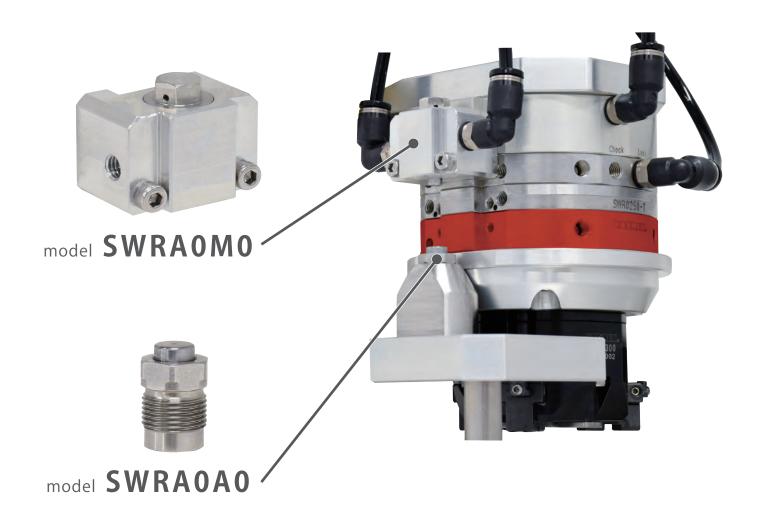
New

Safety Push Valve Fall Prevention Valve



Prevent a Tool Fall during Robot Teaching



Safety Push Valve

Fall Prevention Valve

Model SWRA



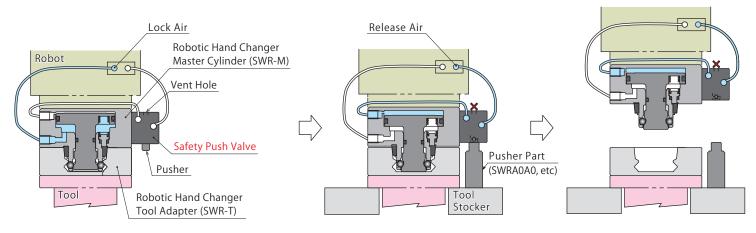
Prevent a Tool Fall during Robot Teaching

Able to mount directly on the Kosmek Robotic Hand Changer (Model SWR), and prevent a tool fall caused by valve operating error.

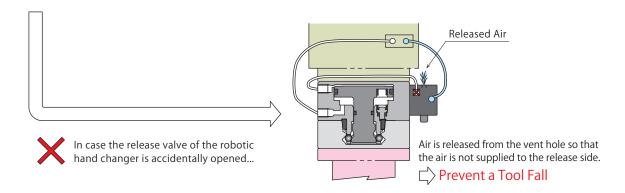
PAT.P.

Prevent a Tool Fall caused by Valve Operating Error

Enables to limit the robotic hand changer to release only at a designated position (tool stocker). Preventing a tool fall caused by valve operating error during robot teaching.



- ① Lock air is supplied. The master cylinder and the tool adapter are connected.
- ② Release air can be supplied only when the pusher is pushed in at the designated position (tool stocker).
- ③ Released until release air supply is stopped.



1



Model No. Indication

SWRA0 □ 0

: Port M5 Thread : Port Rc Thread : Pusher Accessory

M R Α







Specifications

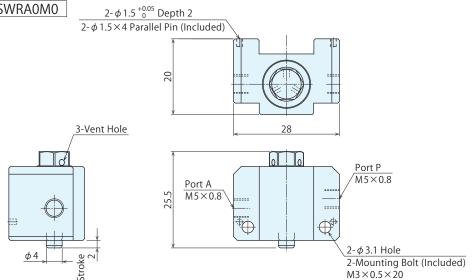
Model No.		SWRA0M0	SWRA0R0
Operating Pressure	MPa	0.35 ~ 0.5	
Withstanding Pressure	MPa	0.75	
Min. Passage Area	mm^2	0.8	
Pusher Stroke	mm	2	
Pusher Pushing Force	N	5	
Operating Temperature	°C	0 ~ 70	
Usable Fluid		Dry Air	
Weight	g	30	60

Corresponding Model No.

Safety Push Valve		
SWRA0M0		
		SWRA0R0

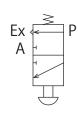
©External Dimensions: Safety Push Valve





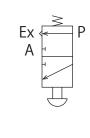
Circuit Symbol

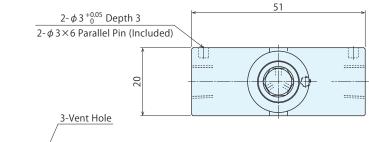
SWRA0M0

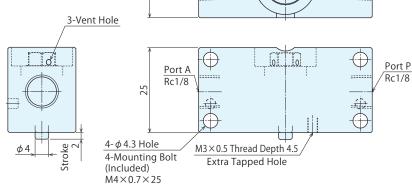


SWRA0R0

SWRA0R0

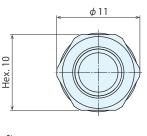


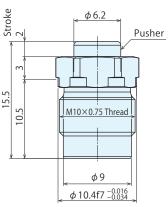




External Dimensions: Pusher Accessory

SWRA0A0





Specifications

Model No.		SWRA0A0
Pusher Stroke	mm	2
Pusher Pushing Force	N	15
Operating Temperature	°C	0~70
Weight	g	6.3

- 1. This drawing shows the pusher projected state.
- 2. When the pusher of Safety Push Valve is projected, air is released from the vent port by supplying air to the port P. Air is supplied to the port A only when Safety Push Valve is pushed. (Air will not be released from the vent port.)
- 3. At the first use, push the pusher by hand and use it with the released state.
- 4. Design the pushing part considering the lifting stroke of SWR.
- 5. It is recommended that the pushing part floats up and down. (Teaching and designing of the pushing part become easier.)



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■ For Further Information on Unlisted Specifications and Sizes, Please call us. Specifications in this Leaflet are Subject to Change without Notice.

