7MPa

Single Acting

New

Swing Clamp / Link Clamp with Action Confirmation

ONLY ONE AIR PORT to confirm clamp and unclamp.





Air Sensing Swing Clamp

Low Pressure: 2.5~7MPa

Swing Clamp with Action Confirmation

Hydraulic Single Action

Model LGV



ONLY ONE AIR PORT to confirm clamp and unclamp.

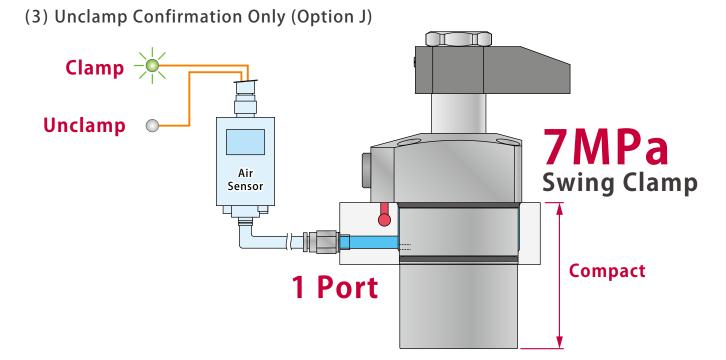
Compact Clamp with Action Confirmation System

PAT.P.



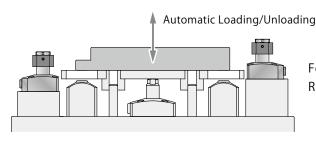
3 Options Available

- (1) Clamp Unclamp Confirmation with One Air Port (Option E)
- (2) Clamp Confirmation Only (Option H)



1

Application Example



For Automation Line Requiring Action Confirmation Clamp

Accessories

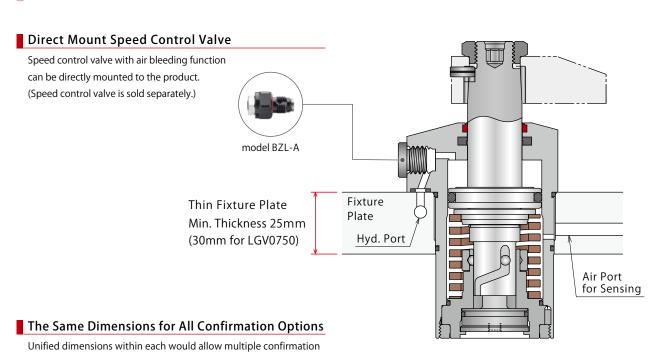
Cautions

Swing Clamp with Action Confirmation

Link Clamp with Action Confirmation

LJV

Features

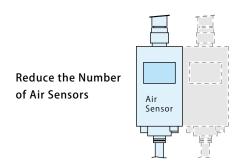


Minimized Number of Sensors

■ ※ In case of option E: Clamp • Unclamp Detection

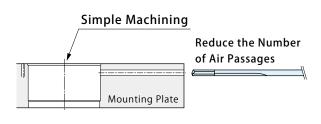
Only one air sensor is required to check both clamping and unclamping actions. (Required to use a two-output air sensor.)

configuration. Common porting simplifies fixture circuit design.



■ Minimized Number of Ports • Simple Machining

Integrating ports for the sensor allows for reducing the number of both ports of a rotary joint and air passages of a fixture plate. Plus, they can simplify the machining of a mounting hole.



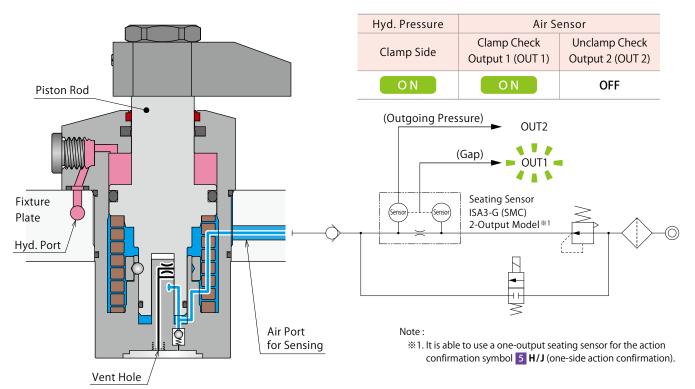
Action Description (Internal Structure)

The figure shows clamp with option **5 E** (Clamp - Unclamp Confirmation)

Clamping Action

The piston rod descends as it swings.

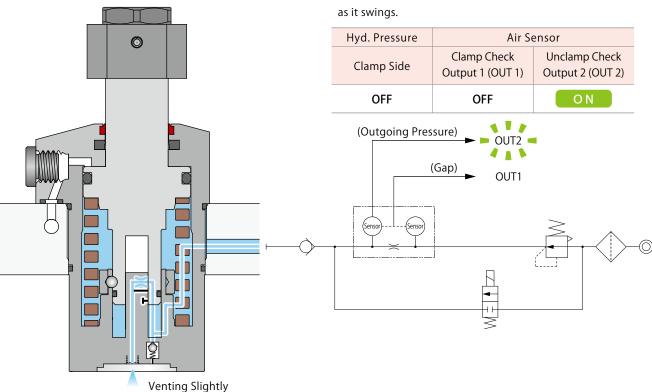
After swing action is completed, the piston rod descends vertically and clamps the workpiece.



Unclamping Action

The piston rod ascends vertically (Clamp Stroke Range).

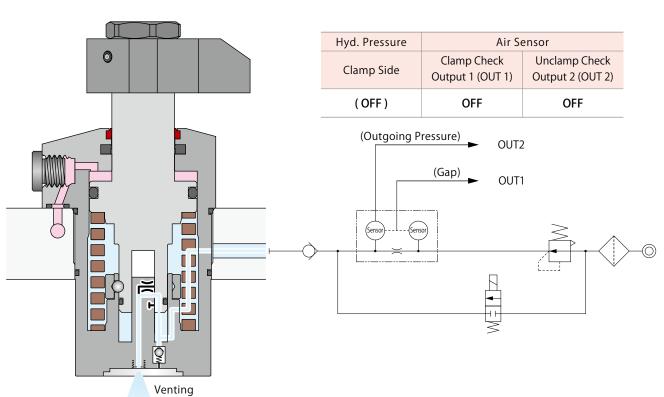
After vertical action is completed, the piston rod ascends as it swings.



During Swing Action

The air sensor turns OFF during swing action.

The detail of sensor ON/OFF range is shown in Air Sensing Chart on P. 6.



The following shows the actions and the air sensor outputs for the action confirmation symbol 5 H/J.

| Action Confirmation | In case of 5 H Clamp Confirmation | In case of 5 J Unclamp Confirmation | | |
|---------------------|-----------------------------------|-------------------------------------|--|--|
| Clamping Action | Air Sensor Output | Air Sensor OFF | | |
| Unclamping Action | Air Sensor (OFF) | Air Sensor Output | | |
| During Swing Action | Air Sensor OFF | Air Sensor OFF Output | | |

[%] When air sensor is ON: No air leakage from the vent hole. When air sensor is OFF: Air releasing from the vent hole.

Accessories

Cautions

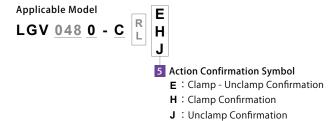
Swing Clamp with Action Confirmation

Link Clamp with Action Confirmation

LJV

Action Confirmation and Air Sensing Chart

Action confirmation can be conducted by detecting differential pressure with an air sensor.

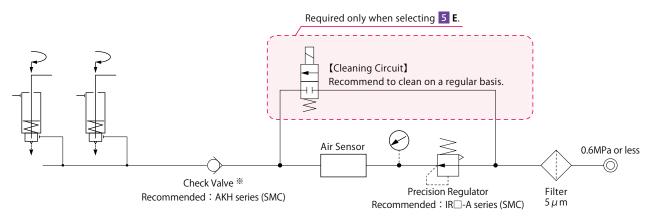


Air Sensor

Recommended Air Sensor

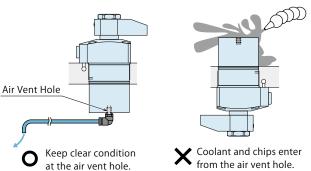
| Action Confirmation Symbol | In case of 5 E | In case of 5 H, J | | |
|----------------------------|--|------------------------|----------------------|--|
| Manufacturer | SMC | SMC | CKD | |
| Name | Digital Seating Switch | Digital Seating Switch | Digital Gap Switch | |
| Model No. | ISA3-G□A, ISA3-G□B | ISA3-G□N, ISA3-G□P | GPS3-E | |
| Air Sensor Requirement | Required to use the 2-output air sensor shown above. | Able to use a genera | 1-output air sensor. | |
| Recommended Air Pressure | 0.1 ~ 0.2MPa (0.15 ~ 0.2MPa when using 4 clamps.) | 0.1 ~ 0.2MPa | | |

- In case of 5 E, the number of clamps connected per air sensor: 2 ~ 4 pcs.
 **Please contact us when using an air sensor for one clamp.
- In case of 5 H and J, there is no limitation for the number of clamps connected per air sensor.
- Please refer to manufacturer's catalog or other documents for the details about the air sensor.
- Please keep supplying air pressure when in use.
- Refer to the drawing below for the air circuit structure.
- Please install a check valve (** part) with low cracking pressure to the detection port of the air sensor.
 (Recommended Check Valve: SMC-made AKH series Cracking Pressure 0.005MPa)

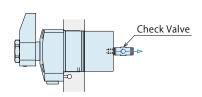


Notes for Design • Installation • Use

 Please keep clear condition at the air vent hole, and prevent coolant and chips from entering the hole. *
 The air sensor can malfunction if the air vent hole is blocked.



* The product will be damaged or malfunction due to internal corrosion. 【Prevention of Contaminants to the Air Vent Hole 】
Coolant and chips can be prevented by setting a check
valve with low cracking pressure. (Recommended Check
Valve: SMC-made AKH series, cracking pressure: 0.005MPa)

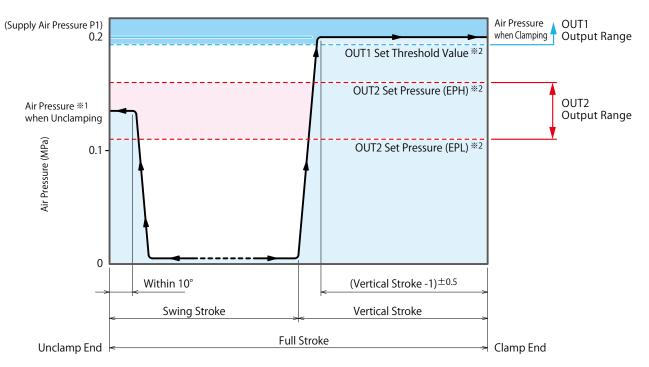


 Keep supplying air pressure to the air port for sensing when in use.

Air Sensing Chart

5 E : Clamp - Unclamp Confirmation

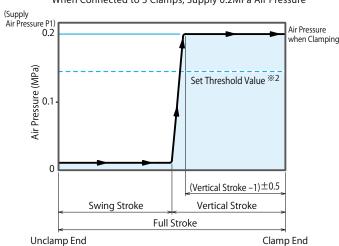
When Connected to 3 Clamps, Supply 0.2MPa Air Pressure



Sensor Setting should be as follows: Detect with OUT1 (Threshold Value) for clamp action confirmation, OUT2 (Pressure Set Value) for unclamp action confirmation. Hysteresis for both OUT1 and OUT2 should be set as 0. Please make sure to use the recommended air sensor.

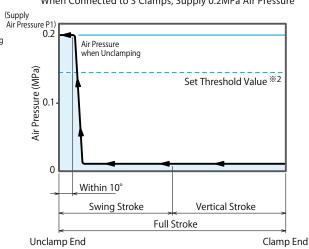
5 H: Clamp Confirmation

When Connected to 3 Clamps, Supply 0.2MPa Air Pressure



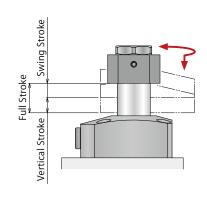
5 J: Unclamp Confirmation

When Connected to 3 Clamps, Supply 0.2MPa Air Pressure



Notes:

- 1. The sensing chart shows the relationship between the stroke and detection circuit air pressure.
- 2. The specifications may vary depending on the air circuit construction. Because it may affect the responsiveness of the air sensor, use the piping tube with outer diameter ϕ 6 (inner diameter ϕ 4) for the outgoing side of the sensor and its length should be as short as possible.
- *1. Pressure when unclamping may vary depending on the condition of air circuit.
- ※2. The location of a signal from air sensor output varies depending on the sensor setting. Set according to using systems. Please refer to manufacturer's instruction manual or other documents for the details about the air sensor.



Clamp

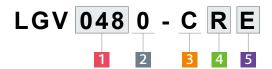
Accessories

Cautions

Action Confirmation

Link Clamp with Action Confirmation

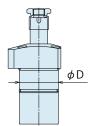
Model No. Indication



1 Body Size

040: φ D=40mm **048**: φ D=48mm **055**: φ D=55mm **065**: φ D=65mm **075**: φ D=75mm

 \times Indicates the cylinder outer diameter (ϕ D).



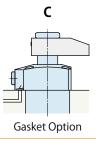
2 Design No.

0 : Revision Number

3 Piping Method

C: Gasket Option (With G Thread Plug)

Speed control valve (BZL-A) is sold separately.
 Please refer to P. 37.



