper is μ 0.1.
- %3. FH: Gripping Force (N), FC: Clamping Force (N), P: Supply Air Pressure (MPa).

| Harmony in Innovation |
|-----------------------|
|-----------------------|

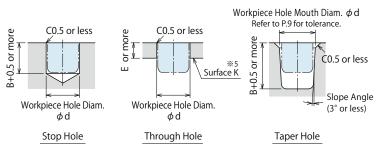
C MEMO

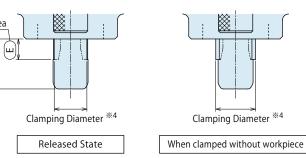
External Dimensions

* The drawing shows the released state of WKK1001- - C-F.

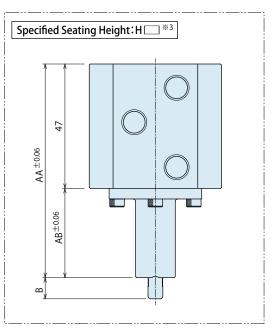


Machining Dimensions of Workpiece (Pallet) Hole





* Expanding Area Detail



Notes :

- Mounting bolts are not provided.
 Please prepare them according to the mounting position. (Refer to "Installation of Hole Gripper" on P.27.)
- This product locks with air pressure and self-locking spring and releases with air pressure. (When air drops to 0MPa, it will be in the locked state with gripper expansion.)
- %1. The workpiece must be resting on all seating surfaces when clamping. Otherwise the workpiece can be deformed by the clamping force.
- ※2. The name of each port is marked on the port. (LOCK: Air Lock Port, RELEASE: Air Release Port, BLOW: Air Blow Port) Continuously supply air pressure to the air blow port when in use.
- %3. Please refer to the drawing on the left side : Seating Height: Standard for unlisted dimensions.
- ※4. For -T: Taper Hole model, the first gripper ridge is the reference diameter.

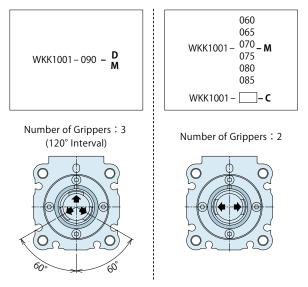
Notes :

 Thin wall around the workpiece hole can be deformed by clamping action, gripping force and clamping force will not fill the specification.

Please make sure to test the clamping function before using and adjust to the appropriate supply of pressure.

※5. When the hole gripper head is sticking above the surface K of the workpiece, please make sure there is no interference with the hole gripper during machining.

Functions and Gripper Direction

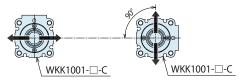


➡ shows the expanding direction of the gripper.

C Mounting Direction of WKK1001-

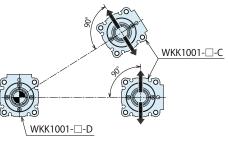
When locating with workpiece hole code 060 ~ 085

※ Rotate 90° of the expanding direction of two hole grippers toward the line connecting the centers of two WKK1001-□-C. (Accuracy is not guaranteed since there is no reference locating.)

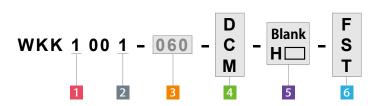


When locating with workpiece hole code 090

% The expanding direction of WKK1001 -C must be vertical toward the line connecting the centers of WKK1001 -D and WKK1001 -D -C.



shows the expanding direction of the gripper.



C External Dimension List

Model No. Indication

| | | | | | | | | (mm) |
|--|--|---|----------|--------|---|--------|---|-------|
| Model No. | | | | WKK1 | 001-🗆-🗆 | | | |
| | iece Hole Code | 060 *6 | 065 | 070 | 075 | 080 | 085 | 090 |
| Workpiece Hole Diam. | ¢d In case of 6 F,S ^{%9} | 6 +0.7 | 6.5 +0.7 | 7 +0.7 | 7.5 +0.7 | 8 -0.3 | 8.5-0.3 | 9+0.7 |
| Clamping Diameter | At Release | 5.5 | 6.0 | 6.5 | 7.0 | 7.5 | 8.0 | 8.5 |
| In case of 6 F,S | At Idle | 7.2 | 7.7 | 8.2 | 8.7 | 9.2 | 9.7 | 10.2 |
| Clamping Diameter | At Release | _ | 5.7 | 6.2 | 6.7 | 7.2 | 7.7 | 8.2 |
| In case of 6 T | At Idle | - | 7.4 | 7.9 | 8.4 | 8.9 | 9.4 | 9.9 |
| Workpiece Pulling S | troke | | | | $\begin{array}{c ccccccccccccccccccccccccccccccccccc$ | | | |
| | A | e Code 060 **6 065 070 07 case of 6 F,S **9 $6 + \frac{0.7}{0.3}$ $6.5 + \frac{0.7}{0.3}$ $7.5 + \frac{0.7}{0.3}$ | 7.1 | 7.6 | 8.1 | 8.6 | | |
| In case of 6 F,S | В | 8 | 8 | 8 | 8 | 8 | $\begin{array}{c cccc} 80 & 085 \\ \hline 80 & 8.5 \pm 0.3 \\ \hline 0.3 & 8.5 \pm 0.3 \\ \hline 0.5 & 8.0 \\ \hline .2 & 9.7 \\ \hline .2 & 7.7 \\ \hline .9 & 9.4 \\ \hline \\ .6 & 8.1 \\ \hline \\ 8 & 8 \\ \hline \\ 3 & 3 \\ .3 & 3.3 \\ \hline \\ .5 & 8 \\ \hline \\ 8 & 8 \\ \hline \\ .5 & 3 \\ \hline \\ .3 & 3.3 \\ \hline \\ 8 & 19 \\ \hline \end{array}$ | 9.5 |
| in case of 6 F,S | С | 2 | 2 | 2.5 | 2.5 | 3 | 3 | 4.5 |
| | E | 3.3 | 3.3 | 3.3 | 3.3 | 3.3 | 3.3 | 4.3 |
| | Α | - | 6 | 6.5 | 7 | 7.5 | 8 | 8.6 |
| In case of 6 T | В | - | 8 | 8 | 8 | 8 | 8 | 9.5 |
| | С | - | 2 | 2 | 2.5 | 2.5 | 3 | 4.5 |
| | E | _ | 3.3 | 3.3 | 3.3 | 3.3 | 3.3 | 4.3 |
| | F | 16 | 17 | 17 | 18 | 18 | 19 | 20 |
| | G | 10.5 | 11.5 | 11.5 | 12.5 | 12.5 | 13.5 | 14.5 |
| 4 Function D Locating Repeatab | Not Available | | | | | | | |
| 4 Function M Allowable Offset (Floating Cle | ±0.3 | | | | | | | |

Body Size
 Design No.
 Workpiece Hole Diam. (Hole Code)
 Functions
 Seating Height Dimension

6 Shape of Gripper (Workpiece Hole)

Notes : %6. The workpiece hole diameter : 060 cannot be selected when selecting 6 T : Taper Hole model.