With G Thread Plug Able to Attach BZL-A Speed Control Valve

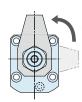
R

4 Swing Direction when Clamping

R : Clockwise

L : Counter-Clockwise





L

Swing Direction when Clamping

5 Action Confirmation Symbol

E : Clamp - Unclamp Confirmation (Both)

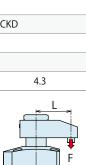
H : Clamp Confirmation OnlyJ : Unclamp Confirmation Only

Specifications

| Mode | l No. | | LGV0400-C□□ | LGV0480-C□□ | LGV0550-C□□ | LGV0650-C□□ | LGV0750-C□□ | | | | |
|--|-------------------|-----------------------|--|---|---|---|---|--|--|--|--|
| Cylind | er Area for Cla | mping cm ² | 5.5 | 7.5 | 10.3 | 14.2 | 21.3 | | | | |
| Cylind | er Inner Diame | eter *1 mm | 32 | 38 | 44 | 52 | 63 | | | | |
| Rod D | iameter **1 | mm | 18 | 22 | 25 | 30 | 35.5 | | | | |
| | oing Force ** | | $F = \frac{P - 1.22}{2.04 + 0.0084 \times L}$ | $F = \frac{P - 1.09}{1.45 + 0.0044 \times L}$ | $F = \frac{P - 1.22}{1.07 + 0.0033 \times L}$ | $F = \frac{P - 1.22}{0.77 + 0.0020 \times L}$ | $F = \frac{P - 0.97}{0.51 + 0.0012 \times L}$ | | | | |
| Cylind | der Capacity | cm ³ | 7.1 | 10.6 | 17 | 25.5 | 45.7 | | | | |
| Full St | troke | mm | 13 | 14 | 16.5 | 18 | 21.5 | | | | |
| Swing | Stroke (90°) |) mm | 6 | 7 | 8.5 | 10 | 11.5 | | | | |
| Vertic | al Stroke | mm | 7 | 7 | 8 | 8 | 10 | | | | |
| Swing | g Angle Accur | racy | | | 90° ±3° | | | | | | |
| Swing (| Complete Position | n Repeatability | ±0.5° | | | | | | | | |
| Retur | n Spring | max. | 0.76 | 0.89 | 1.41 | 2.26 | | | | | |
| Force | kN | min. | 0.45 | 0.45 0.59 0.83 1.08 | | | | | | | |
| | Max. Operating | Pressure MPa | | | 7 | | | | | | |
| Hyd. Pressure | Min. Operating Pr | ressure **3 MPa | | | 2.5 | | | | | | |
| | Withstanding | Pressure MPa | | | 10.5 | | | | | | |
| Recomm | ended Operating A | ir Pressure MPa | | | 0.1 ~ 0.2 | | | | | | |
| Recor | nmended | 5 E **4 | ISA3-G□A, ISA3-G□B (Two-Output Model): Made by SMC ^{※4} | | | | | | | | |
| Air Se | nsor | 5 H/J | ISA3-0 | G□N, ISA3-G□P (One-C | □N, ISA3-G□P (One-Output Model):Made by SMC / GPS3-E: Made by CKD | | | | | | |
| Opera | ating Temper | ature ℃ | | | 0 ~ 70 | | | | | | |
| Usable Fluid General Hydraulic Oil Equivalent to ISO-VG-32 | | | | | | | | | | | |
| Weigl | nt ^{※5} | kg | 1 | 1.3 | 1.8 | 2.8 | 4.3 | | | | |

Notes: %1. Clamping force cannot be calculated from the cylinder inner diameter and rod diameter. Please refer to the clamping force calculation formula and the clamping force curve.

- ※2. F ∶ Clamping Force (kN), P ∶ Supply Hydraulic Pressure (MPa),
 - $\ensuremath{\mathsf{L}}$: Distance between the piston center and the clamping point (mm).
- $\ensuremath{\%3}.$ Minimum pressure to operate the clamp without load.
- #4. The number of clamps connected per air sensor is 2 \sim 4 pcs. Please contact us when using an air sensor for one clamp.
- %5. It shows the weight of single swing clamp including the nut and the taper sleeve.



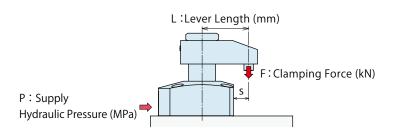
Accessories

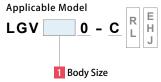
Clamp

Cautions

Link Clamp with Action Confirmation LJV

Clamping Force Curve





(Ex.)

In case of LGV0480: When supply hydraulic pressure P is 5.0MPa and lever length L is 50mm, clamping force becomes about 2.3kN.

Notes:

- 1. Tables and graphs show the relationship between the clamping force (kN) and supply hydraulic pressure (MPa).
- 2. Cylinder force (when L=0) cannot be calculated from the formula of clamping force.
- 3. Lever with a large inertia sometimes does not work depending on supply hydraulic pressure, lever mounting position, etc.
- 4. Values in below charts indicate clamping force when the lever locks a workpiece in horizontal position.
- 5. The clamping force varies depending on the lever length. Set the suitable supply hydraulic pressure based on the lever length.
- 6. Clamping force in the non-usable range may cause deformation, galling and fluid leakage, etc.
- 7. The tables and graphs are only for reference. The exact results should be calculated based on the clamping force calculation formula.
- ※1. F: Clamping Force (kN), P: Supply Hydraulic Pressure (MPa), L: Lever Length (mm).

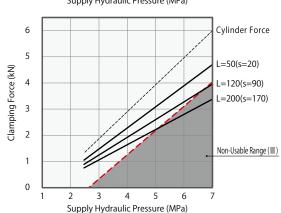
| LGV04 | LGV0400 Clamping Force Calculation Formula *1 (kN) $F = (P-1.22) / (2.04+0.008)$ | | | | | | | | | |
|---------------|--|------|------|------|---------|----------|--------|------------|------------|------------|
| Hydraulic | Cylinder Force | | | Cla | mping | Force (l | kN) No | n-Usable F | Range () | Max. Lever |
| Pressure | (kN) | | | Lev | er Lend | gth L (m | nm) | | | Length (L) |
| (MPa) | | L=40 | L=50 | L=60 | L=70 | L=80 | L=100 | L=120 | L=150 | (mm) |
| 7 | 3.2 | 2.4 | 2.4 | 2.3 | 2.2 | | | | | 71 |
| 6.5 | 2.9 | 2.2 | 2.2 | 2.1 | 2.0 | 2.0 | | | | 81 |
| 6 | 2.6 | 2.0 | 1.9 | 1.9 | 1.8 | 1.8 | | | | 92 |
| 5.5 | 2.3 | 1.8 | 1.7 | 1.7 | 1.6 | 1.6 | 1.5 | | | 108 |
| 5 | 2.1 | 1.6 | 1.5 | 1.5 | 1.4 | 1.4 | 1.3 | 1.2 | | 130 |
| 4.5 | 1.8 | 1.4 | 1.3 | 1.3 | 1.3 | 1.2 | 1.1 | 1.1 | 1.0 | 150 |
| 4 | 1.5 | 1.2 | 1.1 | 1.1 | 1.1 | 1.0 | 1.0 | 0.9 | 0.8 | 150 |
| 3.5 | 1.2 | 1.0 | 0.9 | 0.9 | 0.9 | 0.8 | 0.8 | 0.8 | 0.7 | 150 |
| 3 | 1.0 | 0.8 | 0.7 | 0.7 | 0.7 | 0.7 | 0.6 | 0.6 | 0.5 | 150 |
| 2.5 | 0.7 | 0.5 | 0.5 | 0.5 | 0.5 | 0.5 | 0.4 | 0.4 | 0.4 | 150 |
| Max. Operatir | ng Pressure (MPa) | 7.0 | 7.0 | 7.0 | 7.0 | 6.6 | 5.7 | 5.2 | 4.7 | |

| | 3.5 I | | | | | | | 1 |
|---------------------|-------|---|----------|----------|-----------|---------|-----|----------------------|
| | | | | | | | , | Cylinder Force |
| | 3.0 | | | | | | | |
| KN N | 2.5 | | | | | | | L=36.5(s=14) |
| rce (| 2.0 | | | | | | / / | L=90(s=67.5) |
| g Fo | | | | | | | | L=150(s=127.5) |
| pind | 1.5 | | | | | | | |
| Clamping Force (kN) | 1.0 | | /. | | | | | Non-Usable Range (■) |
| | 0.5 | | | | | | | |
| | 0 | | | | | | | |
| | • | l | 2 | 3 | 4 | 5 | 6 | 7 |
| | | 9 | Supply I | Hydrauli | ic Pressi | ure (MP | a) | |
| | | | | | | | | |

| LGV04 | 180 | Clamping | pping Force Calculation Formula $\frac{1}{N}$ (kN) $F = (P-1.09) / (1.45+0.004)$ | | | | | | | | 44×L) |
|---------------|-----------|----------|--|------|------|---------|----------|---------|------------|------------|------------|
| Hydraulic | Cylind | er Force | | | Cla | amping | Force (l | (N) Noi | n-Usable F | Range () | Max. Lever |
| Pressure | (kN) | | | | Le | ver Len | gth L (m | m) | | | Length (L) |
| (MPa) | | | L=50 | L=60 | L=70 | L=80 | L=100 | L=120 | L=140 | L=150 | (mm) |
| 7 | 4 | 4.4 | 3.5 | 3.5 | 3.4 | 3.3 | | | | | 89 |
| 6.5 | 4 | 4.0 | 3.2 | 3.2 | 3.1 | 3.0 | 2.9 | | | | 100 |
| 6 | | 3.7 | 2.9 | 2.9 | 2.8 | 2.7 | 2.6 | | | | 114 |
| 5.5 | 3 | 3.3 | 2.6 | 2.6 | 2.5 | 2.5 | 2.3 | 2.2 | | | 132 |
| 5 | | 2.9 | 2.3 | 2.3 | 2.2 | 2.2 | 2.1 | 2.0 | 1.9 | 1.9 | 150 |
| 4.5 | | 2.5 | 2.0 | 2.0 | 1.9 | 1.9 | 1.8 | 1.7 | 1.7 | 1.6 | 150 |
| 4 | | 2.2 | 1.7 | 1.7 | 1.7 | 1.6 | 1.5 | 1.5 | 1.4 | 1.4 | 150 |
| 3.5 | | 1.8 | 1.4 | 1.4 | 1.4 | 1.3 | 1.3 | 1.2 | 1.2 | 1.1 | 150 |
| 3 | | 1.4 | 1.1 | 1.1 | 1.1 | 1.1 | 1.0 | 1.0 | 0.9 | 0.9 | 150 |
| 2.5 | | 1.0 | 0.8 | 0.8 | 0.8 | 0.8 | 0.8 | 0.7 | 0.7 | 0.7 | 150 |
| Max. Operatir | ng Pressu | re (MPa) | 7.0 | 7.0 | 7.0 | 7.0 | 6.5 | 5.8 | 5.3 | 5.1 | |

| | 5 | |
|---------------------|---|---------------------------------|
| | 4 | Cylinder Force |
| 9 | 4 | L=42(s=16.5) |
| e (K | 3 | L=100(s=74.5) |
| -orc | J | L=150(s=124.5) |
| Clamping Force (kN) | 2 | Non-Usable Range (■) |
| O | 1 | Troit Gaute range (=) |
| | 0 | |
| | | 1 2 3 4 5 6 7 |
| | | Supply Hydraulic Pressure (MPa) |

| LGV05 | LGV0550 Clamping Force Calculation Formula $*^{1}$ (kN) $F = (P-1.22) / (1.07+0.003)$ | | | | | | | | | 33×L) |
|---------------|--|------|------|------|----------|----------|---------|------------|-------------|------------|
| Hydraulic | Cylinder Force | | | Cla | amping | Force (F | (N) Noi | n-Usable F | Range (III) | Max. Lever |
| Pressure | (kN) | | | Le | ver Leng | gth L (m | ım) | | | Length (L) |
| (MPa) | | L=50 | L=60 | L=80 | L=100 | L=120 | L=140 | L=160 | L=200 | (mm) |
| 7 | 5.9 | 4.7 | 4.6 | 4.3 | 4.1 | | | | | 102 |
| 6.5 | 5.4 | 4.3 | 4.2 | 4.0 | 3.8 | | | | | 115 |
| 6 | 4.9 | 3.9 | 3.8 | 3.6 | 3.4 | 3.3 | | | | 132 |
| 5.5 | 4.4 | 3.5 | 3.4 | 3.2 | 3.1 | 2.9 | 2.8 | | | 156 |
| 5 | 3.9 | 3.1 | 3.0 | 2.8 | 2.7 | 2.6 | 2.5 | 2.4 | | 188 |
| 4.5 | 3.3 | 2.7 | 2.6 | 2.5 | 2.3 | 2.2 | 2.1 | 2.1 | 1.9 | 200 |
| 4 | 2.8 | 2.3 | 2.2 | 2.1 | 2.0 | 1.9 | 1.8 | 1.7 | 1.6 | 200 |
| 3.5 | 2.3 | 1.9 | 1.8 | 1.7 | 1.6 | 1.6 | 1.5 | 1.4 | 1.3 | 200 |
| 3 | 1.8 | 1.4 | 1.4 | 1.3 | 1.3 | 1.2 | 1.2 | 1.1 | 1.0 | 200 |
| 2.5 | 1.3 | 1.0 | 1.0 | 1.0 | 0.9 | 0.9 | 0.8 | 0.8 | 0.7 | 200 |
| Max. Operatir | ng Pressure (MPa) | 7.0 | 7.0 | 7.0 | 7.0 | 6.4 | 5.8 | 5.4 | 4.9 | |



Clamp

Accessories

Cautions

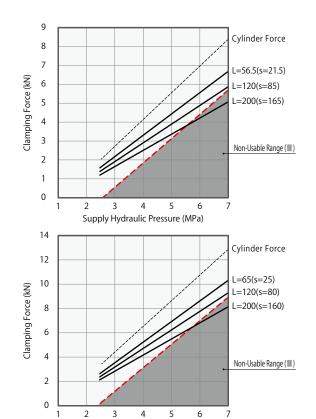
Swing Clamp with Action Confirmation

Link Clamp with Action Confirmation

LJV

| Hydraulic | Cylinder Force | | | Cla | amping | Force (I | (N) Noi | n-Usable f | Range (III) | Max. Lever |
|---------------|-------------------|------|------|------|----------|----------|---------|------------|-------------|------------|
| Pressure | (kN) | | | Le | ver Lend | gth L (m | ım) | | | Length (L) |
| (MPa) | | L=50 | L=60 | L=80 | L=100 | L=120 | L=140 | L=160 | L=200 | (mm) |
| 7 | 8.3 | 6.6 | 6.5 | 6.2 | 6.0 | 5.7 | | | | 126 |
| 6.5 | 7.6 | 6.1 | 5.9 | 5.7 | 5.4 | 5.2 | 5.0 | | | 142 |
| 6 | 6.9 | 5.5 | 5.4 | 5.1 | 4.9 | 4.7 | 4.6 | 4.4 | | 163 |
| 5.5 | 6.2 | 4.9 | 4.8 | 4.6 | 4.4 | 4.2 | 4.1 | 3.9 | | 191 |
| 5 | 5.5 | 4.3 | 4.3 | 4.1 | 3.9 | 3.7 | 3.6 | 3.5 | 3.2 | 200 |
| 4.5 | 4.8 | 3.8 | 3.7 | 3.5 | 3.4 | 3.3 | 3.1 | 3.0 | 2.8 | 200 |
| 4 | 4.1 | 3.2 | 3.1 | 3.0 | 2.9 | 2.8 | 2.7 | 2.6 | 2.4 | 200 |
| 3.5 | 3.4 | 2.6 | 2.6 | 2.5 | 2.4 | 2.3 | 2.2 | 2.1 | 2.0 | 200 |
| 3 | 2.6 | 2.1 | 2.0 | 1.9 | 1.8 | 1.8 | 1.7 | 1.6 | 1.5 | 200 |
| 2.5 | 1.9 | 1.5 | 1.4 | 1.4 | 1.3 | 1.3 | 1.2 | 1.2 | 1.1 | 200 |
| Max. Operatir | ng Pressure (MPa) | 7.0 | 7.0 | 7.0 | 7.0 | 7.0 | 6.6 | 6.1 | 5.4 | |

| LGV07 | LGV0750 Clamping Force Calculation Formula $\frac{1}{2}$ (kN) $F = (P-0.97) / (0.51+0.001)$ | | | | | | | | | | 12×L) |
|-----------------------|--|---------|------|------|------|--------------------|-------|-------|------------|-----------|--------------------------|
| Hydraulic Pressure | Cylinde (k | | | | | amping ver Lend | | | n-Usable F | Range (■) | Max. Lever Length (L) |
| (MPa) | | | L=50 | L=60 | L=80 | L=100 | L=120 | L=140 | L=160 | L=200 | (mm) |
| 7 | 12 | .8 | 10.6 | 10.4 | 10.0 | 9.6 | 9.2 | | | | 134 |
| 6.5 | 11 | .7 | 9.7 | 9.5 | 9.1 | 8.8 | 8.5 | 8.2 | | | 150 |
| 6 | 10 | .7 | 8.8 | 8.6 | 8.3 | 8.0 | 7.7 | 7.4 | 7.2 | | 171 |
| 5.5 | 9 | .6 | 8.0 | 7.8 | 7.5 | 7.2 | 6.9 | 6.7 | 6.5 | 6.0 | 199 |
| 5 | 8 | .6 | 7.1 | 6.9 | 6.7 | 6.4 | 6.2 | 5.9 | 5.7 | 5.4 | 200 |
| 4.5 | 7 | .5 | 6.2 | 6.1 | 5.8 | 5.6 | 5.4 | 5.2 | 5.0 | 4.7 | 200 |
| 4 | 6 | .4 | 5.3 | 5.2 | 5.0 | 4.8 | 4.6 | 4.5 | 4.3 | 4.0 | 200 |
| 3.5 | 5 | .4 | 4.4 | 4.4 | 4.2 | 4.0 | 3.9 | 3.7 | 3.6 | 3.4 | 200 |
| 3 | 4 | .3 | 3.6 | 3.5 | 3.4 | 3.2 | 3.1 | 3.0 | 2.9 | 2.7 | 200 |
| 2.5 | 3 | .2 | 2.7 | 2.6 | 2.5 | 2.4 | 2.3 | 2.3 | 2.2 | 2.0 | 200 |
| Max. Operatir | ng Pressur | e (MPa) | 7.0 | 7.0 | 7.0 | 7.0 | 7.0 | 6.8 | 6.3 | 5.5 | |



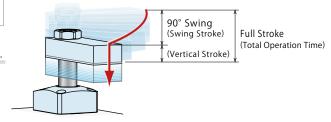
Supply Hydraulic Pressure (MPa)

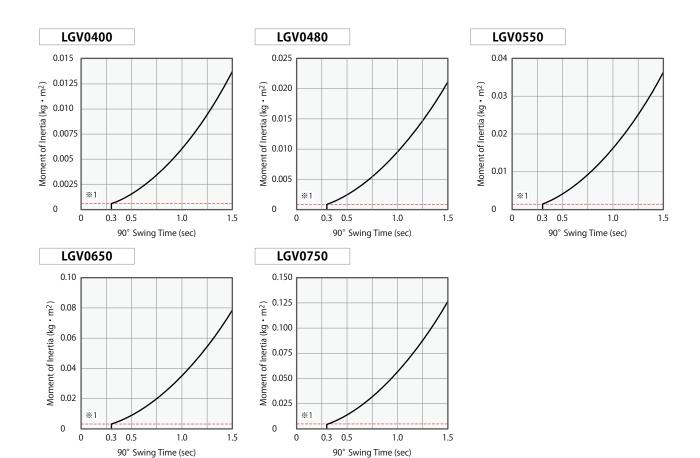
Allowable Swing Time Graph

Adjustment of Swing Time

The graph shows allowable swing time against the moment of inertia of a lever. An operation time should be longer than the operation time shown in the graph.

Excessive action speed can reduce stopping accuracy and damage internal components.





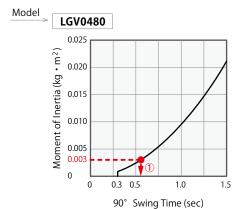
Notes:

- \times 1. It shows the moment of inertia with material lever (LZ \square -LE2).
 - 1. The graph shows the 90° swing time in regard to the moment of inertia of lever.
- 2. Operation time is approximately twice the 90° swing time. Use the calculation formula of the total operation time on the next page to calculate the detailed time.
- $3. \ \ Lever\ with\ a\ large\ inertia\ sometimes\ does\ not\ work\ depending\ on\ supply\ hydraulic\ pressure,\ oil\ flow,\ lever\ mounting\ position,\ etc.$
- 4. Please adjust the 90° swing time against the moment of inertia of lever to be longer than the indicated time in the above graphs.
- 5. Excessive swing speed can reduce stopping accuracy and damage the internal parts.
- 6. The clamping force varies depending on the lever length. Refer to the clamping force curve and set the suitable supply hydraulic pressure based on the lever length.
- 7. When a clamp is mounted horizontally, a lever may be accelerated by its own weight. The swing time may become faster than the allowable time shown above, and this results in a damage to the clamp. In this case, use meter-out flow control valve for speed adjustment.
- 8. For any moment of inertia of a lever, the minimum unclamping time should be 0.3 sec.
- 9. Please contact us if operational conditions differ from those shown on the graphs.

(How to read the allowable operation time graph)
In case of LGV0480

The moment of inertia of a lever: 0.003kg·m²
• 90° Swing Time : About 0.56 sec or more
• Total Operation Time : About 1.12 sec or more

- 1. The total operation time on the graph represents the allowable operation time when fully stroked.
- 2. Calculate the operation time with the formula.



Clamp

Accessories

Cautions

Swing Clamp with Action Confirmation

Link Clamp with
Action Confirmation

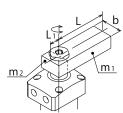
How to Calculate the Moment of Inertia (Estimated)

I: Moment of Inertia (kg·m²)

L,L₁,L₂,K,b:Length (m)

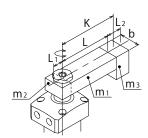
 m,m_1,m_2,m_3 : Weight (kg)

① For a rectangular plate (cuboid), the rotating shaft is vertically on one side of the plate.



$$I = m_1 \frac{4L^2 + b^2}{12} + m_2 \frac{4L_1^2 + b^2}{12}$$

② Load is applied on the lever front end.



$$I = m_1 \frac{4L^2 + b^2}{12} + m_2 \frac{4L_1^2 + b^2}{12} + m_3K^2 + m_3 \frac{L_2^2 + b^2}{12}$$

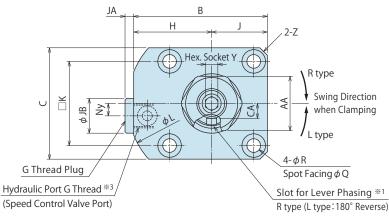
Calculation Formula of Total Operation Time

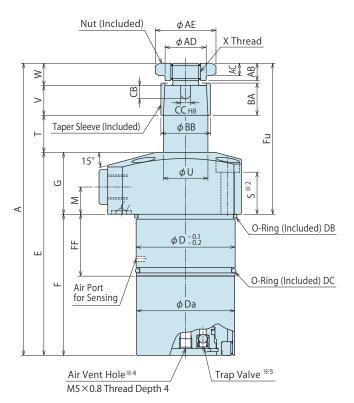
Total Operation Time (sec) = 90° Swing Time (sec)

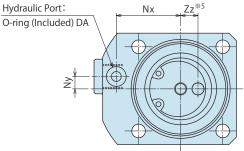
Full Stroke (mm)
Swing Stroke (mm)

External Dimensions

(The dimensions are the same for 5 Action Confirmation Symbol E / H / J.) **The drawing shows the unclamped state of LGV-CR.



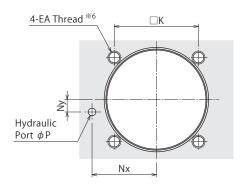




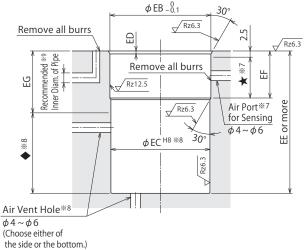
Notes:

- %1. The slot for lever phasing faces the port side when clamped.
- **2. Mounting bolts are not provided with the product. Please prepare them according to the mounting height referring to dimension 'S'.
- *3. Speed control valve is sold separately. Please refer to P.37 for detail.
- **4. Please keep clear condition at the air vent hole, and prevent coolant and chips from entering the hole. If exposed to coolant, use the thread and install piping, etc. to prevent contamination, but do not block the air vent hole.
- %5. Please keep clear condition at the trap valve. Phasing is not as illustrated in the drawing.

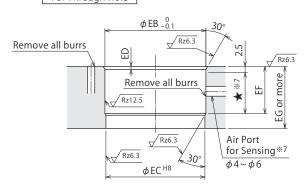
Machining Dimensions of Mounting Area



For Blind Hole



For Through Hole



Notes:

- ※6. EA tapping depth of the mounting bolt should be decided according to the mounting height referring to dimensions 'S'.
- %7. Prepare the air port for sensing within the \bigstar area.
- %8. Prepare the vent hole on the side or the bottom. When preparing on the side, it should be within the \spadesuit area. When preparing on the bottom, it should be within ϕ EC.

JB

Hydraulic Port: G Thread

Rcmd. Inner Diam. of Pipe **9

O-Ring

DA

DB

DC

14

G1/8

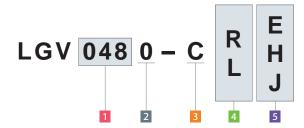
OR NBR-90 P5-N(1BP5)

 $38 \times 1.5 \; \text{(Inner Diam.} \times \; \text{Wire Diam.)}$

AS568-028(70°)

φ6

Model No. Indication



(Format Example: LGV0480-CRE, LGV0750-CLJ)

1 Body Size

2 Design No.

3 Piping Method

4 Swing Direction when Clamping

5 Action Confirmation Symbol

Clamp

Accessories

Cautions

Swing Clamp with Action Confirmation

Link Clamp with Action Confirmation

(mm)

External Dimensions and Machining Dimensions of Mounting

| Model No. | LGV0400-C□□ | LGV0480-C□□ | LGV0550-C□□ | LGV0650-C□□ | LGV0750-C□□ |
|---------------------|-------------|-------------|----------------------|---------------------|----------------------|
| Full Stroke | 13 | 14 | 16.5 | 18 | 21.5 |
| Swing Stroke (90°) | 6 | 7 | 8.5 | 10 | 11.5 |
| Vertical Stroke | 7 | 7 | 8 | 8 | 10 |
| Α | 118 | 128 | 145.5 | 153.5 | 182.5 |
| В | 54 | 61 | 69 | 81 | 92 |
| С | 45 | 51 | 60 | 70 | 80 |
| D | 40 | 48 | 55 | 65 | 75 |
| Da | 39.6 | 47.6 | 54.6 | 64.6 | 74.6 |
| E | 82 | 87 | 95 | 101.5 | 119 |
| F | 57 | 59 | 67 | 71.5 | 82 |
| FF | 25 | 25 | 25 | 25 | 30 |
| Fu | 61 | 69 | 78.5 | 82 | 100.5 |
| G | 25 | 28 | 28 | 30 | 37 |
| Н | 31.5 | 35.5 | 39 | 46 | 52 |
| J | 22.5 | 25.5 | 30 | 35 | 40 |
| K | 34 | 40 | 47 | 55 | 63 |
| L | 68 | 73 | 80 | 94 | 106 |
| M | 11 | 13 | 12 | 13 | 16 |
| Nx | 26 | 30 | 33.5 | 39.5 | 45 |
| | 5 | 0 | 0 | 0 | 0 |
| Ny P | 3 | 3 | 3 | 5 | 5 |
| | | | | | |
| Q | 9.5 | 9.5 | 11 | 11 | 14 |
| R | 5.5 | 5.5 | 6.8 | 6.8 | 9 |
| <u>S</u> | 17 | 18.5 | 17 | 18 | 22 |
| T | 15 | 16 | 18.5 | 20 | 23.5 |
| U | 18 | 22 | 25 | 30 | 35.5 |
| V | 12 | 14 | 20 | 20 | 26 |
| W | 9 | 11 | 12 | 12 | 14 |
| X (Nominal × Pitch) | M12×1.5 | M16×1.5 | M18×1.5 | M22×1.5 | M28×1.5 |
| Υ | 5 | 6 | 8 | 10 | 10 |
| Z (Chamfer) | C3 | C3 | (φ80) | (φ94) | (φ106) |
| Zz | 7 | 8 | 8 | 10 | 10 |
| AA | 22 | 24 | 30 | 36 | 41 |
| AB | 7 | 9 | 10 | 10 | 12 |
| AC | 5 | 6 | 7 | 7 | 8 |
| AD | 16.6 | 20.5 | 22.9 | 27.9 | 32.8 |
| AE | 24.5 | 26.5 | 33 | 40 | 45 |
| BA | 13 | 15 | 21 | 21 | 27 |
| BB | 20 | 25 | 28 | 34 | 40 |
| CA | 6 | 8 | 9 | 11 | 14 |
| СВ | 5.3 | 5.3 | 5.3 | 7.5 | 7.5 |
| CC | 4 +0.018 | 4 +0.018 | 4 +0.018 | 6 ^{+0.018} | 6+0.018 |
| A (Nominal × Pitch) | M5×0.8 | M5×0.8 | M6×1 | M6×1 | M8×1.25 |
| EB | 40.8 | 49 | 56 | 66 | 76 |
| EC | 40 +0.039 | 48 +0.039 | 55 ^{+0.046} | 65 +0.046 | 75 ^{+0.046} |
| ED | 1 | 1 | 1 | 1 | 1.5 |
| EE | 57.5 | 59.5 | 67.5 | 72 | 82.5 |
| EF | 19 | 19 | 19 | 19 | 24 |
| | | | | | |
| EG | 25 | 25 | 25 | 25 | 30 |

14

G1/8

OR NBR-90 P5-N(1BP5)

AS568-034(70°)

AS568-033(70°)

φ6

19

G1/4

OR NBR-90 P7-N(1BP7)

AS568-037(70°)

AS568-036(70°)

 ϕ 8

19

G1/4

OR NBR-90 P7-N(1BP7)

AS568-040(70°)

AS568-039(70°)

φ8

14

G1/8

OR NBR-90 P5-N(1BP5)

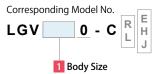
AS568-031(70°)

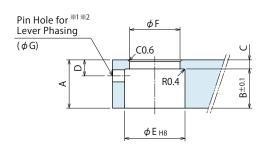
AS568-031(70°)

φ6

Taper Lock Lever Design Dimensions

 $\ensuremath{\ensuremath{\%}}$ Reference for designing taper lock swing lever.





| Corresponding Model No. **3 | LGV0400 | LGV0480 | LGV0550 | LGV0650 | LGV0750 |
|--------------------------------|-----------------------|------------|-----------|-----------|------------------------------------|
| Α | 16 | 19 | 25 | 25 | 32 |
| В | 13 | 15 | 21 | 21 | 27 |
| С | 3 | 4 | 4 | 4 | 5 |
| D | 5.3 | 6.3 | 6.3 | 7.5 | 8.5 |
| E | 20 +0.033 | 25 +0.033 | 28 +0.033 | 34 +0.039 | 40 +0.039 |
| F | 16.7 ^{+0.15} | 20.6 +0.15 | 23 +0.15 | 28 +0.15 | 32.9 ^{+0.20} ₀ |
| G | 4 | 4 | 4 | 6 | 6 |

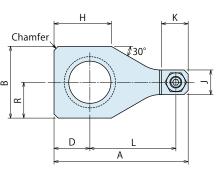
Notes:

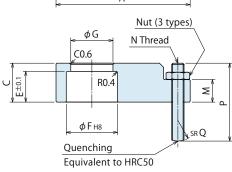
- 1. Swing lever should be designed with its length according to performance curve.
- 2. If the swing lever is not in accordance with the dimensions shown above, performance may be degraded and damage can occur.
- *1. The pin hole (ϕ G) for determining the lever phase should be added, if necessary. This is not required if phasing is not needed.
- ※2. Phasing pin is not included. Prepare it separately.