%7. Locating repeatability under the same condition (no load).

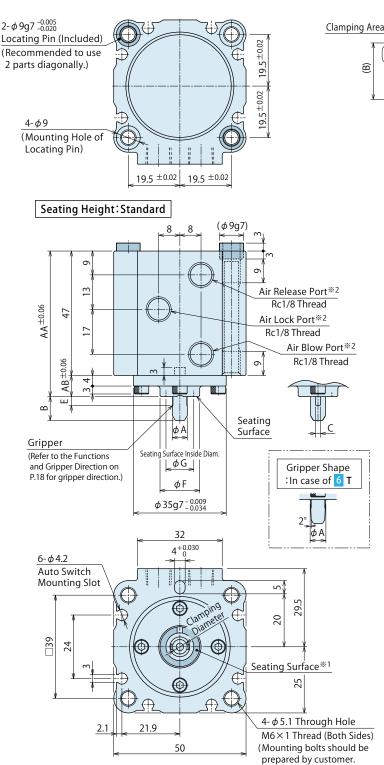
**8. The expanding part is an adjusting structure and the clamping operation is done by locating a workpiece hole. The value in the table shows the amount of tolerance value of single hole gripper. Please consider the distance accuracy of each cylinder mounting hole and each workpiece machining hole when using with another location clamp / location cylinder, or when using more than two of these products.
 **9. The allowable tolerance of workpiece hole mouth diameter varies depending on the slope angle in case of T : Taper Hole model.

(Please refer to P.9.)

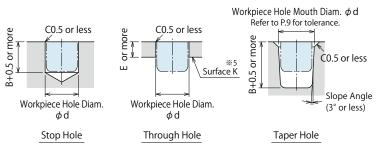
| 5 Seating Height Dimension | Standard | Specified | | | | | | |
|----------------------------|----------|-----------|------|------|------|-------------------------|--|--|
| Jeating height Dimension | Blank | H10 | H20 | H30 | H40 | H50 105 58 | | |
| AA | 55 | 65 | 75 | 85 | 95 | 105 | | |
| AB | 8 | 18 | 28 | 38 | 48 | 58 | | |
| Weight kg | 0.38 | 0.40 | 0.42 | 0.44 | 0.46 | 0.48 | | |

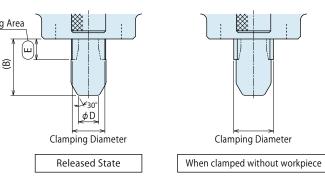
External Dimensions

* The drawing shows the released state of WKK1001- - C-FB.

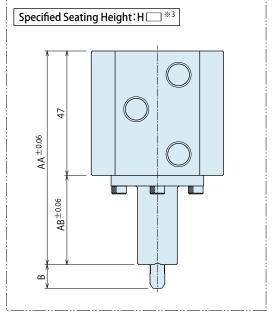


Machining Dimensions of Workpiece (Pallet) Hole





* Expanding Area Detail



Notes :

- Mounting bolts are not provided.
 Please prepare them according to the mounting position. (Refer to "Installation of Hole Gripper" on P.27.)
- This product locks with air pressure and self-locking spring and releases with air pressure. (When air drops to 0MPa, it will be in the locked state with gripper expansion.)
- %1. The workpiece must be resting on all seating surfaces when clamping. Otherwise the workpiece can be deformed by the clamping force.
- *2. The name of each port is marked on the port.
 (LOCK: Air Lock Port, RELEASE: Air Release Port, BLOW: Air Blow Port) Continuously supply air pressure to the air blow port when in use.
- %3. Please refer to the drawing on the left side : Seating Height: Standard for unlisted dimensions.
- ※4. For -T: Taper Hole model, the first gripper ridge is the reference diameter.

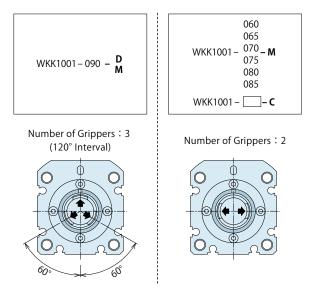
Notes :

 Thin wall around the workpiece hole can be deformed by clamping action, gripping force and clamping force will not fill the specification.

Please make sure to test the clamping function before using and adjust to the appropriate supply of pressure.

※5. When the hole gripper head is sticking above the surface K of the workpiece, please make sure there is no interference with the hole gripper during machining.

Functions and Gripper Direction

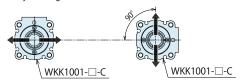


➡ shows the expanding direction of the gripper.

S Mounting Direction of WKK1001-

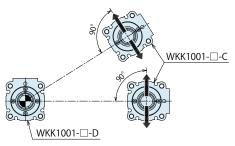
When locating with workpiece hole code 060 ~ 085

※ Rotate 90° of the expanding direction of two hole grippers toward the line connecting the centers of two WKK1001-□-C. (Accuracy is not guaranteed since there is no reference locating.)



When locating with workpiece hole code 090

% The expanding direction of WKK1001 -C must be vertical toward the line connecting the centers of WKK1001 -D and WKK1001 -C.



[➡] shows the expanding direction of the gripper.

1 Body Size

- 2 Design No.
- 3 Workpiece Hole Diam. (Hole Code) 4 Functions
- 5 Seating Height Dimension
- 6 Shape of Gripper (Workpiece Hole)
- 7 Shape of Cap End (In case of B)

External Dimension List

1

WKK 1 00 1 - 060

2

C Model No. Indication

| Model No. | | | | WKK1001B | | | | | | | | |
|--|--|---------------|----------|----------|----------|--------|--|-------|--|--|--|--|
| 3 Workp | iece Hole Code | 060 %6 | 065 | 070 | 075 | 080 | 085 | 090 | | | | |
| Workpiece Hole Diam | . φd In case of 6 F,S ^{%9} | 6 +0.7 | 6.5 +0.7 | 7 -0.3 | 7.5 +0.7 | 8 +0.7 | 8.5-0.3 | 9-0.3 | | | | |
| Clamping Diameter | At Release | 5.5 | 6.0 | 6.5 | 7.0 | 7.5 | 8.0 | 8.5 | | | | |
| In case of 🧿 F,S | At Idle | 7.2 | 7.7 | 8.2 | 8.7 | 9.2 | 9.7 | 10.2 | | | | |
| Clamping Diameter | At Release | _ | 5.7 | 6.2 | 6.7 | 7.2 | 7.7 | 8.2 | | | | |
| In case of 🧕 T | At Idle | - | 7.4 | 7.9 | 8.4 | 8.9 | 9.4 | 9.9 | | | | |
| Workpiece Pulling S | Stroke | | | | 1.0 | | 8.5 ^{+0.7} 8.0 9.7 7.7 | | | | | |
| | A | 5.6 | 6.1 | 6.6 | 7.1 | 7.6 | 8.1 | 8.6 | | | | |
| | В | 9 | 9 | 9 | 10 | 10 | 10 | 11 | | | | |
| In case of 🧿 F,S | С | 2 | 2 | 2.5 | 2.5 | 3 | 3 | 4.5 | | | | |
| | D | 3.5 | 4 | 4.5 | 4 | 4.5 | 5 | 5.4 | | | | |
| | E | 3.3 | 3.3 | 3.3 | 3.3 | 3.3 | 3.3 | 4.3 | | | | |
| | A | _ | 6 | 6.5 | 7 | 7.5 | 8 | 8.6 | | | | |
| | В | _ | 9 | 9 | 9 | 10 | 10 | 11 | | | | |
| In case of 6 T | С | - | 2 | 2 | 2.5 | 2.5 | 3 | 4.5 | | | | |
| | D | _ | 3.2 | 3.7 | 4.2 | 3.6 | 4.1 | 5.2 | | | | |
| | E | - | 3.3 | 3.3 | 3.3 | 3.3 | 3.3 | 4.3 | | | | |
| | F | 16 | 17 | 17 | 18 | 18 | 19 | 20 | | | | |
| | G | 10.5 | 11.5 | 11.5 | 12.5 | 12.5 | 13.5 | 14.5 | | | | |
| 4 Function D Locating Repeatab | Not Available 0.0 | | | | | | | | | | | |
| 4 Function M Allowable Offset (Floating Cle | earance of Expanding Area) ^{※8} | ±0.3 | | | | | | | | | | |

D

С

Μ

Blank

5

HD

F

S

6

В

7

(mm)

Notes: %6. The workpiece hole diameter: **060** cannot be selected when selecting **6 T** : Taper Hole model.

%7. Locating repeatability under the same condition (no load).

※8. The expanding part is an adjusting structure and the clamping operation is done by locating a workpiece hole. The value in the table shows the amount of tolerance value of single hole gripper. Please consider the distance accuracy of each cylinder mounting hole and each workpiece machining hole when using with another location clamp / location cylinder, or when using more than two of these products.

※9. The allowable tolerance of workpiece hole mouth diameter varies depending on the slope angle in case of T : Taper Hole model. (Please refer to P.9.)

| | | | | | | (mm) |
|----------------------------|----------|------|------|-----------|------|------|
| 5 Seating Height Dimension | Standard | | | Specified | 1 | |
| 5 Seating Height Dimension | Blank | H10 | H20 | H30 | H40 | H50 |
| AA | 55 | 65 | 75 | 85 | 95 | 105 |
| AB | 8 | 18 | 28 | 38 | 48 | 58 |
| Weight kg | 0.38 | 0.40 | 0.42 | 0.44 | 0.46 | 0.48 |

+0.07

2

±0.02

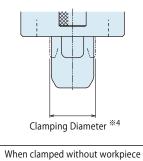
External Dimensions

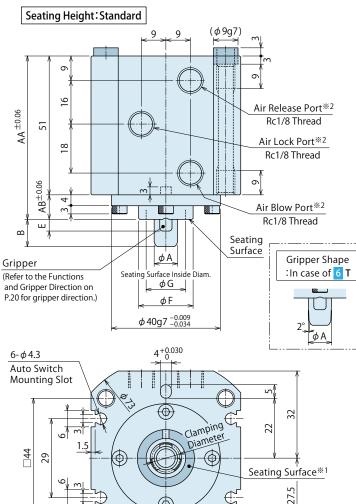
% The drawing shows the released state of WKK2001- \Box -D-F.

 $2-\phi 9g7_{-0.020}^{-0.005}$ Locating Pin (Included) (Recommended to use 2 parts diagonally.) $4-\phi 9$ (Mounting Hole of Locating Pin) Seating Height: Standard 9 - 9 - 0 (1)

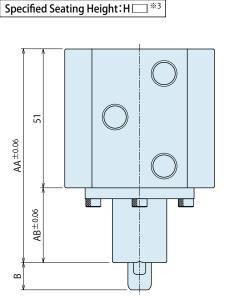
Clamping Area

* Expanding Area Detail





release Port**2 Rc1/8 Thread r Lock Port**2 Rc1/8 Thread Blow Port**2 10 Thread



Notes :

- Mounting bolts are not provided.
 Please prepare them according to the mounting position. (Refer to "Installation of Hole Gripper" on P.27.)
- 2. This product locks with air pressure and self-locking spring and releases with air pressure. (When air drops to 0MPa, it will be in the locked state with gripper expansion.)
- %1. The workpiece must be resting on all seating surfaces when clamping. Otherwise the workpiece can be deformed by the clamping force.
- *2. The name of each port is marked on the port.
 (LOCK: Air Lock Port, RELEASE: Air Release Port, BLOW: Air Blow Port) Continuously supply air pressure to the air blow port when in use.
- %3. Please refer to the drawing on the left side : Seating Height: Standard for unlisted dimensions.
- ※4. For -T: Taper Hole model, the first gripper ridge is the reference diameter.

Notes :

 $4-\phi$ 5.2 Through Hole

M6×1 Thread (Both Sides)

(Mounting bolts should be prepared by customer.

Workpiece Hole Mouth Diam. ϕ d . Refer to P.9 for tolerance. C0.5 or less C0.5 or less more B+0.5 or more more P C0.5 or less 3+0.5 or ш Surface K Slope Angle Workpiece Hole Diam. Workpiece Hole Diam. (3° or less) φd φd Stop Hole Through Hole Taper Hole

Machining Dimensions of Workpiece (Pallet) Hole

23.9

55

es : Thin wa

 Thin wall around the workpiece hole can be deformed by clamping action, gripping force and clamping force will not fill the specification.

Please make sure to test the clamping function before using and adjust to the appropriate supply of pressure.