(mm)

C Accessory: Material Swing Lever for Taper Lock Option

 $\begin{array}{c|c} \text{Model No. Indication} \\ \textbf{LZ} & \textbf{040} \\ \hline & \text{Size (Refer} \\ \text{to the table.)} \end{array} & \textbf{0} & \textbf{-} & \textbf{LE1} \\ \hline & \text{Design No.} \\ \text{(Revision Number)} \end{array}$





| Model No. | LZ0400-LE1 | LZ0481-LE1**3 | LZ0550-LE1 | LZ0650-LE1 | LZ0750-LE1 |
|-------------------------|-----------------------|----------------------|------------|----------------------|------------|
| Corresponding Model No. | LGV0400 | LGV0480 | LGV0550 | LGV0650 | LGV0750 |
| Α | 56.5 | 65.5 | 77 | 91.5 | 105 |
| В | 28 | 35 | 38 | 50 | 58 |
| С | 16 | 19 | 25 | 25 | 32 |
| D | 14 | 17.5 | 19 | 25 | 29 |
| Е | 13 | 15 | 21 | 21 | 27 |
| F | 20 +0.033 | 25 ^{+0.033} | 28 +0.033 | 34 ^{+0.039} | 40 +0.039 |
| G | 16.7 ^{+0.15} | 20.6 +0.15 | 23 +0.15 | 28 +0.15 | 32.9 +0.20 |
| Н | 24 | 28 | 34 | 40 | 47 |
| J | 12 | 12 | 17 | 19 | 22 |
| K | 13 | 13 | 17 | 22 | 25 |
| L | 36.5 | 42 | 50 | 56.5 | 65 |
| М | 10 | 11 | 15 | 13 | 16 |
| N | M6×1 | M6×1 | M8×1.25 | M10×1.5 | M12×1.75 |
| P | 33 | 38 | 42 | 47 | 52 |
| Q | 10 | 10 | 15 | 20 | 30 |
| R | 14 | 17.5 | 19 | 25 | 29 |
| Chamfer | C1 | C1 | C1 | C3 | C4 |

Notes:

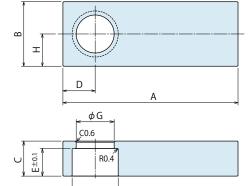
- 1. Material: S45C Surface Finishing: Alkaline Blackening
- 2. When determining the phase, refer to taper lock lever design dimensions for each model for the additional machining.
- %3. Only for LZ048, the design number is 1.

Accessory: Material Swing Lever for Taper Lock Option

Model No. Indication







 ϕ F нв

| | | | | | (mm) |
|-------------------------|-----------------------|---------------|------------|------------|------------------------------------|
| Model No. | LZ0400-LE2 | LZ0481-LE2**4 | LZ0550-LE2 | LZ0650-LE2 | LZ0750-LE2 |
| Corresponding Model No. | LGV0400 | LGV0480 | LGV0550 | LGV0650 | LGV0750 |
| Α | 90 | 95 | 100 | 120 | 125 |
| В | 28 | 35 | 38 | 50 | 58 |
| C | 16 | 19 | 25 | 25 | 32 |
| D | 14 | 17.5 | 5 19 25 | | 29 |
| Е | 13 | 15 | 21 | 21 | 27 |
| F | 20 +0.033 | 25 +0.033 | 28 +0.033 | 34 +0.039 | 40 +0.039 |
| G | 16.7 ^{+0.15} | 20.6 +0.15 | 23 +0.15 | 28 +0.15 | 32.9 ^{+0.20} ₀ |
| Н | 14 | 17.5 | 19 | 25 | 29 |

Notes:

- 1. Material: S45C Surface Finishing: Alkaline Blackening
- 2. If necessary, the front end should be additionally machined.
- 3. When determining the phase, refer to taper lock lever design dimensions for each model for the additional machining.
- $\#4.\,$ Only for LZ048, the design number is 1.

Clamp

Accessories

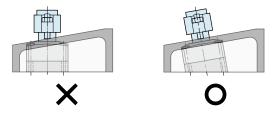
Cautions

Swing Clamp with Action Confirmation

Link Clamp with Action Confirmation

Cautions

- Notes for Design
- 1) Check Specifications
- Please use each product according to the specifications.
- 2) Notes for Circuit Design
- Please read "Notes on Hydraulic Cylinder Speed Control Unit" for proper hydraulic circuit design. Improper circuit design may lead to malfunctions and damages. (Refer to P.40.)
- 3) Swing lever should be designed to make the moment of inertia small.
- Large moment of inertia will degrade the lever's stopping accuracy and cause breakage of the clamp.
 Additionally, the clamp may not function, depending on supplied hydraulic pressure and lever mounting position.
- Set the allowable operation time after the moment of inertia is calculated.
 Refer to "Allowable Swing Time Graph" and make sure to operate a clamp within the allowable operation time.
- 4) Protect the exposed area of the piston rod when using on a welding fixture
- If spatter attaches to the sliding surface it could lead to malfunction and fluid leakage.
- 5) When clamping on a sloped surface of the workpiece
- Make sure the clamping surface and the mounting surface of the clamp are parallel.



- 6) Vent Hole and Check Valve of Air Sensor
- When using an air sensor, make sure to check the Notes for Design Installation • Use on P.5.



Clamp

Accessories

Cautions

Link Clamp with

Action Confirmation

LJV

Installation Notes

- 1) Check the Usable Fluid
- Please use the appropriate fluid by referring to the Hydraulic Fluid List (P.39).
- 2) Swing Speed Adjustment
- Adjust the speed following "Allowable Swing Time Graph".
 If the clamp operates too fast, the parts will be worn out, leading to premature damage and ultimately complete equipment failure.
- Please make sure to release air from the circuit before adjusting speed. It will be difficult to adjust the speed accurately with air mixed in the circuit.
- Turn the speed control valve gradually from the low-speed side (small flow) to the high-speed side (large flow) to adjust the speed.
- 3) Installation of the Product
- When mounting the clamp, use hexagonal socket bolts as multiple bolt holes for mounting (with tensile strength of 12.9) and tighten them with the torque shown in the table below. Tightening with greater torque than recommended can dent the seating surface or break the bolt.

| Model No. | Mounting Bolt Size | Tightening Torque (N⋅m) |
|-------------|--------------------|-------------------------|
| LGV0400-C□□ | M5×0.8 | 6.3 |
| LGV0480-C□□ | M5×0.8 | 6.3 |
| LGV0550-C□□ | M6×1 | 10 |
| LGV0650-C□□ | M6×1 | 10 |
| LGV0750-C□□ | M8×1.25 | 25 |

- 4) Installation / Removal of the Swing Lever
- Oil or debris on the tightened part of the lever or piston rod may cause the rod to loosen. Please clean them thoroughly before installation.
- Tighten the tightening bolt of swing lever with the torque shown below.
 Tightening with greater torque than recommended can damage the bolt and lever tightening function.

| Model No. | Mounting Bolt Size | Tightening Torque (N⋅m) |
|-------------|--------------------|-------------------------|
| LGV0400-C□□ | M12×1.5 | 24 ~ 29 |
| LGV0480-C□□ | M16×1.5 | 37 ~ 45 |
| LGV0550-C□□ | M18×1.5 | 59 ~ 71 |
| LGV0650-C□□ | M22×1.5 | 93 ~ 112 |
| LGV0750-C□□ | M28×1.5 | 147 ~ 177 |

- 5) Checking Looseness and Retightening
- At the beginning of the product installation, bolts may be tightened lightly. Check the looseness and re-tighten as required.

• Installation Notes

• Hydraulic Fluid List • Notes on Hydraulic Cylinder Speed Control Circuit • Maintenance/Inspection • Warranty

* Please refer to P.39 for common cautions.

Notes on Handling

Air Sensing Link Clamp

Low Pressure: 2.5~7MPa

Link Clamp with Action Confirmation

Hydraulic Single Action

Model LJV



ONLY ONE AIR PORT to confirm clamp and unclamp.

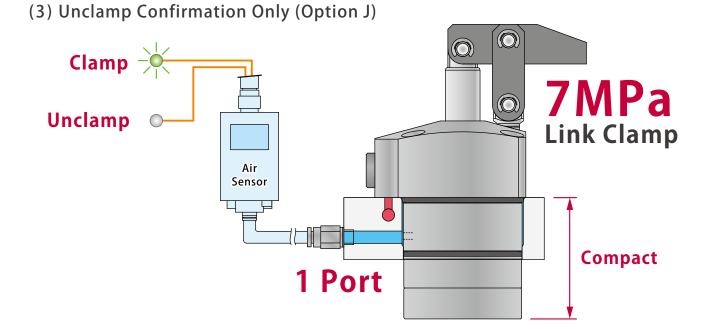
Compact Clamp with Action Confirmation System

PAT.P.

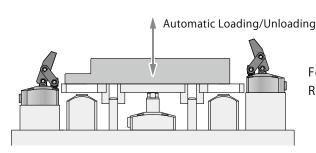


3 Options Available

- (1) Clamp Unclamp Confirmation with One Air Port (Option E)
- (2) Clamp Confirmation Only (Option H)



Application Example



For Automation Line Requiring Action Confirmation Clamp

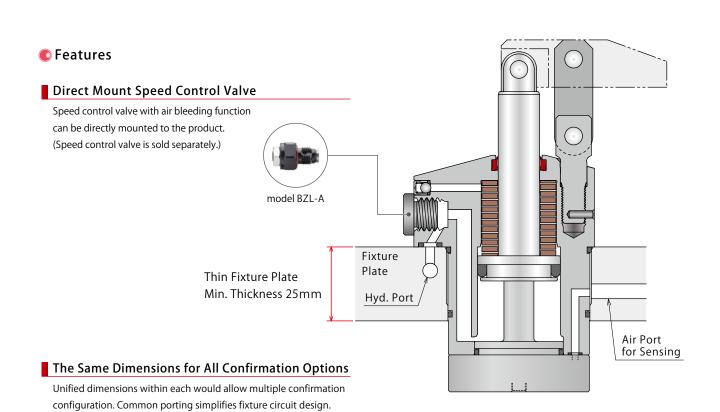
Accessories

Cautions

Swing Clamp with Action Confirmation

LGV

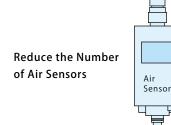
Link Clamp with Action Confirmation



Minimized Number of Sensors

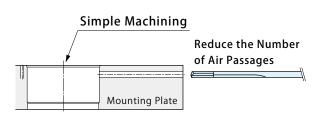
※ In case of option E : Clamp • Unclamp Detection

Only one air sensor is required to check both clamping and unclamping actions. (Required to use a two-output air sensor.)



Minimized Number of Ports • Simple Machining

Integrating ports for the sensor allows for reducing the number of both ports of a rotary joint and air passages of a fixture plate. Plus, they can simplify the machining of a mounting hole.

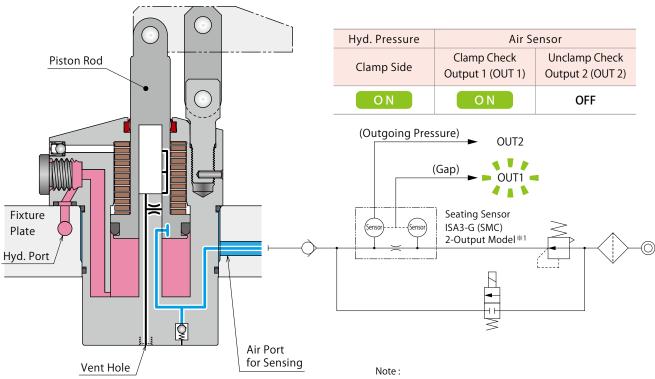


Action Description (Internal Structure)

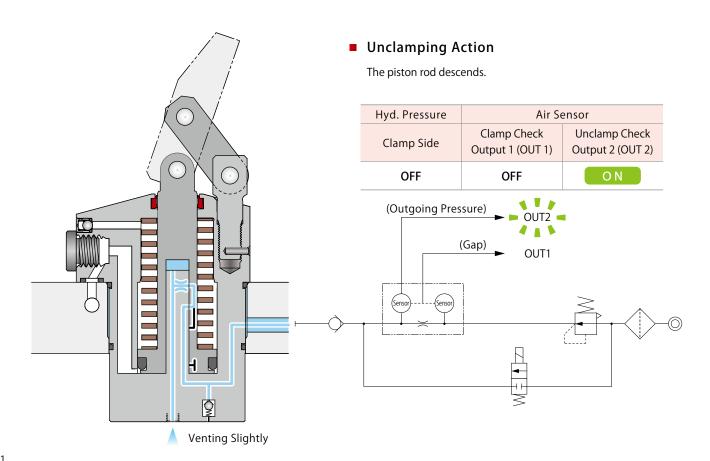
The figure shows clamp with option **5 E** (Clamp - Unclamp Confirmation)

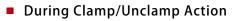
Clamping Action

The piston rod ascends and clamps the workpiece.