※5. When the hole gripper head is sticking above the surface K of the workpiece, please make sure there is no interference with the hole gripper during machining.

| Features | Action Description | Model No. Indication | Specifications Performance Curve | External Dimensions | Layout Sample Circuit Reference | Cautions | |
|----------|-----------------------|-------------------------|-------------------------------------|------------------------|------------------------------------|----------|--|
| | | | | | | | |

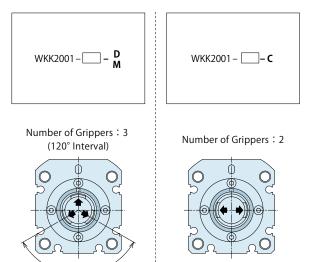
Mounting Direction of WKK2001-□-C

WKK2001-D-D

※ The expanding direction of WKK2001□-C must be vertical toward the line connecting the centers of WKK2001-□-D and WKK2001-□-C.

➡ shows the expanding direction of the gripper.

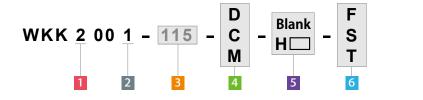
Functions and Gripper Direction



➡ shows the expanding direction of the gripper.

Model No. Indication

External Dimension List



Body Size
 Design No.
 Workpiece Hole Diam. (Hole Code)
 Functions
 Seating Height Dimension
 Shape of Gripper (Workpiece Hole)

WKK2001-D-C

| | | | | | | | | | | (mm) |
|---|---|---------------------------|---------|--------------------|----------------------|----------------------------|----------------------|--------------------|----------------------|--------------------|
| Model No. | | WKK2001-□-□-□ | | | | | | | | |
| 3 Workpiece Hole Code | | | 095 | 100 | 105 | 110 | 115 | 120 | 125 | 130 |
| Workpiece Hole Diam. | ¢ d In case of 6 F,S ^{⋇8} | 9 ^{+0.7} -0.3 | 9.5+0.7 | $10^{+0.7}_{-0.3}$ | $10.5^{+0.7}_{-0.3}$ | 11 ^{+0.7} -0.3 | $11.5^{+0.7}_{-0.3}$ | $12^{+0.7}_{-0.3}$ | $12.5^{+0.7}_{-0.3}$ | $13^{+0.7}_{-0.3}$ |
| Clamping Diameter | At Release | 8.5 | 9.0 | 9.5 | 10.0 | 10.5 | 11.0 | 11.5 | 12.0 | 12.5 |
| In case of 6 F,S | At Idle | 10.2 | 10.7 | 11.2 | 11.7 | 12.2 | 12.7 | 13.2 | 13.7 | 14.2 |
| Clamping Diameter | At Release | 8.2 | 8.5 | 9 | 9.5 | 9.95 | 10.45 | 10.95 | 11.45 | 11.95 |
| In case of 6 T At Idle Workpiece Pulling Stroke | | 9.9 | 10.2 | 10.7 | 11.2 | 11.65 | 12.15 | 12.65 | 13.15 | 13.65 |
| | | 1.0 | | | | | | | | |
| | A | 8.6 | 9.1 | 9.6 | 10.1 | 10.6 | 11.1 | 11.6 | 12.1 | 12.6 |
| In case of 6 F,S | В | 10 | 10 | 10 | 11.5 | 11.5 | 11.5 | 11.5 | 11.5 | 11.5 |
| | С | 4.5 | 4.5 | 5 | 5 | 5.5 | 5.5 | 6 | 6 | 6.5 |
| | E | 4.3 | 4.3 | 4.3 | 5.8 | 5.8 | 5.8 | 5.8 | 5.8 | 5.8 |
| | A | 8.6 | 9 | 9.5 | 10 | 10.4 | 10.9 | 11.4 | 11.9 | 12.4 |
| In case of 6 T | В | 10 | 10 | 10 | 10 | 11.5 | 11.5 | 11.5 | 11.5 | 11.5 |
| | С | 4.5 | 4.5 | 4.5 | 5 | 5 | 5 | 5.5 | 5.5 | 6 |
| | E | 4.3 | 4.3 | 4.3 | 4.3 | 5.8 | 5.8 | 5.8 | 5.8 | 5.8 |
| | F | | 22 | 22 | 23 | 23 | 24 | 24 | 25 | 25 |
| | 14.5 | 15.5 | 15.5 | 16.5 | 16.5 | 17.5 | 17.5 | 18.5 | 18.5 | |
| 4 Function D Locating Repeatable | 0.03 | | | | | | | | | |
| 4 Function M Allowable Offset (Floating Cle | earance of Expanding Area) ^{※ 7} | ±0.5 | | | | | | | | |

Notes: %6. Locating repeatability under the same condition (no load).

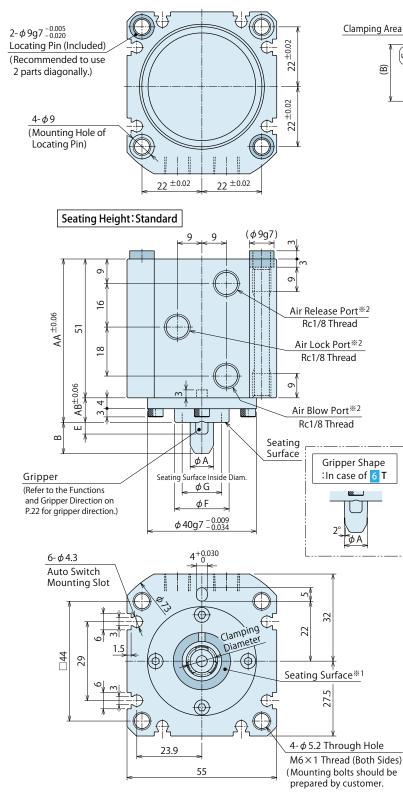
*7. The expanding part is an adjusting structure and the clamping operation is done by locating a workpiece hole. The value in the table shows the amount of tolerance value of single hole gripper. Please consider the distance accuracy of each cylinder mounting hole and each workpiece machining hole when using with another location clamp / location cylinder, or when using more than two of these products.
 *8. The allowable tolerance of workpiece hole mouth diameter varies depending on the slope angle in case of T : Taper Hole model.

(Please refer to P.9.)
(mm)

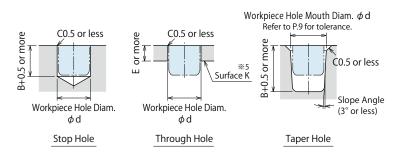
| 5 Seating Height Dimension | Standard | Specified | | | | | |
|----------------------------|----------|-----------|------|------|------|------|--|
| 5 Seating Reight Dimension | Blank | H10 | H20 | H30 | H40 | H50 | |
| AA | 60 | 70 | 80 | 90 | 100 | 110 | |
| AB | 9 | 19 | 29 | 39 | 49 | 59 | |
| Weight kg | 0.50 | 0.54 | 0.57 | 0.60 | 0.64 | 0.67 | |

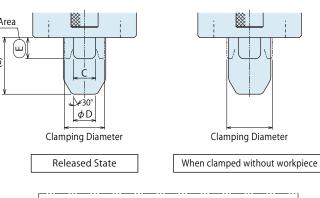
External Dimensions

% The drawing shows the released state of WKK2001- - - D-FB.

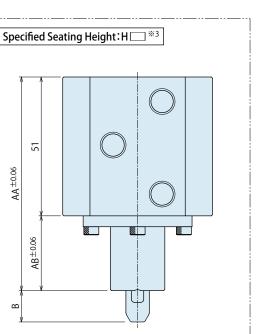


Machining Dimensions of Workpiece (Pallet) Hole





* Expanding Area Detail



Notes :

- Mounting bolts are not provided.
 Please prepare them according to the mounting position. (Refer to "Installation of Hole Gripper" on P.27.)
- 2. This product locks with air pressure and self-locking spring and releases with air pressure. (When air drops to 0MPa, it will be in the locked state with gripper expansion.)
- %1. The workpiece must be resting on all seating surfaces when clamping. Otherwise the workpiece can be deformed by the clamping force.
- ※2. The name of each port is marked on the port. (LOCK: Air Lock Port, RELEASE: Air Release Port, BLOW: Air Blow Port) Continuously supply air pressure to the air blow port when in use.
- %3. Please refer to the drawing on the left side : Seating Height: Standard for unlisted dimensions.
- ※4. For -T: Taper Hole model, the first gripper ridge is the reference diameter.

Notes :

 Thin wall around the workpiece hole can be deformed by clamping action, gripping force and clamping force will not fill the specification.

Please make sure to test the clamping function before using and adjust to the appropriate supply of pressure.

※5. When the hole gripper head is sticking above the surface K of the workpiece, please make sure there is no interference with the hole gripper during machining.

| Features | Action Description | Model No. Indication | Specifications Performance Curve | External Dimensions | Layout Sample Circuit Reference | Cautions | |
|----------|-----------------------|-------------------------|-------------------------------------|------------------------|------------------------------------|----------|--|
| | | | | | | | |

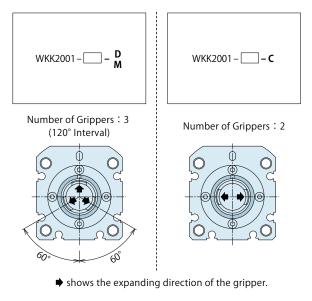
Mounting Direction of WKK2001-□-C

WKK2001-□-D

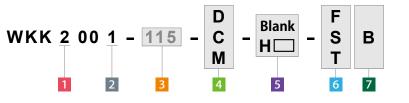
※ The expanding direction of WKK2001□-C must be vertical toward the line connecting the centers of WKK2001-□-D and WKK2001-□-C.

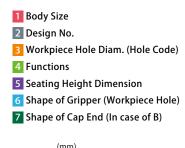
➡ shows the expanding direction of the gripper.

Functions and Gripper Direction



C Model No. Indication





WKK2001-D-C

External Dimension List

| | | | | | | | | | (mm | |
|--|--|----------------|---------|--------------------|----------------------|---------|----------------------|--------------------|----------------------|--------------------|
| Model No. | | WKK2001-□-□-□B | | | | | | | | |
| 3 Workpiece Hole Code | | 090 | 095 | 100 | 105 | 110 | 115 | 120 | 125 | 130 |
| Workpiece Hole Diam. | ϕ d In case of 6 F , S ^{**8} | 9+0.7 | 9.5+0.7 | $10^{+0.7}_{-0.3}$ | $10.5^{+0.7}_{-0.3}$ | 11 +0.7 | $11.5^{+0.7}_{-0.3}$ | $12^{+0.7}_{-0.3}$ | $12.5^{+0.7}_{-0.3}$ | $13^{+0.7}_{-0.3}$ |
| Clamping Diameter | At Release | 8.5 | 9.0 | 9.5 | 10.0 | 10.5 | 11.0 | 11.5 | 12.0 | 12.5 |
| In case of 6 F,S | At Idle | 10.2 | 10.7 | 11.2 | 11.7 | 12.2 | 12.7 | 13.2 | 13.7 | 14.2 |
| Clamping Diameter | At Release | 8.2 | 8.5 | 9 | 9.5 | 9.95 | 10.45 | 10.95 | 11.45 | 11.95 |
| In case of 6 T | At Idle | 9.9 | 10.2 | 10.7 | 11.2 | 11.65 | 12.15 | 12.65 | 13.15 | 13.65 |
| Workpiece Pulling Stroke | | 1.0 | | | | | | | | |
| | A | 8.6 | 9.1 | 9.6 | 10.1 | 10.6 | 11.1 | 11.6 | 12.1 | 12.6 |
| | В | 11.5 | 11.5 | 11.5 | 13.5 | 13.5 | 13.5 | 13.5 | 14.5 | 14.5 |
| In case of 6 F,S | C | 4.5 | 4.5 | 5 | 5 | 5.5 | 5.5 | 6 | 6 | 6.5 |
| | D | 5.2 | 5.7 | 6.2 | 6.1 | 6.6 | 7.1 | 7.6 | 6.9 | 7.4 |
| | E | 4.3 | 4.3 | 4.3 | 5.8 | 5.8 | 5.8 | 5.8 | 5.8 | 5.8 |
| | А | 8.6 | 9 | 9.5 | 10 | 10.4 | 10.9 | 11.4 | 11.9 | 12.4 |
| | В | 11.5 | 11.5 | 11.5 | 11.5 | 13.5 | 13.5 | 13.5 | 13.5 | 14.5 |
| In case of <mark>6</mark> T | С | 4.5 | 4.5 | 4.5 | 5 | 5 | 5 | 5.5 | 5.5 | 6 |
| | D | 4.6 | 4.9 | 5.4 | 5.9 | 5.7 | 6.2 | 6.7 | 7.2 | 6.5 |
| | E | 4.3 | 4.3 | 4.3 | 4.3 | 5.8 | 5.8 | 5.8 | 5.8 | 5.8 |
| F | | 21 | 22 | 22 | 23 | 23 | 24 | 24 | 25 | 25 |
| 1 | G | 14.5 | 15.5 | 15.5 | 16.5 | 16.5 | 17.5 | 17.5 | 18.5 | 18.5 |
| 4 Function D | | | | | | | | | | |
| Locating Repeatab | ility ^{%6} | | | | | 0.03 | | | | |
| 4 Function M Allowable Offset (Floating Cle | earance of Expanding Area) ^{※7} | | | | | ±0.5 | | | | |