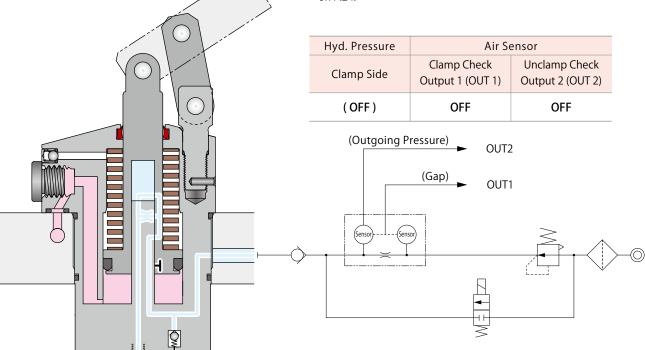
**1. It is able to use a one-output seating sensor for the action confirmation symbol 5 H/J (one-side action confirmation).





The air sensor turns OFF during the stroke action.

The detail of sensor ON/OFF range is shown in Air Sensing Chart on P.24.



The following shows the actions and the air sensor outputs for the action confirmation symbol 5 H/J.

| Action Confirmation | In case of 5 H Clamp Confirmation | In case of 5 J Unclamp Confirmation | | | |
|---------------------------------------|-----------------------------------|--|--|--|--|
| Clamping Action | Air Sensor Output | · Air Sensor (OFF) | | | |
| Unclamping Action | Air Sensor (OFF) | Air Sensor Output | | | |
| During Clamping/ Unclamping Action | Air Sensor OFF Output | Air Sensor OFF Output | | | |

Venting

Accessories

Cautions

Swing Clamp with Action Confirmation

LGV

Link Clamp with

[※] When air sensor is ON: No air leakage from the vent hole. When air sensor is OFF: Air releasing from the vent hole.

Action Confirmation and Air Sensing Chart

Action confirmation can be conducted by detecting differential pressure with an air sensor.



5 Action Confirmation Symbol

E: Clamp - Unclamp Confirmation

H: Clamp Confirmation

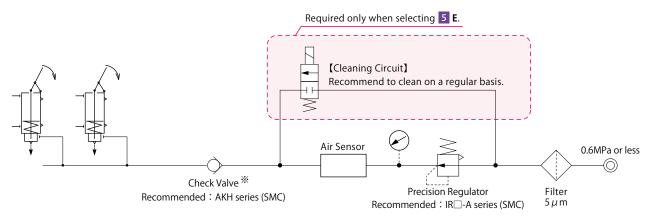
J: Unclamp Confirmation

Air Sensor

Recommended Air Sensor

| Action Confirmation Symbol | In case of 5 E | In case of 5 H, J | | |
|----------------------------|--|--|--------------------|--|
| Manufacturer | SMC | SMC | CKD | |
| Name | Digital Seating Switch | Digital Seating Switch | Digital Gap Switch | |
| Model No. | ISA3-G□A, ISA3-G□B | ISA3-G□N, ISA3-G□P | GPS3-E | |
| Air Sensor Requirement | Required to use the 2-output air sensor shown above. | Able to use a general 1-output air sensor. | | |
| Recommended Air Pressure | 0.1 ~ 0.2MPa (0.15 ~ 0.2MPa when using 4 clamps.) | 0.1 ~ 0.2MPa | | |

- In case of 5 E, the number of clamps connected per air sensor: 2 ~ 4 pcs.
 **Please contact us when using an air sensor for one clamp.
- In case of 5 H and J, there is no limitation for the number of clamps connected per air sensor.
- Please refer to manufacturer's catalog or other documents for the details about the air sensor.
- Please keep supplying air pressure when in use.
- Refer to the drawing below for the air circuit structure.
- Please install a check valve (** part) with low cracking pressure to the detection port of the air sensor.
 (Recommended Check Valve: SMC-made AKH series Cracking Pressure 0.005MPa)



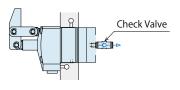
- Notes for Design Installation Use
 - Please keep clear condition at the air vent hole, and prevent coolant and chips from entering the hole. *
 The air sensor can malfunction if the air vent hole is blocked.

Air Vent Hole

• Keep clear condition at the air vent hole.

Coolant and chips enter from the air vent hole.

【Prevention of Contaminants to the Air Vent Hole 】
Coolant and chips can be prevented by setting a check
valve with low cracking pressure. (Recommended Check
Valve: SMC-made AKH series, cracking pressure: 0.005MPa)



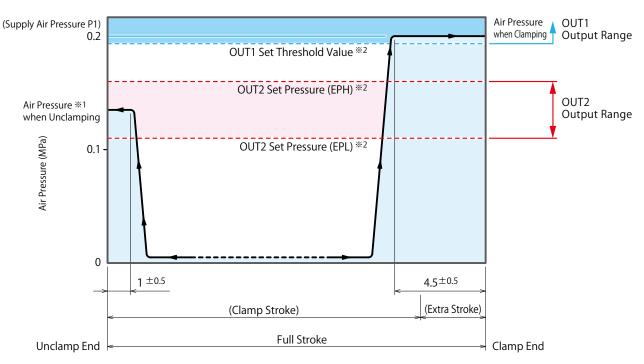
 Keep supplying air pressure to the air port for sensing when in use.

* The product will be damaged or malfunction due to internal corrosion.

Air Sensing Chart

5 **E**: Clamp - Unclamp Confirmation

When Connected to 3 Clamps, Supply 0.2MPa Air Pressure

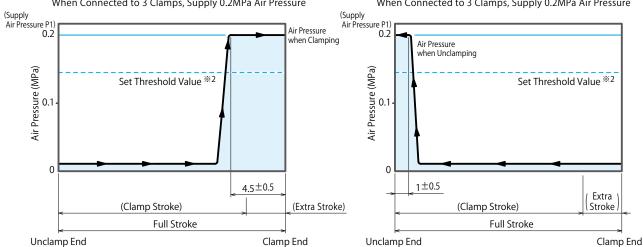


Sensor Setting should be as follows: Detect with OUT1 (Threshold Value) for clamp action confirmation, OUT2 (Pressure Set Value) for unclamp action confirmation. Hysteresis for both OUT1 and OUT2 should be set as 0. Please make sure to use the recommended air sensor.



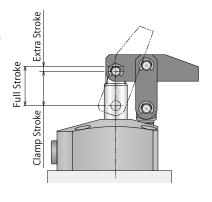
5 J: Unclamp Confirmation

When Connected to 3 Clamps, Supply 0.2MPa Air Pressure



Notes:

- 1. The sensing chart shows the relationship between the stroke and detection circuit air pressure.
- 2. The specifications may vary depending on the air circuit construction. Because it may affect the responsiveness of the air sensor, use the piping tube with outer diameter ϕ 6 (inner diameter ϕ 4) for the outgoing side of the sensor and its length should be as short as possible.
- *1. Pressure when unclamping may vary depending on the condition of air circuit.
- *2. The location of a signal from air sensor output varies depending on the sensor setting. Set according to using systems. Please refer to manufacturer's instruction manual or other documents for the details about the air sensor.



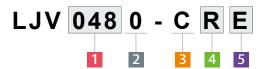
Accessories

Cautions

Swing Clamp with Action Confirmation LGV

nk Clamp with tion Confirmati

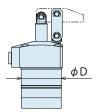
Model No. Indication



1 Body Size

040: φD=40mm **048**: φD=48mm **055**: φD=55mm **065**: φD=65mm **075** : φD=75mm

 \times Indicates the cylinder outer diameter (ϕ D).

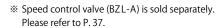


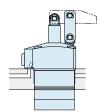
2 Design No.

0 : Revision Number

3 Piping Method

C: Gasket Option (With G Thread Plug)





With G Thread Plug Able to Attach BZL-A Speed Control Valve

4 Lever Direction

L : Left

C: Center R: Right

 $\ensuremath{\ensuremath{\%}}$ The images show the lever direction when the piping port is placed in front of you.



L





R

5 Action Confirmation Symbol

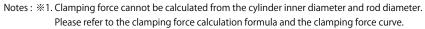
: Clamp - Unclamp Confirmation (Both)

: Clamp Confirmation Only : Unclamp Confirmation Only



Specifications

| Mode | l No. | | LJV0400-C□□ | LJV0480-C□□ | LJV0550−C□□ | LJV0650-C□□ | LJV0750-C□□ | | | | |
|---|---|-----------------------|----------------|--|---------------------------|-------------------------------|------------------|--|--|--|--|
| Cylind | er Area for Cla | mping cm ² | 4 | 5.4 | 8.3 | 12.7 | 20.1 | | | | |
| Cylind | er Inner Diame | eter *1 mm | 24 | 28 | 34 | 42 | 52 | | | | |
| Rod D | iameter **1 | mm | 12 | 14 | 16 | 18 | 22 | | | | |
| Clam | oing Force * | 2 | F= 5.79×P-2.80 | F= 8.94×P-5.62 | F= 15.68×P-7.49 | F= 28.06×P-12.13 | F= 54.29×P-24.93 | | | | |
| (Calcul | lation Formula) | kN | L-16 | $=$ ${L-16}$ $F=$ ${L-18.5}$ $F=$ ${L-21}$ $F=$ ${L-24.5}$ $F=$ ${L-30}$ | | | | | | | |
| Full St | troke | mm | 20.5 | 23.5 | 26 | 29.5 | 35 | | | | |
| Clam | o Stroke | mm | 17.5 | 17.5 20.5 23 26.5 32 | | | | | | | |
| Extra | Stroke mm 3 3 3 3 | | | | | | | | | | |
| Cylinder Capacity cm ³ 8.2 12.6 21.6 37.5 70.4 | | | | | | | 70.4 | | | | |
| Return Spring max. | | | 0.21 | 0.36 | 0.44 | 0.58 | 0.96 | | | | |
| Force | kN | min. | 0.1 | 0.17 | 0.24 | 0.33 | 0.49 | | | | |
| | Max. Operating | Pressure MPa | | | 7 | | | | | | |
| Hyd. Pressure | Min. Operating Pr | ressure **3 MPa | 2.5 | | | | | | | | |
| rressure | Withstanding | Pressure MPa | | | 10.5 | | | | | | |
| Recomm | ended Operating A | ir Pressure MPa | | | 0.1 ~ 0.2 | | | | | | |
| Recor | nmended | 5 E **4 | | ISA3-G□A, ISA3-C | G□B (Two-Output Mod | el):Made by SMC ^{※4} | | | | | |
| Air Se | nsor | 5 H/J | ISA3-G | i□N, ISA3-G□P (One-C | Output Model): Made b | y SMC / GPS3-E:Made I | by CKD | | | | |
| Opera | ating Temper | ature ℃ | | | 0 ~ 70 | | | | | | |
| Usabl | e Fluid | | | General Hy | draulic Oil Equivalent to | SISO-VG-32 | | | | | |
| Weigl | nt ^{**5} | kg | 0.9 | 1.2 | 1.8 | 2.5 | 4 | | | | |



- $\ensuremath{\,\%} 2.\,F \div \text{Clamping Force (kN)}\,, P \div \text{Supply Hydraulic Pressure (MPa)},$
 - $\ensuremath{\mathsf{L}}$: Distance between the piston center and the clamping point (mm).
- $\ensuremath{\%3}.$ Minimum pressure to operate the clamp without load.
- %4. The number of clamps connected per air sensor is 2 \sim 4 pcs.

Please contact us when using an air sensor for one clamp.

%5. It shows the weight of single link clamp without the link lever.



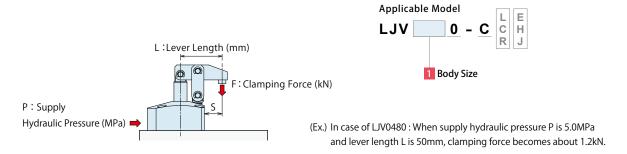
Accessories

Cautions

Swing Clamp with Action Confirmation

LGV
Link Clamp with
Action Confirmatio

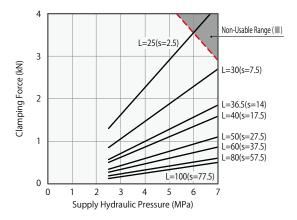
Clamping Force Curve



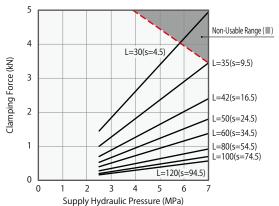
Notes:

- 1. Tables and graphs show the relationship between the clamping force (kN) and supply hydraulic pressure (MPa).
- 2. Cylinder force (when L=0) cannot be calculated from the formula of clamping force.
- 3. Clamping force in the non-usable range may cause deformation, galling and fluid leakage, etc.
- %1. F: Clamping Force (kN), P: Supply Hydraulic Pressure (MPa), L: Lever Length (mm).