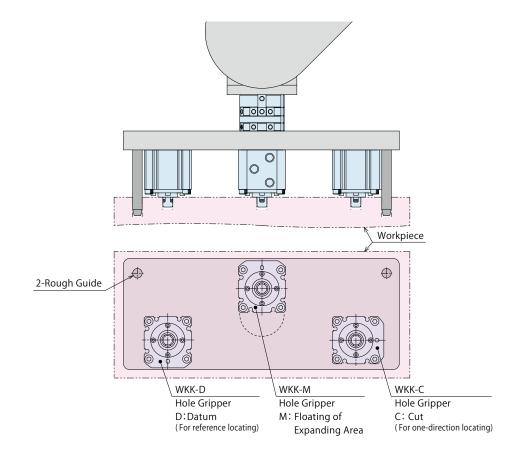
Notes: %6. Locating repeatability under the same condition (no load).

*7. The expanding part is an adjusting structure and the clamping operation is done by locating a workpiece hole. The value in the table shows the amount of tolerance value of single hole gripper. Please consider the distance accuracy of each cylinder mounting hole and each workpiece machining hole when using with another location clamp / location cylinder, or when using more than two of these products.
 *8. The allowable tolerance of workpiece hole mouth diameter varies depending on the slope angle in case of T : Taper Hole model.

(Please refer to P.9.)

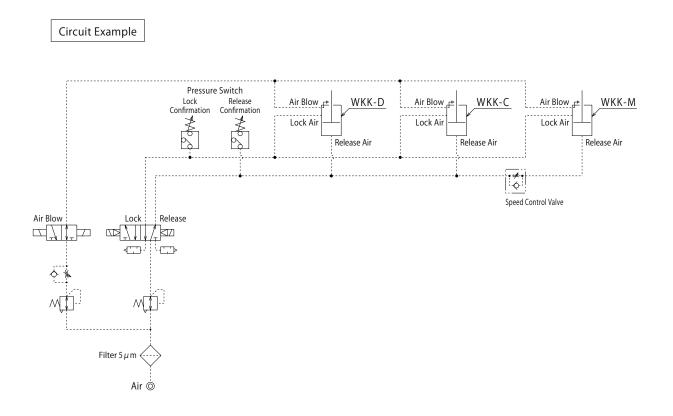
| | | | | | | (mm) | |
|----------------------------|----------|-----------|------|------|------|------|--|
| 5 Seating Height Dimension | Standard | Specified | | | | | |
| 5 Seating height Dimension | Blank | H10 | H20 | H30 | H40 | H50 | |
| AA | 60 | 70 | 80 | 90 | 100 | 110 | |
| AB | 9 | 19 | 29 | 39 | 49 | 59 | |
| Weight kg | 0.50 | 0.54 | 0.57 | 0.60 | 0.64 | 0.67 | |

Sample 1 (Layout and Circuit)



Note :

1. When loading/unloading a workpiece, install 2 or more rough guides in order to prevent damage to a clamping part.



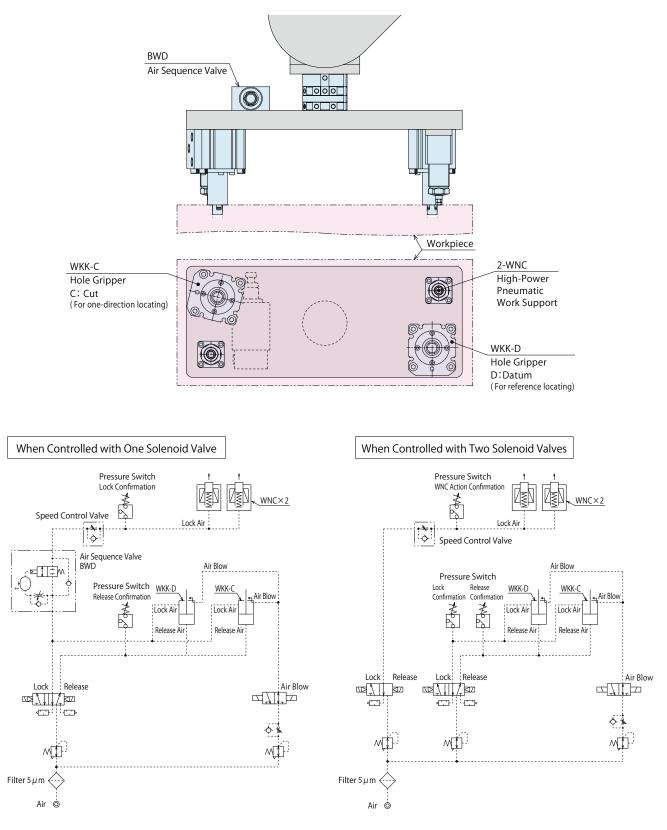
| Description Indication Performance Curve Dimensions Circuit Reference | Features | Action | Model No. | Specifications | External Dimensions | Layout Sample | Cautions | KOSMEN |
|---|----------|--------|-----------|----------------|------------------------|---------------|----------|--------|
|---|----------|--------|-----------|----------------|------------------------|---------------|----------|--------|

Sample 2 (Layout and Circuit)

Combination Use with High-Power Pneumatic Work Support (model WNC) for Workpiece Inclination Prevention During Transfer

When the gravity center of a workpiece is unbalanced, it could damage the hole gripper or drop a workpiece affected by inertia moment due to high-speed transfer (sudden stop). Use work supports, etc. when designing a system.

** This drawing shows a layout sample of WKK-D/C (Hole Gripper), WNC (High-Power Pneumatic Work Support) and BWD (Air Sequence Valve).

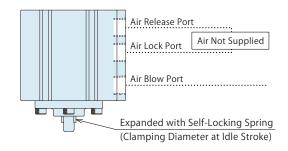


Note :

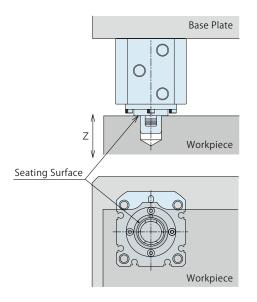
1. Please use solenoid valve or BWD (Air Sequence Valve) to make a sequence operation that WKK (Hole Gripper) starts working after WNC (High-Power Pneumatic Work Support) completes the movement. If WKK activates after WNC completes operation, a workpiece can be projected out, leading to damage on WKK, a workpiece fall and seating malfunction.