| LJV0400 Clamping Force Calculation Formula *1 (kN) | | | | | F = (5 | 5.79 × | P – 2.8 | 30)/(| (L-16) | |
|--|-------------------|------|--|--------|--------|----------|---------|-------|--------|------------|
| Hydraulic | Cylinder Force | | Clamping Force (kN) Non-Usable Range (III) | | | | | | | Min. Lever |
| Pressure | (kN) | | | Lev | er Len | gth L (m | nm) | | | Length (L) |
| (MPa) | | L=25 | L=30 | L=36.5 | L=40 | L=50 | L=60 | L=80 | L=100 | (mm) |
| 7 | 2.6 | | 2.7 | 1.8 | 1.6 | 1.1 | 0.9 | 0.6 | 0.4 | 30 |
| 6.5 | 2.4 | | 2.5 | 1.7 | 1.5 | 1.0 | 0.8 | 0.5 | 0.4 | 28 |
| 6 | 2.2 | | 2.3 | 1.6 | 1.3 | 0.9 | 0.7 | 0.5 | 0.4 | 26 |
| 5.5 | 2.0 | 3.2 | 2.1 | 1.4 | 1.2 | 0.9 | 0.7 | 0.5 | 0.3 | 25 |
| 5 | 1.8 | 2.9 | 1.9 | 1.3 | 1.1 | 0.8 | 0.6 | 0.4 | 0.3 | 23 |
| 4.5 | 1.6 | 2.6 | 1.7 | 1.1 | 1.0 | 0.7 | 0.5 | 0.4 | 0.3 | 23 |
| 4 | 1.4 | 2.3 | 1.5 | 1.0 | 0.8 | 0.6 | 0.5 | 0.3 | 0.2 | 23 |
| 3.5 | 1.2 | 1.9 | 1.2 | 0.9 | 0.7 | 0.5 | 0.4 | 0.3 | 0.2 | 23 |
| 3 | 1.0 | 1.6 | 1.0 | 0.7 | 0.6 | 0.4 | 0.3 | 0.2 | 0.2 | 23 |
| 2.5 | 0.8 | 1.3 | 0.8 | 0.6 | 0.5 | 0.3 | 0.3 | 0.2 | 0.1 | 23 |
| Max. Operatir | ng Pressure (MPa) | 5.6 | 7.0 | 7.0 | 7.0 | 7.0 | 7.0 | 7.0 | 7.0 | |



| LJV04 | Clamping | g Force Ca | lculation | Formula * | ⁽¹ (kN) | F = (8 | .94× | P – 5.6 | 2)/(| L-18.5) |
|---------------|-------------------|------------|--|-----------|--------------------|----------|------|---------|-------|------------|
| Hydraulic | Cylinder Force | | Clamping Force (kN) Non-Usable Range (III) | | | | | | | Min. Lever |
| Pressure | (kN) | | | Le | ver Lend | gth L (m | nm) | | | Length (L) |
| (MPa) | | L=30 | L=35 | L=42 | L=50 | L=60 | L=80 | L=100 | L=120 | (mm) |
| 7 | 3.4 | | | 2.4 | 1.8 | 1.4 | 0.9 | 0.7 | 0.6 | 36 |
| 6.5 | 3.2 | | 3.2 | 2.2 | 1.7 | 1.3 | 0.9 | 0.6 | 0.5 | 33 |
| 6 | 2.9 | | 2.9 | 2.0 | 1.5 | 1.2 | 0.8 | 0.6 | 0.5 | 31 |
| 5.5 | 2.6 | 3.8 | 2.6 | 1.9 | 1.4 | 1.0 | 0.7 | 0.5 | 0.4 | 29 |
| 5 | 2.3 | 3.4 | 2.4 | 1.7 | 1.2 | 0.9 | 0.6 | 0.5 | 0.4 | 27 |
| 4.5 | 2.1 | 3.0 | 2.1 | 1.5 | 1.1 | 0.8 | 0.6 | 0.4 | 0.3 | 26 |
| 4 | 1.8 | 2.6 | 1.8 | 1.3 | 1.0 | 0.7 | 0.5 | 0.4 | 0.3 | 26 |
| 3.5 | 1.5 | 2.2 | 1.6 | 1.1 | 0.8 | 0.6 | 0.4 | 0.3 | 0.3 | 26 |
| 3 | 1.3 | 1.8 | 1.3 | 0.9 | 0.7 | 0.5 | 0.3 | 0.3 | 0.2 | 26 |
| 2.5 | 1.0 | 1.5 | 1.0 | 0.7 | 0.5 | 0.4 | 0.3 | 0.2 | 0.2 | 26 |
| Max. Operatir | ng Pressure (MPa) | 5.8 | 7.0 | 7.0 | 7.0 | 7.0 | 7.0 | 7.0 | 7.0 | |



Clamp

Cautions

Swing Clamp with Action Confirmation

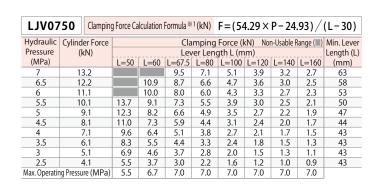
LGV

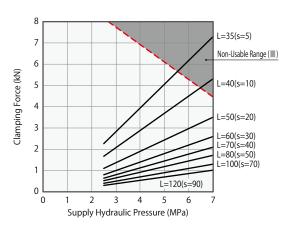
Link Clamp with Action Confirmation

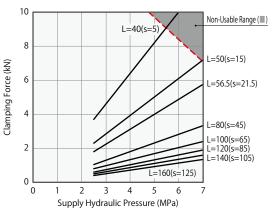
LIV

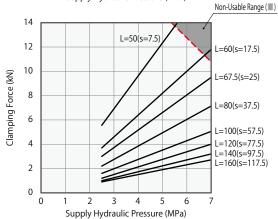
| LJV0550 Clamping Force Calculation Formula ^{※1} (kN) | | | | | F = (1 | 5.68 × | P-7. | 49)/ | (L-21) | |
|--|-------------------|------|------|------|---------|----------|--------|------------|-------------|------------|
| Hydraulic | Cylinder Force | | | Cla | mping | Force (F | (N) No | n-Usable F | Range (III) | Min. Lever |
| Pressure | (kN) | | | Lev | er Lend | gth L (m | ım) | | | Length (L) |
| (MPa) | | L=35 | L=40 | L=50 | L=60 | L=70 | L=80 | L=100 | L=120 | (mm) |
| 7 | 5.4 | | | 3.5 | 2.6 | 2.1 | 1.7 | 1.3 | 1.0 | 44 |
| 6.5 | 5.0 | | | 3.3 | 2.4 | 1.9 | 1.6 | 1.2 | 1.0 | 41 |
| 6 | 4.6 | | 4.6 | 3.0 | 2.2 | 1.8 | 1.5 | 1.1 | 0.9 | 37 |
| 5.5 | 4.2 | 5.6 | 4.1 | 2.7 | 2.0 | 1.6 | 1.3 | 1.0 | 0.8 | 35 |
| 5 | 3.8 | 5.1 | 3.7 | 2.4 | 1.8 | 1.4 | 1.2 | 0.9 | 0.7 | 33 |
| 4.5 | 3.3 | 4.5 | 3.3 | 2.2 | 1.6 | 1.3 | 1.1 | 0.8 | 0.6 | 31 |
| 4 | 2.9 | 3.9 | 2.9 | 1.9 | 1.4 | 1.1 | 0.9 | 0.7 | 0.6 | 30 |
| 3.5 | 2.5 | 3.4 | 2.5 | 1.6 | 1.2 | 1.0 | 0.8 | 0.6 | 0.5 | 30 |
| 3 | 2.1 | 2.8 | 2.1 | 1.4 | 1.0 | 0.8 | 0.7 | 0.5 | 0.4 | 30 |
| 2.5 | 1.7 | 2.3 | 1.7 | 1.1 | 0.8 | 0.6 | 0.5 | 0.4 | 0.3 | 30 |
| Max. Operatir | ng Pressure (MPa) | 5.5 | 6.4 | 7.0 | 7.0 | 7.0 | 7.0 | 7.0 | 7.0 | |

| LJV0650 Clamping Force Calculation Formula *1 (kN) | | | | | F=(28 | 3.06 × | P – 12. | 13)/(| L-24.5) | |
|--|-------------------|------|--|--------|--------|----------|---------|-------|---------|------------|
| Hydraulic | Cylinder Force | | Clamping Force (kN) Non-Usable Range (III) | | | | | | | Min. Lever |
| Pressure | (kN) | | | Lev | er Len | gth L (m | ım) | | | Length (L) |
| (MPa) | | L=40 | L=50 | L=56.5 | L=80 | L=100 | L=120 | L=140 | L=160 | (mm) |
| 7 | 8.4 | | | 5.8 | 3.3 | 2.4 | 1.9 | 1.6 | 1.4 | 51 |
| 6.5 | 7.7 | | 6.7 | 5.3 | 3.1 | 2.3 | 1.8 | 1.5 | 1.3 | 47 |
| 6 | 7.1 | | 6.1 | 4.9 | 2.8 | 2.1 | 1.6 | 1.4 | 1.2 | 43 |
| 5.5 | 6.5 | | 5.6 | 4.4 | 2.6 | 1.9 | 1.5 | 1.2 | 1.1 | 41 |
| 5 | 5.8 | 8.3 | 5.0 | 4.0 | 2.3 | 1.7 | 1.3 | 1.1 | 1.0 | 38 |
| 4.5 | 5.2 | 7.4 | 4.5 | 3.6 | 2.1 | 1.5 | 1.2 | 1.0 | 0.8 | 36 |
| 4 | 4.5 | 6.5 | 3.9 | 3.1 | 1.8 | 1.3 | 1.0 | 0.9 | 0.7 | 35 |
| 3.5 | 3.9 | 5.6 | 3.4 | 2.7 | 1.6 | 1.1 | 0.9 | 0.7 | 0.6 | 35 |
| 3 | 3.3 | 4.6 | 2.8 | 2.3 | 1.3 | 1.0 | 0.8 | 0.6 | 0.5 | 35 |
| 2.5 | 2.6 | 3.7 | 2.3 | 1.8 | 1.1 | 0.8 | 0.6 | 0.5 | 0.4 | 35 |
| Max. Operatir | ng Pressure (MPa) | 5.4 | 6.9 | 7.0 | 7.0 | 7.0 | 7.0 | 7.0 | 7.0 | |

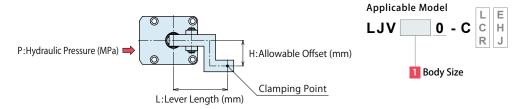








Allowable Offset Graph



(Ex.) When using LJV0480

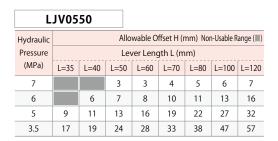
Supply Hydraulic Pressure 5.0MPa, Lever Length L=80mm, Allowable Offset is about 19mm.

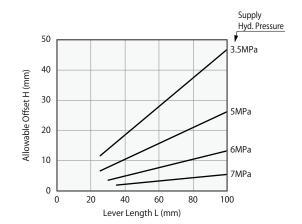
Notes:

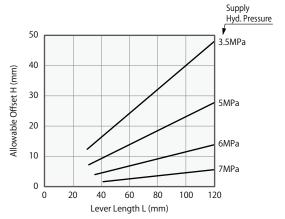
- 1. Tables and graphs shown are the relationships between the lever length (mm) for supply hydraulic pressure (MPa) and the allowable offset (mm).
- 2. Using the lever beyond allowable offset may cause deformation, galling and fluid leakage etc.
- 3. The tables and graphs are only for reference. The design should be carried out with allowance fully taken into consideration.

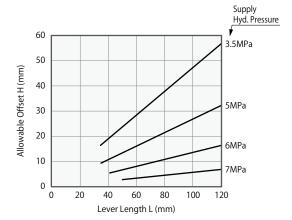
| L | JV04 | 00 | | | | | | | | |
|-----------|--|------|--------|------|------|------|------|-------|--|--|
| Hydraulic | Allowable Offset H (mm) Non-Usable Range (III) | | | | | | | | | |
| Pressure | Lever Length L (mm) | | | | | | | | | |
| (MPa) | L=25 | L=30 | L=36.5 | L=40 | L=50 | L=60 | L=80 | L=100 | | |
| 7 | | | 2 | 2 | 3 | 3 | 4 | 5 | | |
| 6 | | 4 | 5 | 5 | 6 | 8 | 11 | 13 | | |
| 5 | 7 | 8 | 10 | 11 | 13 | 16 | 21 | 26 | | |
| 3.5 | 12 | 14 | 17 | 19 | 23 | 28 | 37 | 47 | | |

| LJV0480 | | | | | | | | |
|-----------|------|--|------|------|------|------|-------|-------|
| Hydraulic | | Allowable Offset H (mm) Non-Usable Range (■) | | | | | | |
| Pressure | | Lever Length L (mm) | | | | | | |
| (MPa) | L=30 | L=35 | L=42 | L=50 | L=60 | L=80 | L=100 | L=120 |
| 7 | | | 2 | 2 | 3 | 4 | 5 | 6 |
| 6 | | 4 | 5 | 6 | 7 | 9 | 12 | 14 |
| 5 | 7 | 8 | 10 | 12 | 14 | 19 | 23 | 28 |
| 3.5 | 13 | 15 | 17 | 20 | 24 | 32 | 40 | 48 |









Clamp

Accessories

Cautions

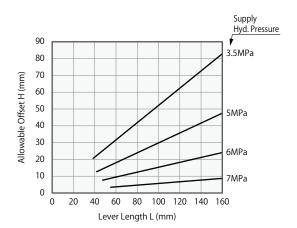
Swing Clamp with Action Confirmation

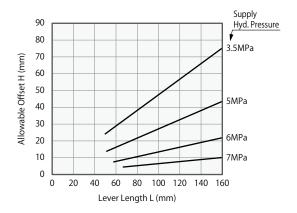
LGV

Link Clamp with Action Confirmatio

| LJV0650 | | | | | | | | |
|-----------|------|---------------------|--------|---------|------------|---------|------------|----------|
| Hydraulic | | | Allo | wable O | ffset H (r | nm) Nor | n-Usable R | ange (🔳) |
| Pressure | | Lever Length L (mm) | | | | | | |
| (MPa) | L=40 | L=50 | L=56.5 | L=80 | L=100 | L=120 | L=140 | L=160 |
| 7 | | | 4 | 5 | 6 | 7 | 8 | 9 |
| 6 | | 8 | 9 | 12 | 15 | 18 | 21 | 24 |
| 5 | | 15 | 17 | 24 | 30 | 36 | 42 | 48 |
| 3.5 | 21 | 27 | 30 | 42 | 52 | 62 | 73 | 83 |

| | LJV0750 | | | | | | | |
|-----------|---------|---------------------|--------|---------|------------|---------|------------|----------|
| Hydraulie | 5 | | Allo | wable O | ffset H (r | nm) Nor | n-Usable R | ange (■) |
| Pressure | : | Lever Length L (mm) | | | | | | |
| (MPa) | L=50 | L=60 | L=67.5 | L=80 | L=100 | L=120 | L=140 | L=160 |
| 7 | | | 5 | 5 | 7 | 8 | 9 | 10 |
| 6 | | 8 | 9 | 11 | 14 | 16 | 19 | 22 |
| 5 | | 16 | 18 | 22 | 27 | 33 | 38 | 44 |
| 3.5 | 24 | 29 | 33 | 38 | 47 | 57 | 66 | 75 |





External Dimensions

Direction

L type

Lever

R type

Direction

Trap Valve **5

È

(for Spring

Chamber)

G Thread Plug

(Speed Control

Hyd. Port G Thread *3

(The dimensions are the same for 5 Action Confirmation Symbol E / H / J.)

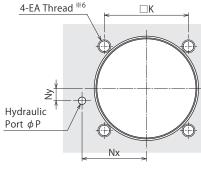
2 - Chamfer 1

4-φR

Spot Facing ϕ Q

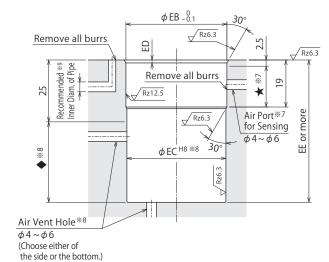
Link Lever (Prepared by Customer)

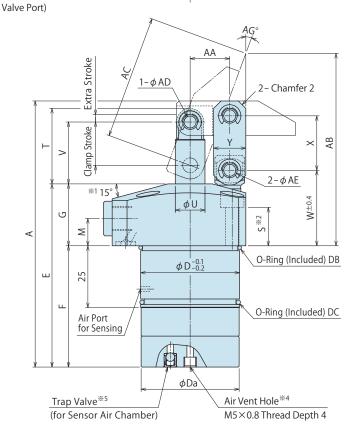
Lever Direction C type



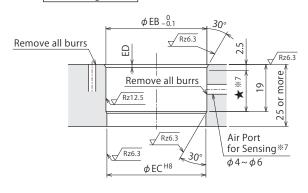
Machining Dimensions of Mounting Area

For Blind Hole





For Through Hole



Hydraulic Port O-Ring (Included) DA BA BA

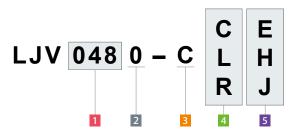
Notes:

- ※6. EA tapping depth of the mounting bolt should be decided according to the mounting height referring to dimensions 'S'.
- *7. Prepare the air port for sensing within the \bigstar area.
- **8. Prepare the vent hole on the side or the bottom. When preparing on the side, it should be within the \spadesuit area. When preparing on the bottom, it should be within ϕ EC.

Notes:

- ※ 1. Flange inclination angle is 12° only for LJV0650.
- * 2. Mounting bolts are not provided with the product. Please prepare them according to the mounting height referring to dimension 'S'.
- * 3. Speed control valve is sold separately. Please refer to P.37 for detail.
- ** 4. Please keep clear condition at the air vent hole, and prevent coolant and chips from entering the hole.
 If exposed to coolant, use the thread and prepare piping to prevent coolant and chips, but do not block the air vent hole.
- * 5. Please keep clear condition at the trap valve.
 - 1. Please use the provided pin (equivalent to ϕ ADf6, ϕ AEf6, HRC60) as mounting pin for lever.

Model No. Indication



(Format Example: LJV0480-CCE, LJV0750-CLJ)

1 Body Size

2 Design No.

3 Piping Method

4 Lever Direction

5 Action Confirmation Symbol

Clamp Accessories

Cautions

Swing Clamp with Action Confirmation

LGV

External Dimensions and Machining Dimensions of Mounting

(mm)

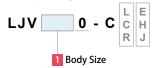
| Model No | o | LJV0400-C□□ | LJV0480-C□□ | LJV0550-C□□ | LJV0650-C□□ | LJV0750-C□□ |
|------------------|--------------|-----------------------------------|----------------------|----------------------------|-----------------|----------------------|
| Full Strok | e | 20.5 | 23.5 | 26 | 29.5 | 35 |
| Clamp Stro | ke | 17.5 | 20.5 | 23 | 26.5 | 32 |
| Extra Stro | ke | 3 | 3 | 3 | 3 | 3 |
| Α | | 107.5 | 119 | 135 | 148.5 | 175 |
| В | | 54 | 61 | 69 | 81 | 94.5 |
| C | | 45 | 51 | 60 | 70 | 85 |
| D | | 40 | 48 | 55 | 65 | 75 |
| Da | | 39.6 | 47.6 | 54.6 | 64.6 | 74.6 |
| E | | 74 | 80 | 89.5 | 94.5 | 108 |
| F | | 49 | 52 | 61.5 | 64.5 | 71 |
| G | | 25 | 28 | 28 | 30 | 37 |
| Н | | 31.5 | 35.5 | 39 | 46 | 52 |
| J | | 22.5 | 25.5 | 30 | 35 | 42.5 |
| K | | 34 | 40 | 47 | 55 | 63 |
| L | | 68 | 73 | 80 | 94 | 106 |
| М | | 11 | 12 | 12 | 13 | 16 |
| Nx | | 26 | 30 | 33.5 | 39.5 | 45 |
| Ny | | 5 | | | 0 | |
| P | | | 3 | | | 5 |
| Q | | 9.5 | | 1 | 1 | 14 |
| R | | 5.5 | | | .8 | 9 |
| S | | 15.5 | 17.5 | 15 | 15.5 | 19.5 |
| T | | 30.5 | 35 | 37.5 | 45 | 55 |
| U | | 12 | 14 | 16 | 18 | 22 |
| V | | 25 | 29 | 31.5 | 37 | 45 |
| W | | 30.5 | 34.5 | 35.5 | 39 | 48 |
| X | | 22 | 26 | 30 | 35.5 | 43.5 |
| Y | | 13 | 13 | 16 | 19 | 25 |
| | | 21 | 21 | 28 | 37 | 40 |
| Chamfer | 1 | C3 | C3 | (φ80) | (φ94) | (φ106) |
| Chamfer | | C3 | G | C3 | C5 | (φ100) C5 |
| AA | | 16 | 18.5 | 21 | 24.5 | 30 |
| AB | | 77.7 | 92.4 | 101.9 | 111.4 | 130.8 |
| AC | | 50.2 | 61.2 | 71.7 | 78.7 | 90.8 |
| AC | | 6 | 6 | | 8 | 10 |
| | | 6 | 6 | 6 | 10 | 12 |
| AE AG | | 20.2 | 18.9 | 19.9 | 20.5 | 21.4 |
| BA | | 6.9 | 4 | 19.9 | 4 | 7.1 |
| BB | | | | | | 7.1 |
| | 'D:4 -l-\ | 4 M5× | 6.9 | 6.9 | 6.9 | |
| EA (Nominal× | PILCH) | | | M6 | | M8×1.25 |
| EB | | 40.8 | 49 40 ±0.039 | 56 55 ^{+0.046} | 66 65 +0.046 | 76 7r +0.046 |
| EC | | 40 +0.039 | 48 + 0.039 | | 65 +0.046 | 75 ^{+0.046} |
| ED | | 1 | 1 52.5 | 1 | 1 | 1.5 |
| | EE 49.5 52.5 | | | 62 | 65 | 71.5 |
| JA | | | 3.5 | | 4 | |
| | JB 14 | | | | 9 | |
| ydraulic Port: (| | | G1/8 | | G1 | |
| | DA | | OR NBR-90 P5-N(1BP5) | | OR NBR-90 | T |
| O-ring | DB | 3.8×1.5 (Inner Diam.× Wire Diam.) | AS568-031(70°) | AS568-034(70°) | AS568-037(70°) | AS568-040(70°) |
| | DC | AS568-028(70°) | AS568-031(70°) | AS568-033(70°) | AS568-036(70°) | AS568-039(70°) |

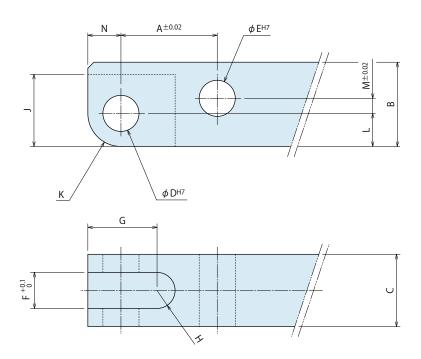
Note: **9. The recommended inner diameter of pipe is a reference value. Please change it depending on the number of clamps or the length of piping.

Link Lever Design Dimensions

* Reference for designing link lever.

Corresponding Model No.





Link Lever Design Dimension List

| | | | | | (mm) |
|-------------------------|----------|---------------------|----------|-----------|-----------|
| Corresponding Model No. | LJV0400 | LJV0480 | LJV0550 | LJV0650 | LJV0750 |
| А | 16 | 18.5 | 21 | 24.5 | 30 |
| В | 14 | 16 | 20 | 25 | 32 |
| С | 12_0.3 | 12 _0.3 | 16 _0.3 | 19 _0.3 | 22 - 0.3 |
| D | 6 +0.012 | 6 ^{+0.012} | 6 +0.012 | 8 +0.015 | 10 +0.015 |
| E | 6 +0.012 | 6 ^{+0.012} | 8 +0.015 | 10 +0.015 | 12 +0.018 |
| F | 6 | 6 | 8 | 10 | 11 |
| G | 11.5 | 13 | 12.5 | 16 | 20 |
| Н | R3 | R3 | R4 | R5 | R5.5 |
| J | 12 | 13 | 13 | 17.5 | 22 |
| K | R5.5 | R6 | R6 | R8 | R10 |
| L | 5.5 | 6 | 6 | 8 | 10 |
| М | 2.5 | 3.5 | 6 | 7.5 | 9.5 |
| N | 5.5 | 6 | 6 | 8 | 10 |

Notes:

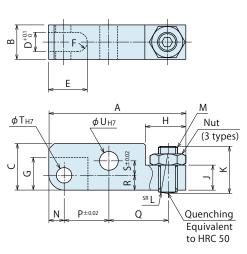
- 1. Please design the link lever length according to the performance curve.
- 2. If the link lever is not in accordance with the dimensions shown above, performance may be degraded and damage can occur.
- 3. Please use the attached pin (equivalent to ϕ ADf6, ϕ AEf6, HRC60) as the mounting pin for lever. (Please refer to each external dimension of LJV for the dimensions ϕ AD and ϕ AE.)

(mm)

Accessory: Link Lever (LZ-LJ1)

Model No. Indication





| Model No. | LZ0400-LJ1 | LZ0480-LJ1 | LZ0550-LJ1 | LZ0650-LJ1 | LZ0750-LJ1 |
|-------------------------|---------------------|---------------------|---------------------|------------|------------|
| Corresponding Model No. | LJV0400 | LJV0480 | LJV0550 | LJV0650 | LJV0750 |
| Α | 48 | 54 | 64 | 74.5 | 88.5 |
| В | 12 _0.3 | 12 _0.3 | 16 _0.3 | 19 _0.3 | 22 -0.3 |
| C | 14 | 16 | 20 | 25 | 32 |
| D | 6 | 6 | 8 | 10 | 11 |
| Е | 14.5 | 16 | 16.5 | 21 | 25.5 |
| F | R3 | R3 | R4 | R5 | R5.5 |
| G | 12 | 13 | 13 | 17.5 | 22 |
| Н | 13 | 13 | 17 | 22 | 25 |
| J | 7.5 | 8 | 10 | 13 | 16 |
| K | 16 | 18 | 22 | 27 | 31 |
| L | 10 | 10 | 15 | 20 | 30 |
| М | M6×1 | M6×1 | M8×1.25 | M10×1.5 | M12×1.75 |
| N | 5.5 | 6 | 6 | 8 | 10 |
| Р | 16 | 18.5 | 21 | 24.5 | 30 |
| Q | 20.5 | 23.5 | 29 | 32 | 37.5 |
| R | 5.5 | 6 | 6 | 8 | 10 |
| S | 2.5 | 3.5 | 6 | 7.5 | 9.5 |
| T | 6 ^{+0.012} | 6 ^{+0.012} | 6 ^{+0.012} | 8 +0.015 | 10 +0.015 |
| U | 6 +0.012 | 6 ^{+0.012} | 8 +0.015 | 10 +0.015 | 12 +0.018 |

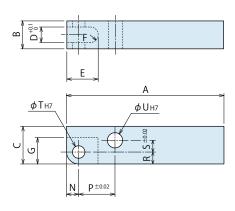
Notes:

- 1. Material: S45C Surface Finishing: Alkaline Blackening
- 2. If necessary, the front end should be additionally machined.
- 3. Please use the attached pin (equivalent to ϕ ADf6, ϕ AEf6, HRC60) as the mounting pin for lever.

Accessory: Material Link Lever (LZ-LJ2)

Model No. Indication





| | | | | | (mm) |
|-------------------------|------------|------------|------------|------------|------------|
| Model No. | LZ0400-LJ2 | LZ0480-LJ2 | LZ0550-LJ2 | LZ0650-LJ2 | LZ0750-LJ2 |
| Corresponding Model No. | LJV0400 | LJV0480 | LJV0550 | LJV0650 | LJV0750 |
| Α | 75 | 85 | 90 | 105 | 110 |
| В | 12 _0.3 | 12 _0.3 | 16 -0.3 | 19 _0.3 | 22 _0.3 |
| С | 14 | 16 | 20 | 25 | 32 |
| D | 6 | 6 | 8 | 10 | 11 |
| Е | 14.5 | 16 | 16.5 | 21 | 25.5 |
| F | R3 | R3 | R4 | R5 | R5.5 |
| G | 12 | 13 | 13 | 17.5 | 22 |
| N | 5.5 | 6 | 6 | 8 | 10 |
| Р | 16 | 18.5 | 21 | 24.5 | 30 |
| R | 5.5 | 6 | 6 | 8 | 10 |
| S | 2.5 | 3.5 | 6 | 7.5 | 9.5 |
| T | 6 +0.012 | 6 +0.012 | 6 +0.012 | 8 +0.015 | 10 +0.015 |
| U | 6 +0.012 | 6 +0.012 | 8 +0.015 | 10 +0.015 | 12 +0.018 |

Notes :

- 1. Material: S45C Surface Finishing: Alkaline Blackening
- 2. If necessary, the front end should be additionally machined.
- 3. Please use the attached pin (equivalent to ϕ ADf6, ϕ AEf6, HRC60) as the mounting pin for lever.

Clamp

Accessories

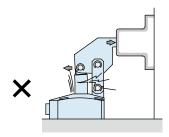
Cautions

Swing Clamp with Action Confirmation

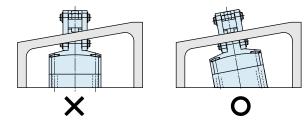
LGV
Link Clamp with
Action Confirmation

Cautions

- Notes for Design
- 1) Check Specifications
- Please use each product according to the specifications.
- 2) Notes for Circuit Design
- Please read "Notes on Hydraulic Cylinder Speed Control Unit" for proper hydraulic circuit design. Improper circuit design may lead to malfunctions and damages. (Refer to P.40.)
- 3) Notes for Link Lever Design
- Make sure no force is applied to the piston rod except from the axial direction. The usage like the one shown in the drawing below will apply a large bending stress to the piston rod and must be avoided.



- If offset load is applied on the link part, use it within the allowable range of "Allowable Offset Graph".
- 4) Protect the exposed area of the piston rod when using on a welding fixture.
- If spatter attaches to the sliding surface it could lead to malfunction and fluid leakage.
- 5) When clamping on a sloped surface of the workpiece
- Make sure the clamping surface and the mounting surface of the clamp are parallel.