Cautions

- Notes for Design
- 1) Check Specifications
- Please use each product according to its specifications.
- This product is an air double-acting cylinder which locks with air pressure and spring force (gripping and clamping), and releases with air pressure. Even when air is not supplied to either lock or release port, the selflock spring maintains clamped state (clamping diameter is expanded).
 ① Gripping force and clamping force at 0MPa are lower than those
 - when air is supplied. For using at zero pressure, please refer to P.13 Gripping • Clamping Force Curve : Air Pressure 0 MPa.
 - ② Supply the release air when loading/unloading a workpiece. Otherwise the workpiece contacts the hole gripper leading to damage to the workpiece and the hole gripper.



- 2) Working Reference Plate (Seating Surface) Z Axis
- The upper surface of the flange of this product is the seating surface of workpiece and locates in Z direction.



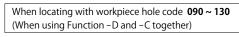
A workpiece must be resting on all seating surfaces when clamping. If not, calculate contacting pressure with clamping force and seating area not to deform a workpiece.

- 3) Wall Thickness around Workpiece Hole
- Thin wall around the workpiece hole can be deformed by clamping action, gripping and clamping forces do not fill the specification.
 Please conduct clamping test and adjust to proper air pressure before use. If clamping force is insufficient, workpiece may fall out.

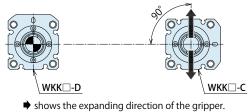


- 4) Hole Gripper Installation
- When Using Functions D/C

-C: Cut locates the orientation using -D: Datum as a reference. Therefore, it is required to determine the phase of -C: Cut when mounting.



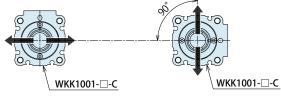
The expanding direction of WKK- \Box -C must be vertical toward the line connecting the centers of WKK- \Box -D and WKK- \Box -C.



When roughly locating with workpiece hole code $\,060\sim085$ (When using Function –C and –C together)

Rotate 90° of the expanding direction of two cylinders toward the line connecting the centers of two WKK1001- \Box -C.

(Accuracy is not guaranteed since there is no reference locating.)



➡ shows the expanding direction of the gripper.

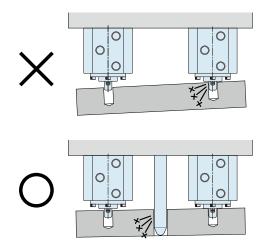
- When Using Function -M: Floating of Expanding Area
 -M has the floating function (WKK1001: ±0.3mm, WKK2001: ±0.5mm). Please consider the distance accuracy of each hole gripper mounting hole and each workpiece machining hole when using with another location clamp / location cylinder, or when using more than two of these products.
- 5) Clamping Force
- Clamping force shows the force that pulls a workpiece onto the seating surface. Please conduct clamping test and adjust to proper air pressure before use. Insufficient clamping force causes a workpiece to fall.
- 6) Workpiece hole size, slope angle and workpiece hardness should be within the range of the specification.

| When workpiece hole diameter is larger than specification. | Leads to insufficient expansion stroke. Gripping force and clamping force will not fill the specifications. |
|--|---|
| When using it with insufficient gripping (clamping) force. | Leads to falling of the workpiece. |
| When workpiece hole diameter is smaller than specification. | Difficult to attach/detach the workpiece leading to damage to the hole gripper. |
| When workpiece hole depth is shallow. | May lead to abnormal seating and damage to the hole gripper. |
| When workpiece hole taper is larger than standard. | May cause gripping malfunction leading to a workpiece fall. |
| When workpiece hole is harder than specified. (" with serration" only) | Gripper does not dig into a workpiece enough and it cannot clamp securely. |

25

| Ha | armony in Innov |
|----|-----------------|
| | |

- 7) Horizontal Locating
- When a workpiece is set, please make sure there is no lifting or slope of the workpiece. If the clamping operation is done with lifting or slope of the workpiece, it will lead to possible damage of the gripper and deformation of the workpiece hole.
- 8) Please detach a workpiece with all grippers fully released.
- When detaching a workpiece during lock or release operation, it may cause damage to the hole gripper and a workpiece fall.
- 9) Please set up rough guides.
- When detaching a workpiece with slope it may cause the damage to the hole gripper and a workpiece fall.

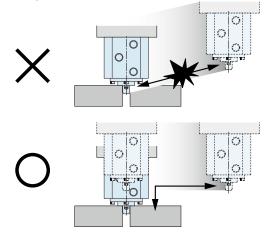


Please set up rough guides considering the pitch accuracy of location clamp / location cylinder mounting hole and each workpiece machining hole when using with another location clamp / location cylinder, etc.

- 10) For Use of Auto Switch
- Select an auto switch depending on the environment.
- An auto switch may be stuck out of the Hole Gripper depending on the installation position and direction.
- 2-wire reed auto switch cannot be used.
- Depending on difference of workpiece hole diameters, the detection range of an auto switch can be insufficient. If using an auto switch, workpiece hole diameter difference should be within ± 0.3 mm.
- 11) Fall Prevention Measures
- In case of accident such as detachment of a workpiece, please prepare fall prevention measures for safety.
- 12) Air Blow Port
- Continuously supply air pressure to the air blow port. Using without air supply causes contaminants entering into the hole gripper leading to clamping malfunction.

- 13) Damage Prevention during Robot Handling, etc.
- When inserting the Hole Gripper tip into/taking it out of a workpiece hole, the Hole Gripper tip has to be vertical to the workpiece hole.

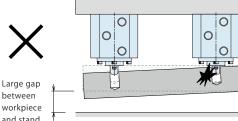
Especially after releasing a workpiece, the Hole Gripper tip must be fully taken out from the workpiece hole before moving to a next coordinate.



- If the Hole Gripper tip touches a workpiece when inserting, control the insertion speed to avoid damage on the workpiece and Hole Gripper tip.
- When the Hole Gripper is mounting/removing a workpiece, make sure that a robot operates only after the Gripper completes locking or releasing action by using a sensor or timer.

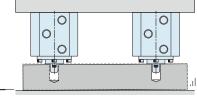
If the robot starts operating in the middle of locking or releasing action, the workpiece may be fallen off.

• When mounting/removing a workpiece, it may be tilted due to a gap between the workpiece and the stand. This causes damage of the Hole Gripper. The gap has to be minimized as much as possible when mounting/removing.



workpiece and stand





between workpiece and stand

Cautions

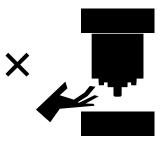
Installation Notes

- 1) Check the fluid to use.
- Please supply filtered clean dry air.
- Oil supply with a lubricator etc. is unnecessary.
- 2) Preparation for Piping
- The pipeline, piping connector and fixture circuits should be cleaned and flushed thoroughly.
 The dust and cutting chips in the circuit may lead to fluid leakage and malfunction.
- There is no filter provided with this product for prevention of contaminants in the air circuit.
- 3) Applying Sealing Tape
- Wrap with tape 1 to 2 times following the screwing direction.
- Pieces of the sealing tape may lead to air leaks and malfunction.
- In order to prevent contaminants from entering into the product during the piping work, it should be carefully cleaned before working.
- 4) Mounting Hole Gripper
- When mounting the product use four hexagonal socket bolts (with tensile strength of A2-70 or more) and tighten them with the torque shown in the list below.
 Tightening with greater torque than recommended can

depress the seating surface or break the bolt. Model Mounting Bolt Size Tightening Torque (N·m) M5×0.8 5.0 WKK $M6 \times 1$ 8.0 4-M6×1 Prepared by Customer С C Ō Ō C С 4-M5×0.8 Prepared by Customer 4-M5×0.8 Prepared by Customer O С 0 O $M6 \times 1$ Prepared by Customer

Notes on Handling

- 1) It should be operated by qualified personnel.
- The hydraulic machine and air compressor should be operated and maintained by qualified personnel.
- 2) Do not operate or remove the product unless the safety protocols are ensured.
- ① The machine and equipment can only be inspected or prepared when it is confirmed that the safety devices are in place.
- ② Before the product is removed, make sure that the above-mentioned safety devices are in place. Shut off the pressure and power source, and make sure no pressure exists in the air and hydraulic circuits.
- ③ After stopping the product, do not remove until the temperature drops.
- ④ Make sure there is no trouble/issue in the bolts and respective parts before restarting the machine or equipment.
- 3) Do not touch workpieces (pallets) or hole grippers while they are working. Otherwise, your hands may be injured.

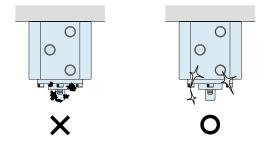


- 4) When transferring a workpiece, make sure the safety of environment in case of an accidental workpiece detachment.
- 5) Do not disassemble or modify.
- If the product is taken apart or modified, the warranty will be voided even within the warranty period.
- Powerful spring is built in inside which is very dangerous.

| Features | Action Description | Model No. Indication | Specifications Performance Curve | External Dimensions | Layout Sample Circuit Reference | Cautions | |
|----------|-----------------------|-------------------------|-------------------------------------|------------------------|------------------------------------|----------|--|
| | | | | | | | |
| | | | | | | | |

Maintenance and Inspection

- 1) Removal of the Product and Shut-off of Pressure Source
- Before removing the product, make sure that safety devices and preventive devices are in place. Shut off the pressure and power source, and make sure no pressure exists in the air and hydraulic circuits.
- Make sure there is no trouble/issue in the bolts and respective parts before restarting.
- 2) Regularly clean the clamping part and seating surface.
- If operating with dirt adhering to the clamping part, it will lead to damage to a product and a workpiece fall due to insufficient gripping force and clamping force, locating malfunction and air leakage, etc.



- 3) Regularly tighten pipe line and mounting bolt to ensure proper use.
- Clamping force will be decreased after repetitive operation due to friction of a gripper surface.
 Replacement period differs depending on operating pressure, workpiece material, and shape of hole. When you find friction on gripper surface, the gripper part needs to be replaced.
 Please contact us for replacement.
- 5) Make sure there is a smooth action without an irregular noise.
- Especially when it is restarted after left unused for a long period, make sure it can be operated correctly.
- 6) The products should be stored in the cool and dark place without direct sunshine or moisture.
- Please contact us for overhaul and repair.
 Powerful spring is built in inside which is very dangerous.

Warranty

- 1) Warranty Period
- The product warranty period is 18 months from shipment from our factory or 12 months from initial use, whichever is earlier.
- 2) Warranty Scope
- If the product is damaged or malfunctions during the warranty period due to faulty design, materials or workmanship, we will replace or repair the defective part at our expense.
 Defects or failures caused by the following are not covered.
- ① If the stipulated maintenance and inspection are not carried out.
- ② If the product is used while it is not suitable for use based on the operator's judgment, resulting in defect.
- ③ If it is used or operated in an inappropriate way by the operator. (Including damage caused by the misconduct of the third party.)
- ⑤ If repair or modifications are carried out by anyone other than Kosmek, or without our approval and confirmation, it will void warranty.
- ⑥ Others caused by natural disasters or calamities not attributable to our company.
- ⑦ Parts or replacement expenses due to parts consumption and deterioration.

(Such as rubber, plastic, seal material and some electric components.)

Damages excluding from direct result of a product defect shall be excluded from the warranty.



| United States of America SUBSIDIARY | KOSMEK (USA) LTD. 650 Springer Drive, Lomba TEL. +1-630-620-7650 | ard, IL 60148 USA FAX. +1-630-620-9015 |
|--|---|---|
| MEXICO REPRESENTATIVE OFFICE | KOSMEK USA Mexico Offic Av. Santa Fe 103, Int. 59, cc QRO, 76230, Mexico | ol. Santa Fe Juriquilla, Queretaro, |
| EUROPE SUBSIDIARY | KOSMEK EUROPE GmbH Schleppeplatz 2 9020 Klag TEL. +43-463-287587 | enfurt am Wörthersee Austria FAX. +43-463-287587-20 |
| CHINA SUBSIDIARY | KOSMEK (CHINA) LTD. Room601, RIVERSIDE PYRAMII Shanghai 200125, China | D No.55, Lane21, Pusan Rd, Pudong TEL. +86-21-54253000 |
| INDIA BRANCH OFFICE | KOSMEK LTD INDIA 4A/Old No:649, Ground Floor, 4th RT Nagar, Bangalore -560032 India | ID cross, MM Layout, Kavalbyrasandra, TEL.+91-9880561695 |
| THAILAND REPRESENTATIVE OFFICE | KOSMEK Thailand Represe 67 Soi 58, RAMA 9 Rd., Phatthana TEL. +66-2-300-5132 | kan, Suanluang, Bangkok 10250, Thailand |
| | | |

KOSMEK LTD.

https://www.kosmek.com/ HEAD OFFICE 1-5, 2-chome, Murotani, Nishi-ku, Kobe-city, Hyogo, Japan 651-2241 TEL.+81-78-991-5162 FAX.+81-78-991-8787

For Further Information on Unlisted Specifications and Sizes, Please call us. Specifications in this Leaflet are Subject to Change without Notice.