- 6) When using in a dry environment.
- The link pin can be dried out. Grease it periodically or use a special pin.
 Contact us for the specifications for special pins.
- 7) Vent Hole and Check Valve of Air Sensor
- Make sure to check the notes for design, installation and use on P. 23 when using an air sensor.

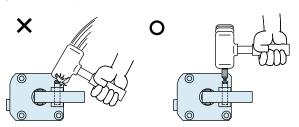


Installation Notes

- 1) Check the Usable Fluid
- Please use the appropriate fluid by referring to the Hydraulic Fluid List (P.39).
- 2) Installation of the Product
- When mounting the clamp, use hexagonal socket bolts as multiple bolt holes for mounting (with tensile strength of 12.9) and tighten them with the torque shown in the table below. Tightening with greater torque than recommended can dent the seating surface or break the bolt.

| Model No. | Mounting Bolt Size | Tightening Torque (N·m) |
|-------------|--------------------|-------------------------|
| LJV0400-C□□ | M5×0.8 | 6.3 |
| LJV0480-C□□ | M5×0.8 | 6.3 |
| LJV0550-C□□ | M6×1 | 10 |
| LJV0650-C□□ | M6×1 | 10 |
| LJV0750-C□□ | M8×1.25 | 25 |

- 3) Installation / Removal of the Link Lever
- When inserting the link pin, do not hit the pin directly with a hammer. When using a hammer to insert the pin, always use a cover plate with a smaller diameter than the snap ring groove on the pin.



- 4) Speed Adjustment
- Adjust the speed so that the total operating time is one second or more. If the clamp operates too fast, the parts will be worn out, leading to premature damage and ultimately complete equipment
- Please make sure to release air from the circuit before adjusting speed. It will be difficult to adjust the speed accurately with air mixed in the circuit.
- Turn the speed control valve gradually from the low-speed side (small flow) to the high-speed side (large flow) to adjust the speed.

Clamp

Accessories

Cautions

Swing Clamp with Action Confirmation

LGV

- * Please refer to P.39 for common cautions.
- Installation Notes
- Hydraulic Fluid List Notes on Hydraulic Cylinder Speed Control Circuit
- Notes on Handling
- Maintenance/Inspection Warranty

Speed Control Valve (For Low Pressure)

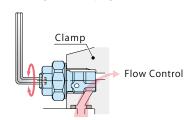
Directly Mounted to Clamps

Speed Control Valve (model BZL) attaches directly to KOSMEK hydraulic clamp with piping method: type C.



Action Description

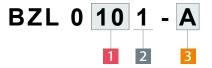
Control the flow with a wrench. Able to change the clamping action speed individually.



Able to release the air in the circuit by loosening the Speed Control Valve.

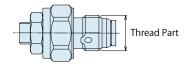


Model No. Indication (Speed Control Valve for Low Pressure)



1 G Thread Size

10 : Thread Part G1/8A Thread 20 : Thread Part G1/4A Thread

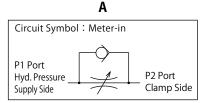


2 Design No.

1 : Revision Number

Control Method

A: Meter-in



Specifications

| Model No. | | BZL0101-A | BZL0201-A | |
|---------------------------------|-----------------|----------------------|----------------------|--|
| Max. Operating Pressure | MPa | 7 | 7 | |
| Withstanding Pressure | MPa | 10 |).5 | |
| Control Method | | Meter-in | | |
| G Thread Size | | G1/8A | G1/4A | |
| Cracking Pressure | MPa | 0.04 | | |
| Max. Passage Area | $\mathrm{mm^2}$ | 2.6 | 5.0 | |
| Usable Fluid | | General Hyd. Oil Equ | ivalent to ISO-VG-32 | |
| Operating Temperature | ℃ | 0 ~ 70 | | |
| Tightening Torque for Main Body | N∙m | 10 | 25 | |
| Weight | g | 12 | 26 | |
| | | | | |

Notes:

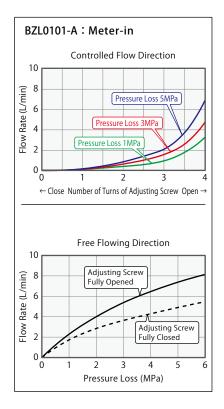
- 1. It must be mounted with recommended torque. Because of the structure of the metal seal, if mounting torque is insufficient, it may not be able to control the flow rate.
- 2. Do not attach a used BZL to other clamps. Flow control may not be succeeded because the bottom depth difference of G thread makes metal sealing insufficient.

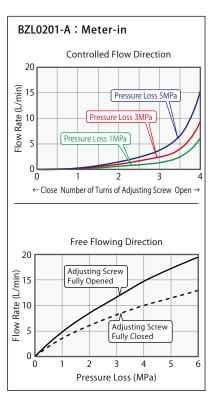
Applicable Products

| Model No. | LGV (Single Action) | LJV (Single Action) |
|-----------|---------------------|---------------------|
| woder No. | Swing Clamp | Link Clamp |
| | LGV0400-C □□ | LJV0400-C□□ |
| BZL0101-A | LGV0480-C□□ | LJV0480-C□□ |
| | LGV0550-C□□ | LJV0550-C □□ |
| BZL0201-A | LGV0650-C□□ | LJV0650-C□□ |
| | LGV0750-C □□ | LJV0750-C□□ |

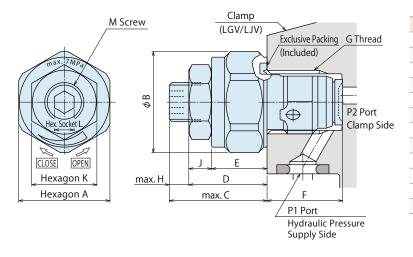
Model No. Indication | Specifications | Flow Rate Graph | External Dimensions | Cautions

KOSMEK Harmony in Innovation





External Dimensions



| | | (mm) |
|------------------------------|-----------|-----------|
| Model No. | BZL0101-A | BZL0201-A |
| Α | 14 | 18 |
| В | 15.5 | 20 |
| C | 15 | 16 |
| D | 12 | 13 |
| Е | 8.5 | 9.5 |
| F | (11.6) | (15.1) |
| G | G1/8 | G1/4 |
| Н | 3 | 3 |
| J | 3.5 | 3.5 |
| K | 10 | 10 |
| L | 3 | 3 |
| M (Nominal \times Pitch) | M6×0.75 | M6×0.75 |

Notes

- 1. Please read "Notes on Hydraulic Cylinder Speed Control Unit" for proper hydraulic circuit design. Improper circuit design may lead to malfunctions and damages. (Refer to P.40)
- 2. It is dangerous to release the air under high pressure. It must be done under lower pressure. (For reference: the minimum operating range of the product within the circuit.)

Clamp

Accessories

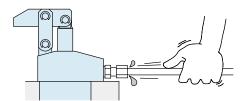
Cautions

Control Valve BZL

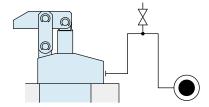
Cautions

Installation Notes (for Hydraulic Series)

- 1) Check the Usable Fluid
- Please use the appropriate fluid by referring to the Hydraulic Fluid List.
- 2) Procedure before Piping
- The pipeline, piping connector and fixture circuits should be cleaned by thorough flushing.
- The dust and cutting chips in the circuit may lead to fluid leakage and malfunction.
- There is no filter provided with Kosmek's product except for a part of valves which prevent contamination in the circuit.
- 3) Applying Sealing Tape
- Wrap with tape 1 to 2 times following the screw direction.
- Pieces of the sealing tape can lead to oil leakage and malfunction.
- Please implement piping construction in a clear environment to prevent anything getting in products.
- 4) Air Bleeding of the Hydraulic Circuit
- If the hydraulic circuit has excessive air, the action time may become very long. If air enters the circuit after connecting the hydraulic port or under the condition of no air in the oil tank, please perform the following steps.
- ① Reduce hydraulic pressure to less than 2MPa.
- ② Loosen the cap nut of pipe fitting closest to the clamp, cylinder, work support, etc. by one full turn.
- ③ Shake the pipeline to loosen the outlet of pipe fitting. Hydraulic fluid mixed with air comes out.



- ④ Tighten the cap nut after air bleeding.
- ⑤ It is more effective to release air at the highest point inside the circuit or at the end of the circuit. (For the gasket option, set an air bleeding valve at the highest point inside the circuit.)



- 5) Checking Looseness and Retightening
- At the beginning of the product installation, the bolt and nut may be tightened lightly.
 - Check the looseness and re-tighten as required.

Hydraulic Fluid List

| | IS | 60 Viscosity Grade ISO-VG-32 |
|------------------------|---------------------------|------------------------------|
| Manufacturer | Anti-Wear Hydraulic Oil | Multi-Purpose Hydraulic Oil |
| Showa Shell Sekiyu | Tellus S2 M 32 | Morlina S2 B 32 |
| Idemitsu Kosan | Daphne Hydraulic Fluid 32 | Daphne Super Multi Oil 32 |
| JX Nippon Oil & Energy | Super Hyrando 32 | Super Mulpus DX 32 |
| Cosmo Oil | Cosmo Hydro AW32 | Cosmo New Mighty Super 32 |
| ExxonMobil | Mobil DTE 24 | Mobil DTE 24 Light |
| Matsumura Oil | Hydol AW-32 | |
| Castrol | Hyspin AWS 32 | |

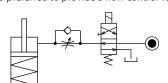
 $Note: \ Please \ contact \ manufacturers \ when \ customers \ require \ products \ in \ the \ list \ above.$

Notes on Hydraulic Cylinder Speed Control Unit

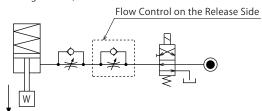


Please pay attention to the cautions below. Design the hydraulic circuit for controlling the action speed of hydraulic cylinder. Improper circuit design may lead to malfunctions and damages. Please review the circuit design in advance.

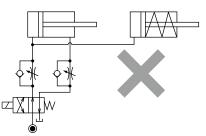
Flow Control Circuit for Single Acting Cylinder For spring return single acting cylinders, restricting flow during release can extremely slow down or disrupt release action. The preferred method is to control the flow during the lock action only using a flow control valve with a check valve. It is also preferred to provide a flow control valve at each actuator.



If a load is applied in the direction of release action during release, which may damage the cylinder, use a flow control valve with a check valve to control the flow rate on the release side as well. (This also applies to swing clamps where the lever weight is applied during release.)

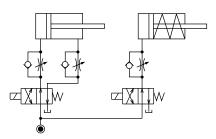


Single acting cylinders should not be used in the same flow control circuit as the double acting cylinders. The release action of the single acting cylinders may become erratic or very slow.

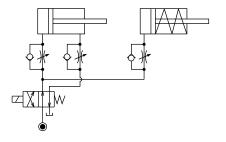


Refer to the following circuit when both the single acting cylinder and double acting cylinder are used together.

O Separate the control circuit.



O Reduce the influence of double acting cylinder control unit. However, due to the back pressure in tank line, single acting cylinder is activated after double acting cylinder works.



Clamp

Accessories

Cautions

Cautions

(for Hyd. Series)

Hyd. Fluid List

Notes on Hyd. Cylind

Notes on Handling

Maintenance/ Inspection

Warranty

Cautions

Notes on Handling

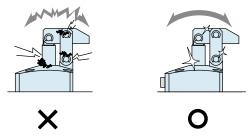
- 1) It should be operated by qualified personnel.
- The hydraulic machine and air compressor should be operated and maintained by qualified personnel.
- 2) Do not operate or remove the product unless the safety protocols are ensured.
- ① The machine and equipment can only be inspected or prepared when it is confirmed that the safety devices are in place.
- ② Before the product is removed, make sure that the abovementioned safety devices are in place. Shut off the pressure and power source, and make sure no pressure exists in the air and hydraulic circuits.
- ③ After stopping the product, do not remove until the temperature drops
- Make sure there is no abnormality in the bolts and respective parts before restarting the machine or equipment.
- Do not touch the clamp (cylinder) while it is working.
 Otherwise, your hands may be injured due to clinching.



- 4) Do not disassemble or modify.
- If the equipment is taken apart or modified, the warranty will be voided even within the warranty period.

Maintenance and Inspection

- 1) Removal of the Product and Shut-off of Pressure Source
- Before the product is removed, make sure that safety devices and preventive devices are in place. Shut off the pressure and power source, and make sure no pressure exists in the air and hydraulic circuits.
- Make sure there is no abnormality in the bolts and respective parts before restarting.
- 2) Regularly clean the area around the piston rod.
- If it is used when the surface is contaminated with dirt, it may lead to packing seal damage, malfunctioning and fluid leakage.



- 3) If disconnecting by couplers, air bleeding should be carried out on a regular basis to avoid air mixed in the circuit.
- 4) Regularly tighten pipe, mounting bolt, nut, snap ring, cylinder and others to ensure proper use.
- 5) Make sure the hydraulic fluid has not deteriorated.
- 6) Make sure there is a smooth action without an irregular noise.
- Especially when it is restarted after left unused for a long period, make sure it can be operated correctly.
- The products should be stored in the cool and dark place without direct sunshine or moisture.
- 8) Please contact us for overhaul and repair.

Installation Notes Notes on Hyd. Cylinder Notes on Maintenance Hydraulic Fluid List Warranty (for Hydraulic Series) Handling Speed Control Circuit Inspection

Warranty

- 1) Warranty Period
- The product warranty period is 18 months from shipment from our factory or 12 months from initial use, whichever is earlier.
- 2) Warranty Scope
- If the product is damaged or malfunctions during the warranty period due to faulty design, materials or workmanship, we will replace or repair the defective part at our expense. Defects or failures caused by the following are not covered.
- ① If the stipulated maintenance and inspection are not carried out.
- ② If the product is used while it is not suitable for use based on the operator's judgment, resulting in defect.
- ③ If it is used or operated in an inappropriate way by the operator. (Including damage caused by the misconduct of the third party.)
- 4 If the defect is caused by reasons other than our responsibility.
- ⑤ If repair or modifications are carried out by anyone other than Kosmek, or without our approval and confirmation, it will void warranty.
- ⑥ Others caused by natural disasters or calamities not attributable to our company.
- $\ensuremath{{\ensuremath{\bigcirc}}}$ Parts or replacement expenses due to parts consumption and deterioration. (Such as rubber, plastic, seal material and some electric components.)

Damages excluding from direct result of a product defect shall be excluded from the warranty.

Clamp

Accessories

Cautions

Installation Notes (for Hyd. Series)

Hyd. Fluid List

Notes on Hyd. Cylinder Speed Control Circuit



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